

High Performance Graphics 2013

19.7.2013

SCREEN-SPACE FAR-FIELD AMBIENT
OBSCURANCE

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1. SSAO and previous approaches
2. Our method
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4. Left out from the presentation (in paper)
5. Questions

I AMBIENT OBSCURANCE

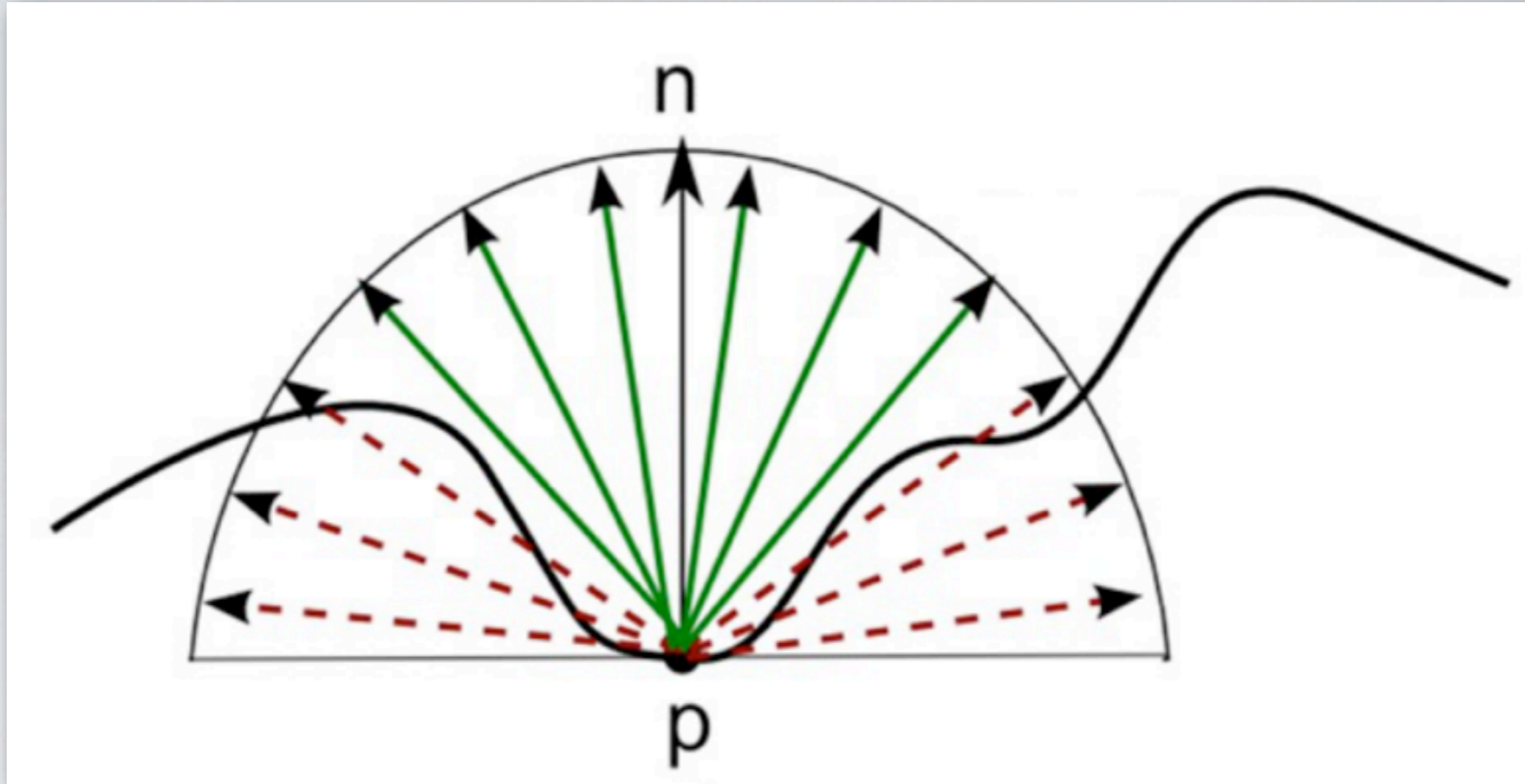
Is an approximation for global illumination



AdamLHumphreys.com

I AMBIENT OBSCURANCE

Defined as the cosine and falloff weighted hemisphere visibility



$$A(\mathbf{p}, \vec{n}) = \frac{1}{\pi} \int_{\Omega} F(D(\mathbf{p}, \vec{\omega})) \vec{n} \cdot \vec{\omega} d\vec{\omega}$$

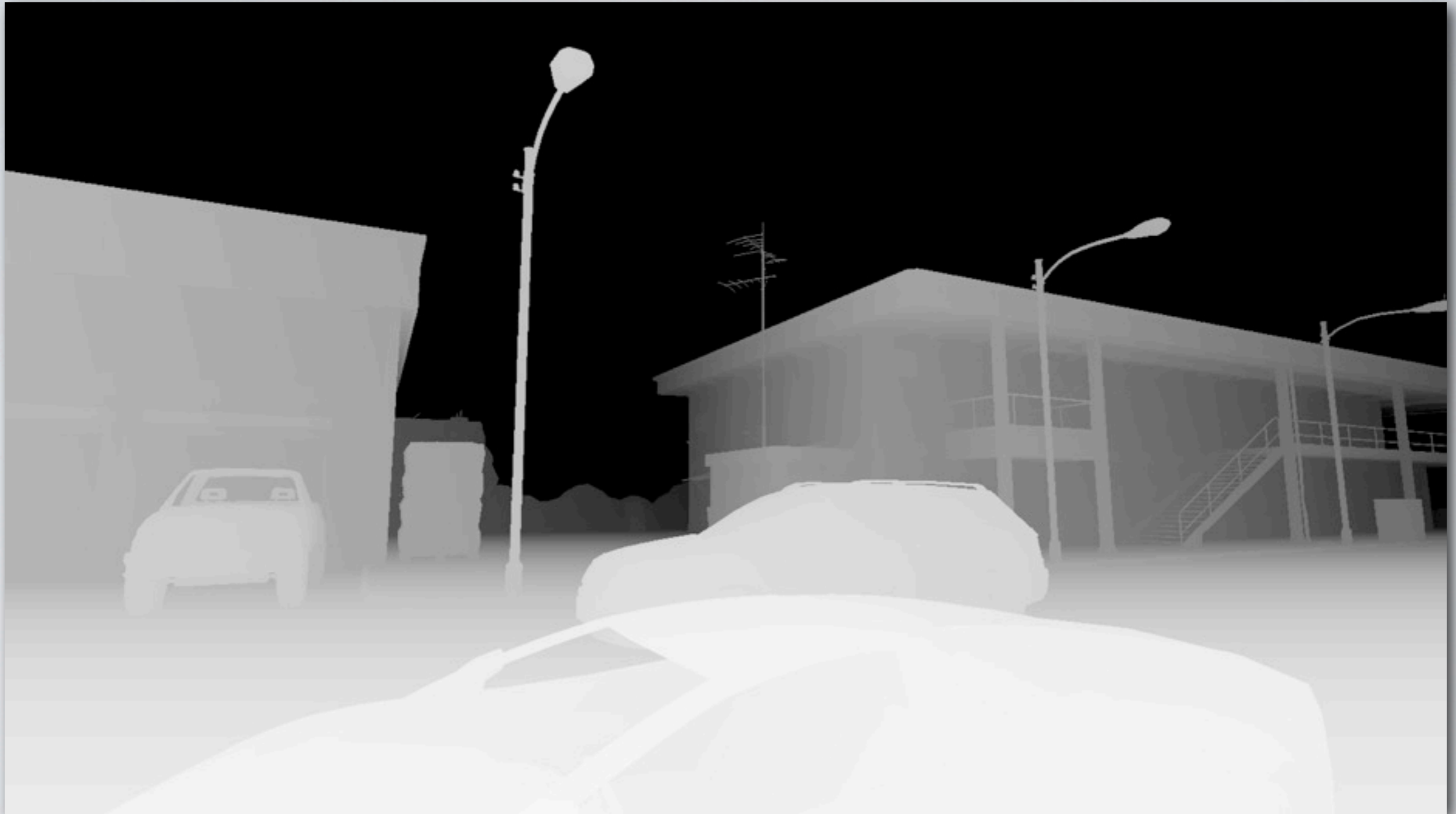
I AMBIENT OBSCURANCE

Screen-Space Ambient Obscurance

- General AO solutions quite not real-time ready
- Screen-Space methods work on the depth buffer geometry only
 - Constant amount of geometry
 - Restricted geometry makes room for optimizations

I SCREEN-SPACE AMBIENT OBSCURANCE

This is a depth map (dark = far, light = near)

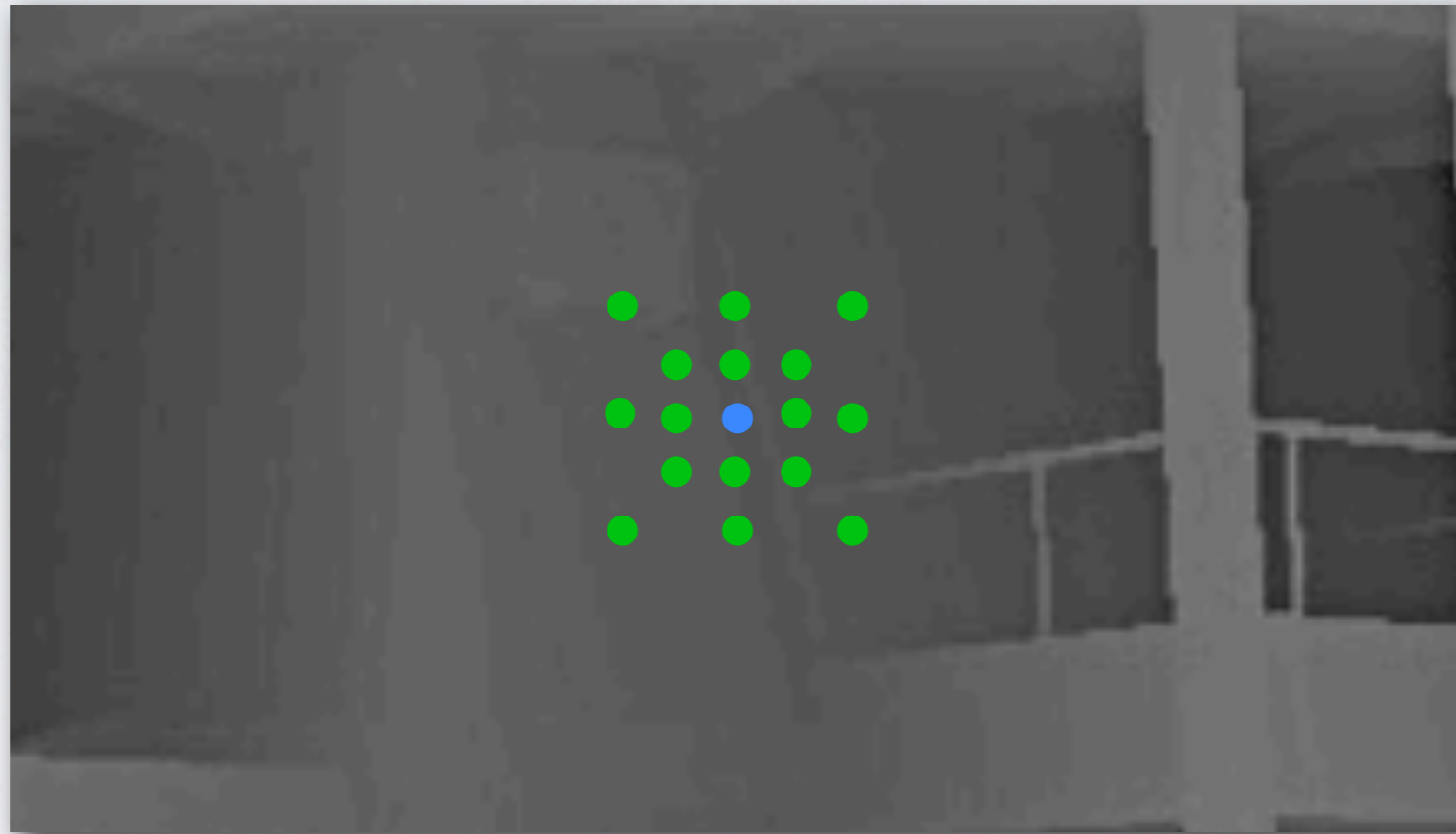


A by-product of most graphics pipelines

I SCREEN-SPACE AMBIENT OBSCURANCE

So this is what SSAO does:

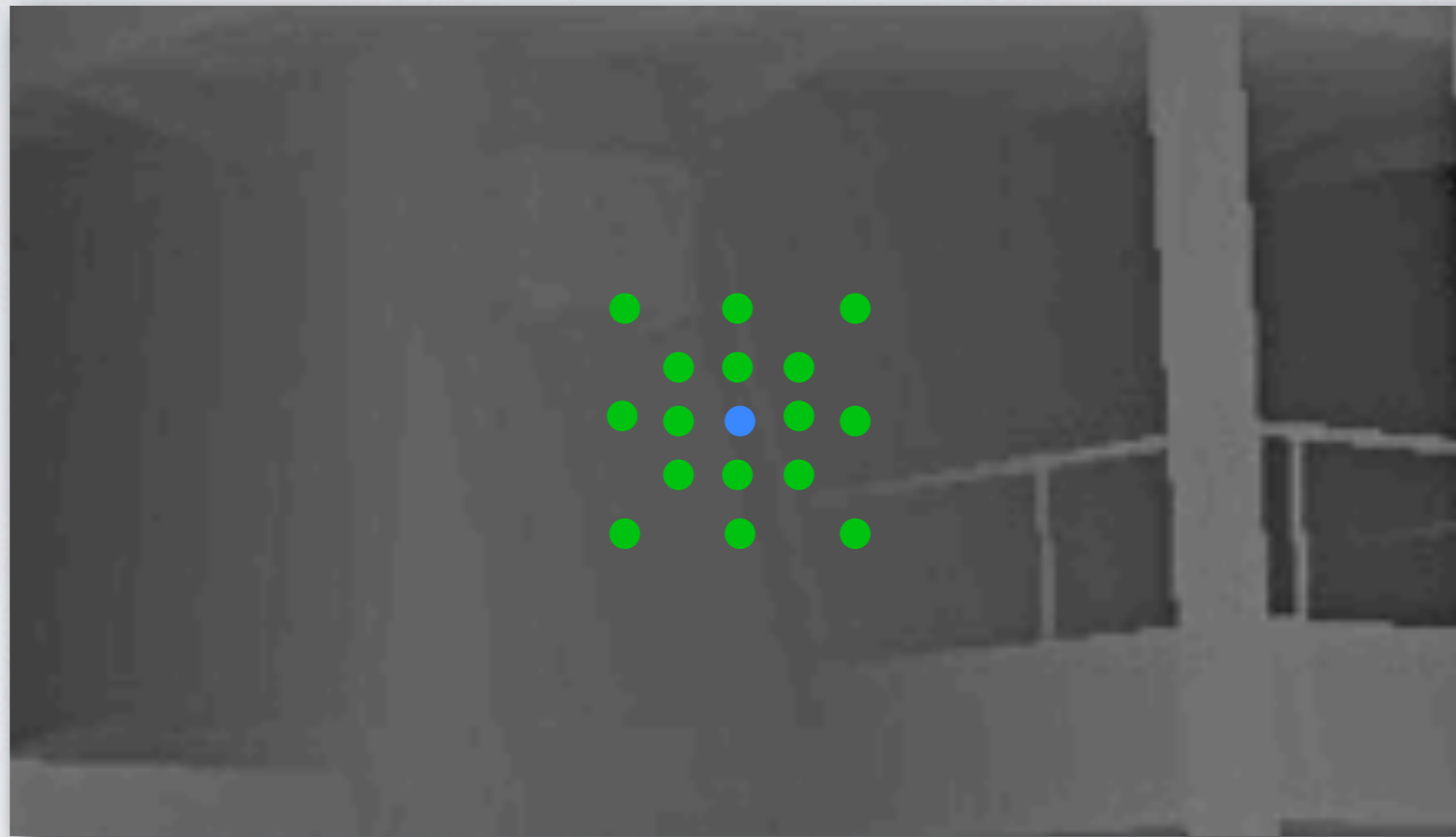
For the blue point...



Sample the surroundings...

I SCREEN-SPACE AMBIENT OBSCURANCE

So this is what SSAO does:



Deproject points to world space and evaluate AO:

$$A(\mathbf{p}, \vec{n}) = \frac{1}{\pi} \int_{\Omega} F(D(\mathbf{p}, \vec{\omega})) \vec{n} \cdot \vec{\omega} d\vec{\omega}$$

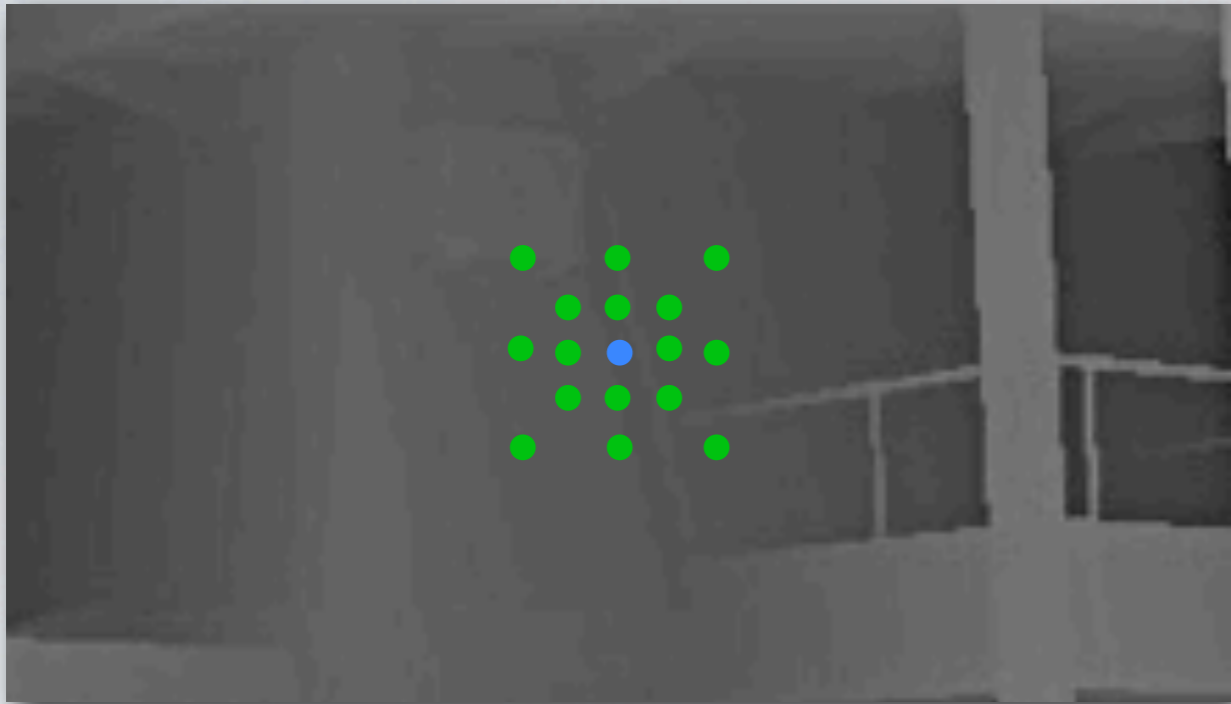
I SCREEN-SPACE AMBIENT OBSCURANCE

Two components of SSAO

1. Input geometry (i.e. samples of the depth field)
 - This is our main contribution, presentation's topic
2. Obscurance estimator (i.e. how to integrate AO from the samples)
 - Our secondary contribution; supports any falloff function, efficient to evaluate and converges to ray traced reference, beyond presentation's scope

I SCREEN-SPACE AMBIENT OBSCURANCE

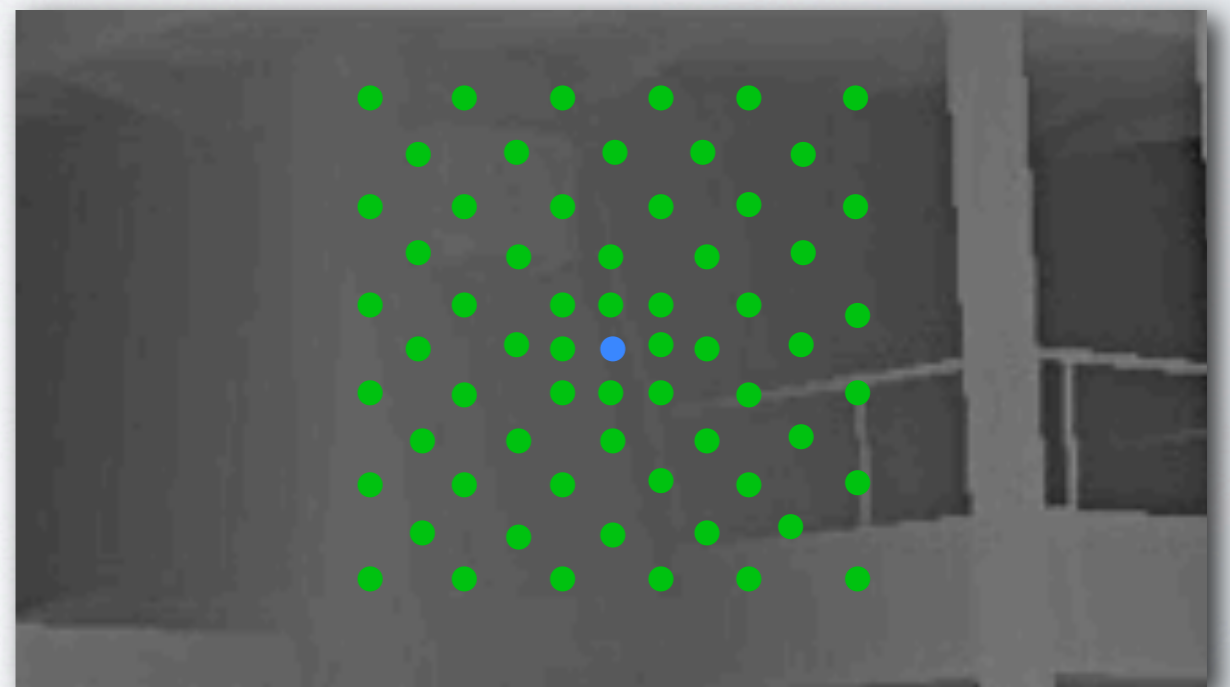
Key problem of SSAO



Sampling the near field
is not a problem

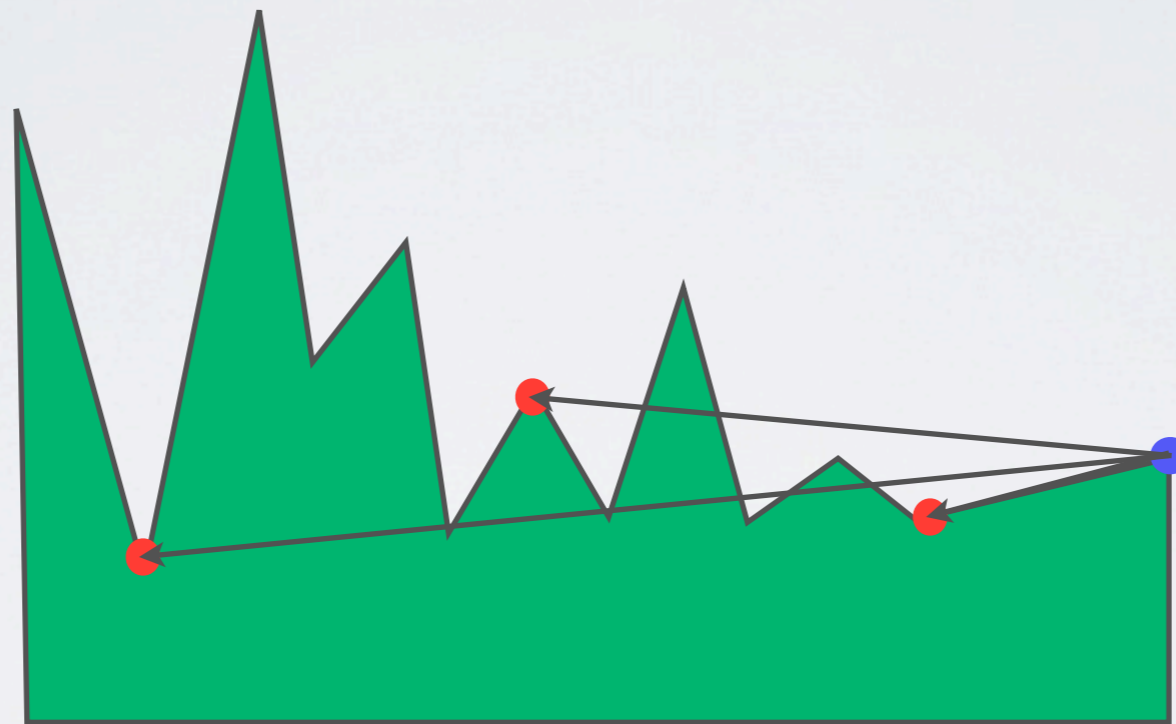
But far field easily becomes
prohibitively expensive:

Have to seriously undersample



I SCREEN-SPACE AMBIENT OBSCURANCE

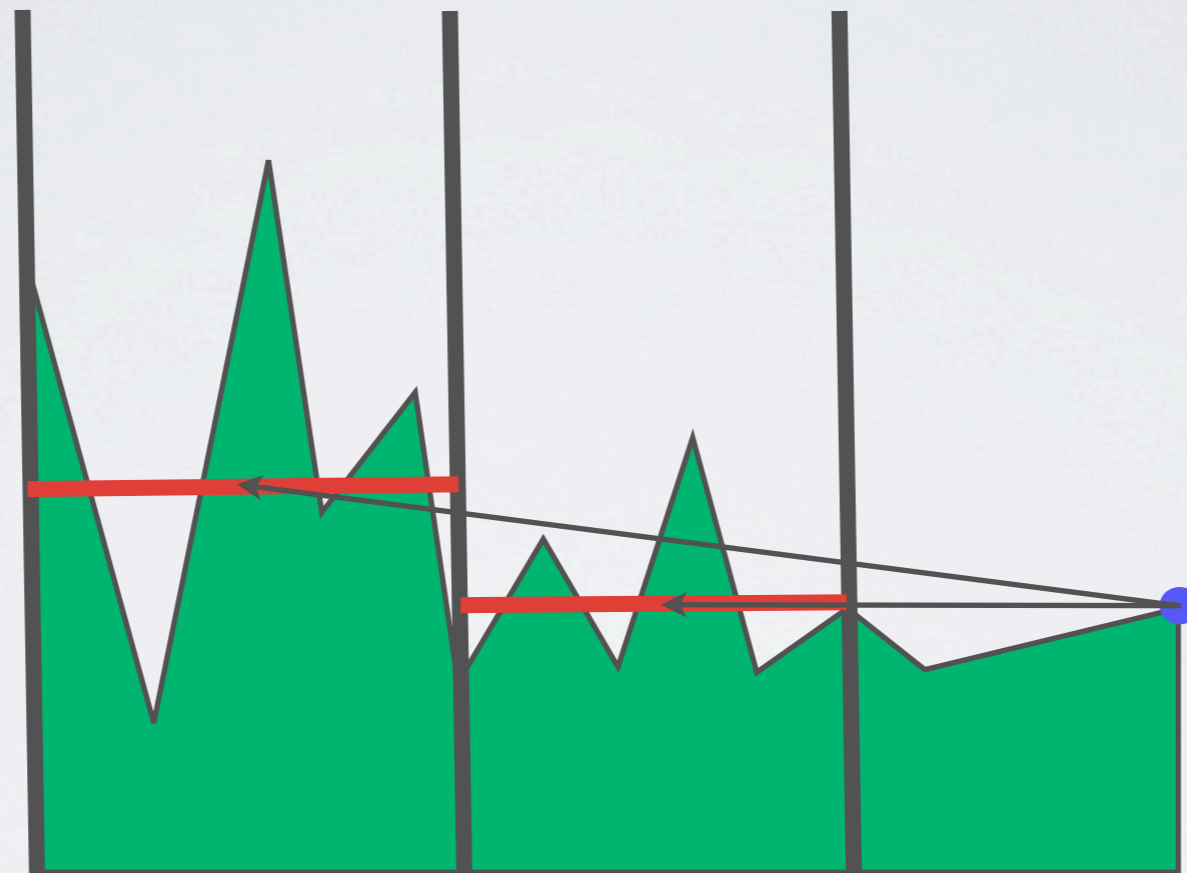
Previous 2 approaches:



Direct depth buffer samples
easily miss important occluders

I SCREEN-SPACE AMBIENT OBSCURANCE

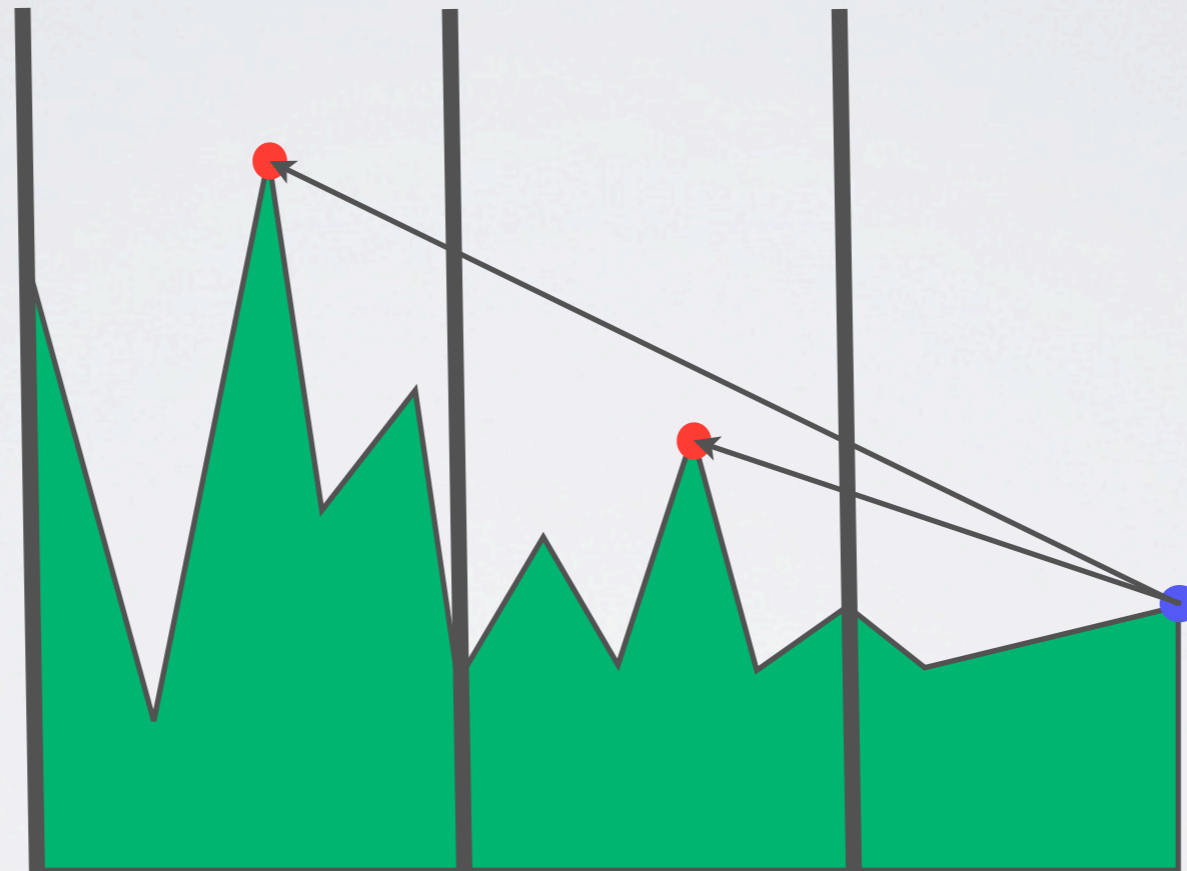
Previous 2 approaches:



Mip-mapping flattens the
geometry

2 OUR METHOD

2 OUR METHOD

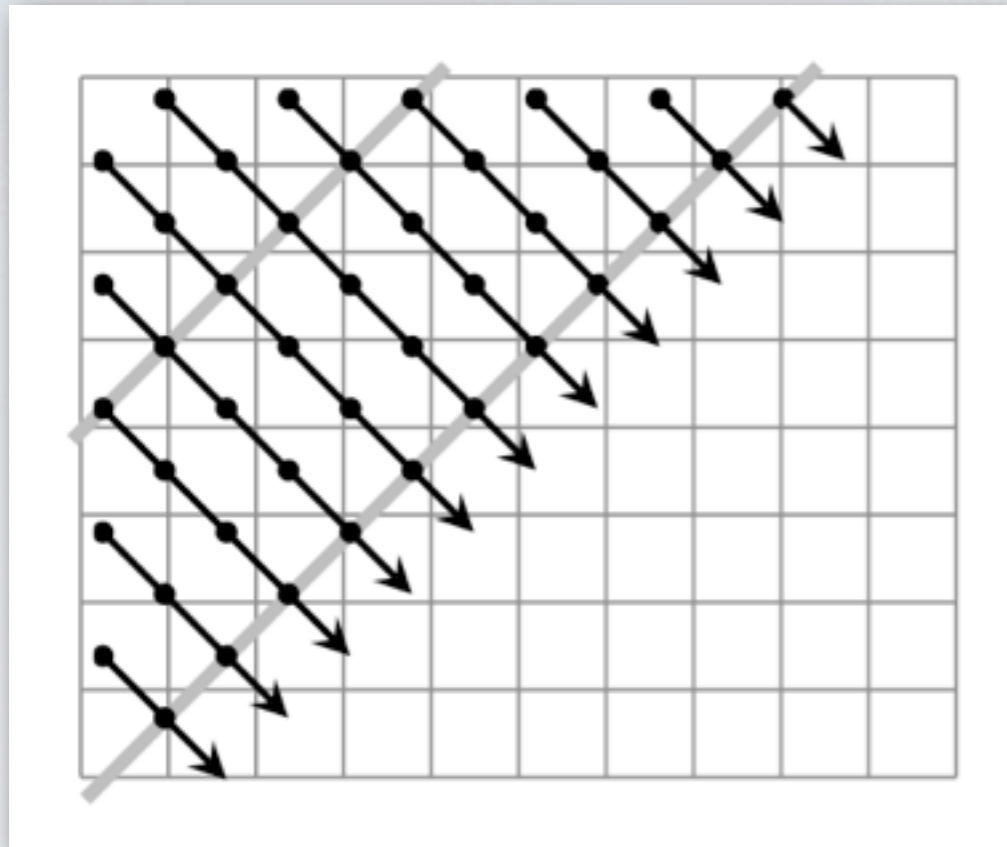


We capture points important for AO

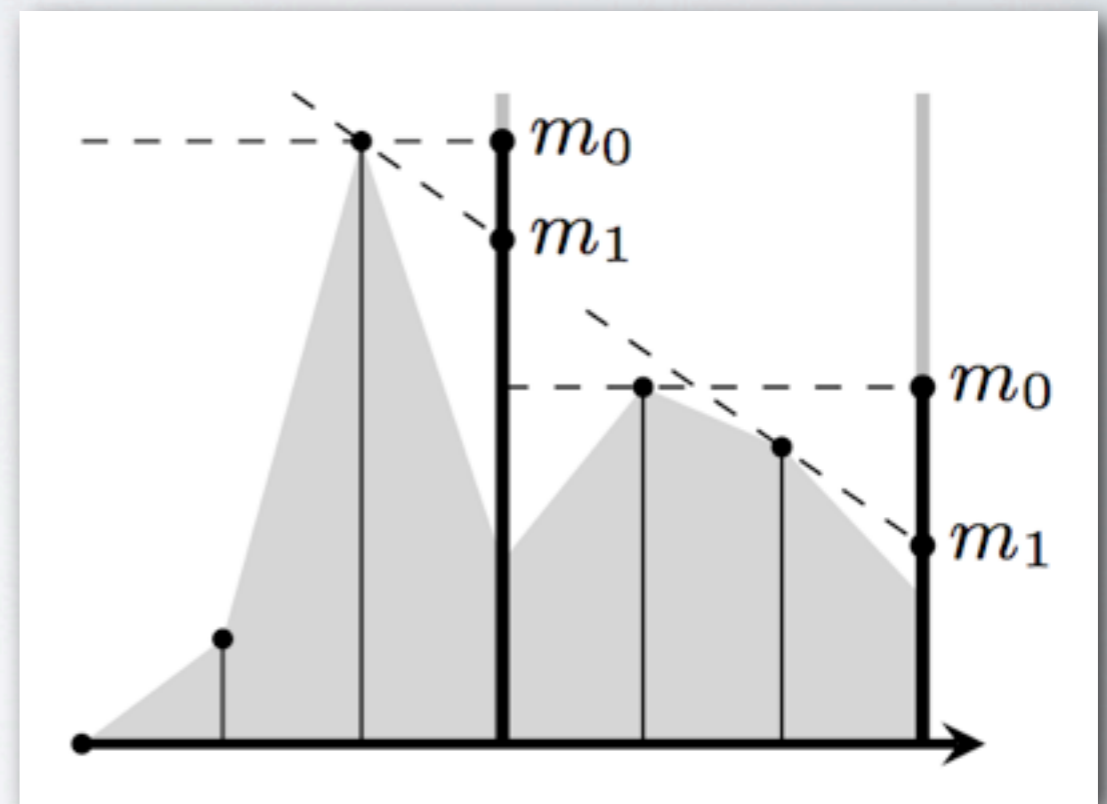
2 OUR METHOD

We capture points important for AO

Scans in multiple directions
(one direction below)



We find highest
“projections” (m_0, m_1) every
 n steps, and write them out

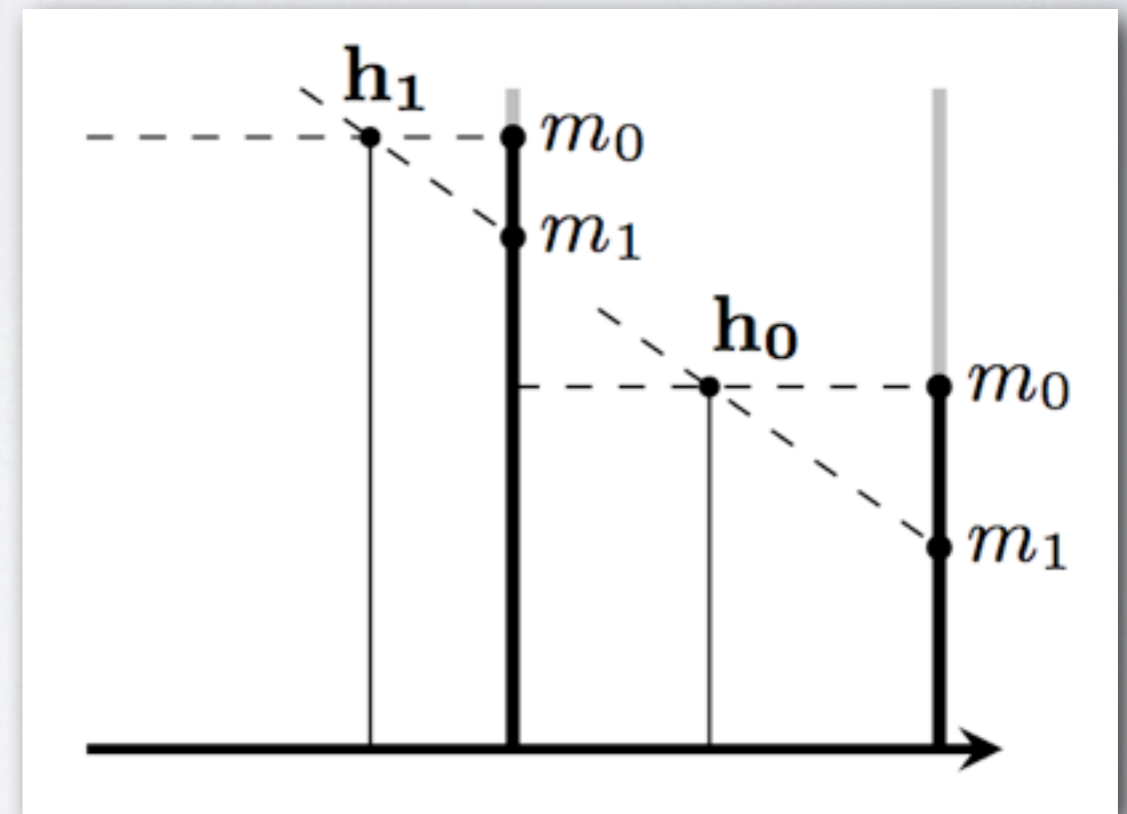
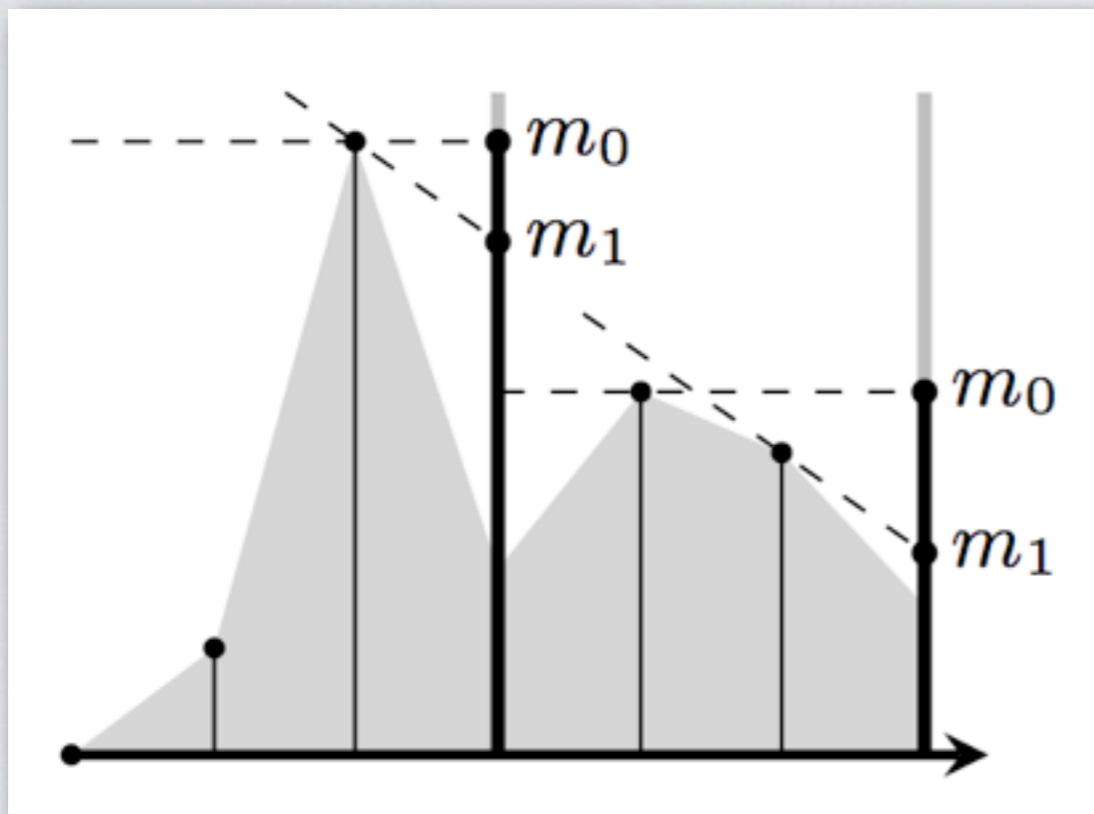


Time complexity of this phase is small w.r.t. to full SSAO

2 OUR METHOD

Final sample points, h_i

Out of these values, we construct final sample points h_i at the intersections

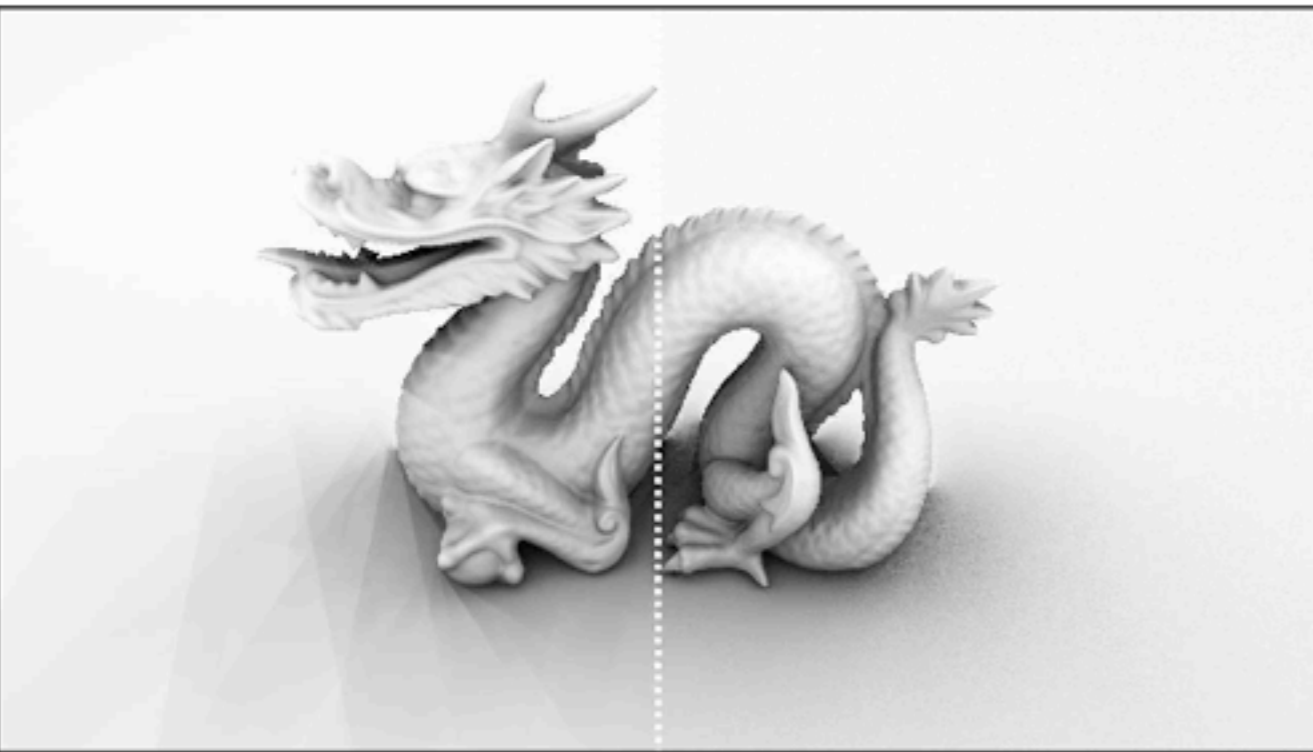


2 OUR METHOD

Results

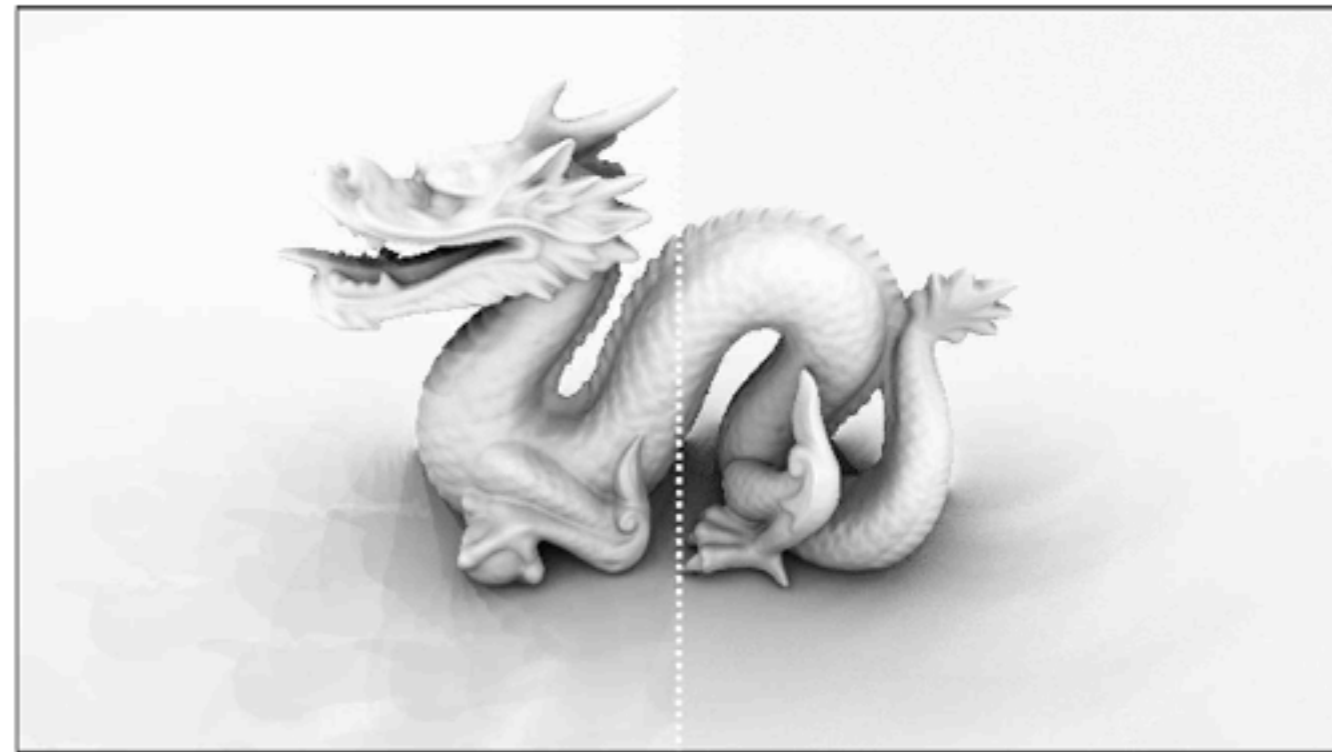
Our method

No jittering (16.3 ms) Jittered (19.1 ms)



Direct samples

No jittering (16.8 ms) Jittered (38.8 ms)

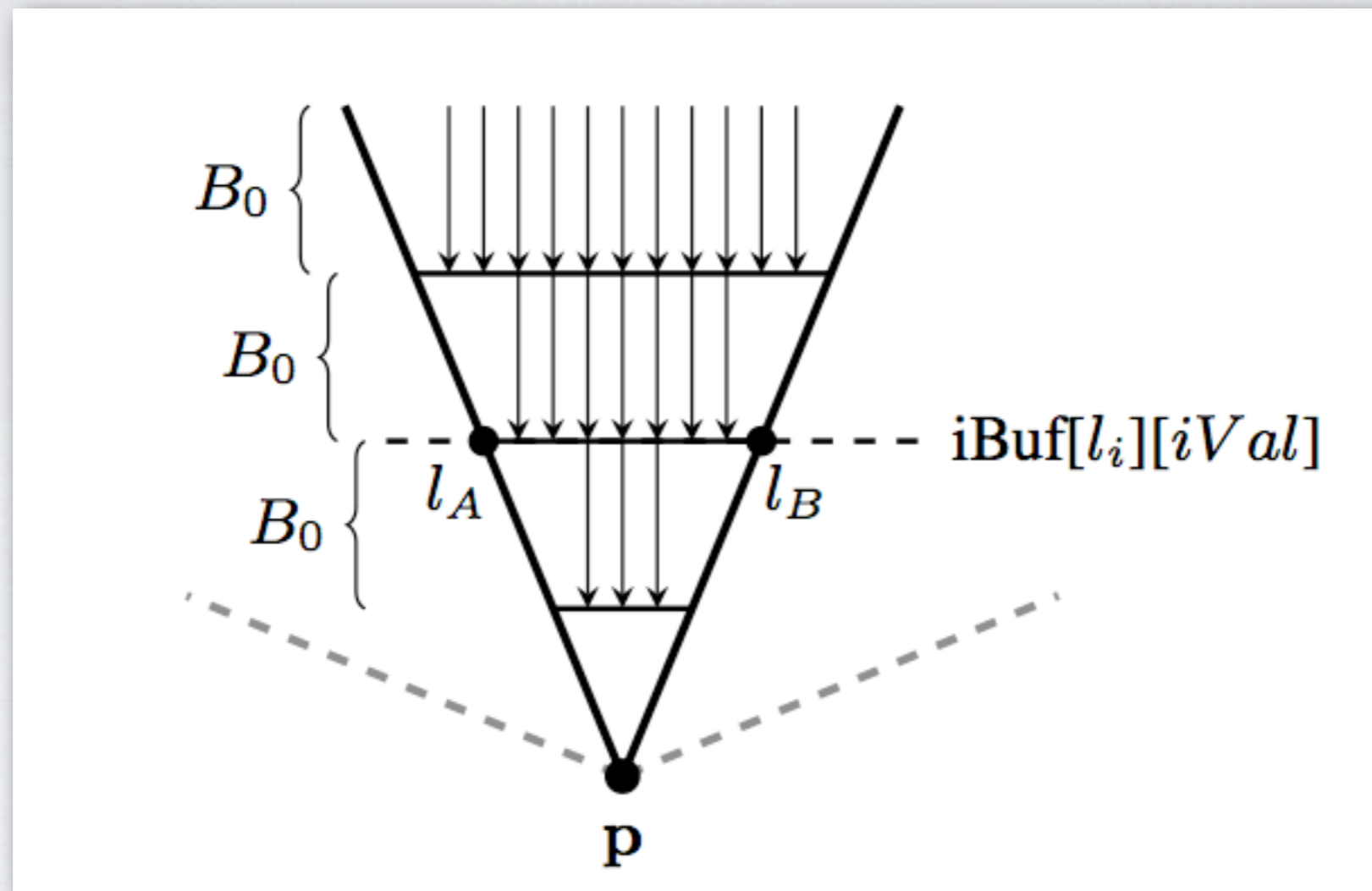


Along each azimuthal sampling direction, results are good
But banding persists between directions

2 OUR METHOD

Averaging the sectors

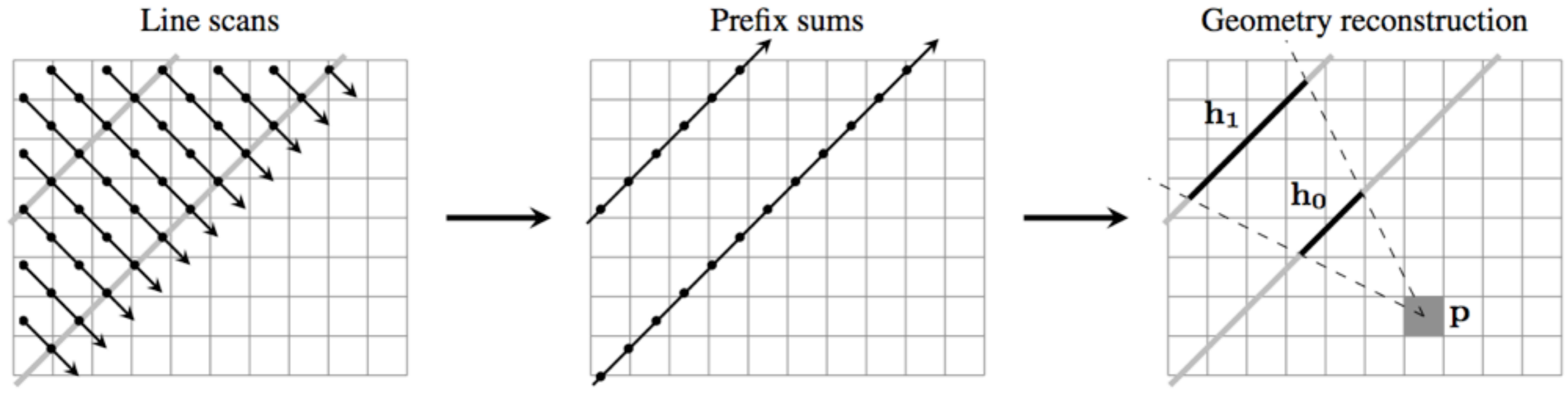
Instead of sampling along straight lines, we can average m_0 and m_1 across the azimuthal sector width



For fast averaging, we turn arrays of m_0 and m_1 into prefix sums

2 OUR METHOD

Overview of the 3 phases



This way we get scene points h_i that represent the entire sector, and therefore the full depth buffer

3 RESULTS

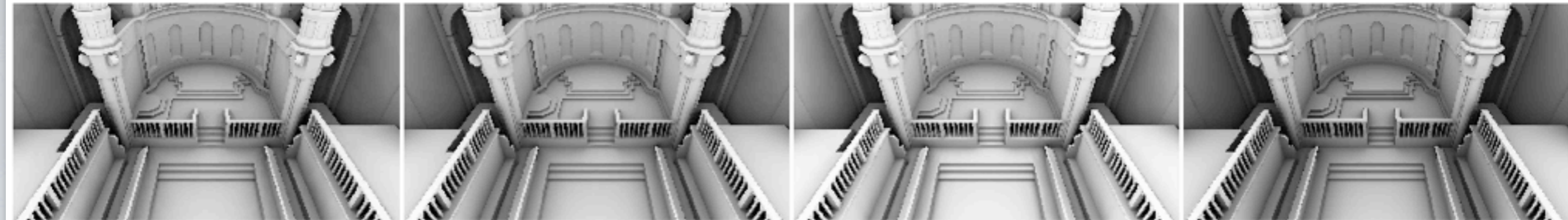
3 RESULTS

Our, $K = 8 \times 2$

Our, $K = 16 \times 2$

Mipmap, $K = 16$

Ray traced



error $\times 5$

error $\times 5$

error $\times 5$

$e_A = 1.17\%$, $e_{<5\%} = 98.9\%$

$e_A = 0.92\%$, $e_{<5\%} = 99.8\%$

$e_A = 8.63\%$, $e_{<5\%} = 25.8\%$



error $\times 5$

error $\times 5$

error $\times 5$

$e_A = 1.92\%$, $e_{<5\%} = 93.3\%$

$e_A = 1.27\%$, $e_{<5\%} = 98.5\%$

$e_A = 9.90\%$, $e_{<5\%} = 38.9\%$

3 RESULTS

Table 1: Total render times of the far-field AO component.

Method	Radeon 7970	GTX 580
1280(+256) × 720(+144), $B_0 = 10$:		
Our, $K = 8 \times 2$	7.26 ms	12.0 ms
Our, $K = 16 \times 2$	13.3 ms	23.6 ms
Mipmap, $K = 16$	19.2 ms	17.7 ms
1920(+384) × 1080(+216), $B_0 = 10$:		
Our, $K = 8 \times 2$	16.7 ms	29.4 ms
Our, $K = 16 \times 2$	31.6 ms	58.1 ms
Mipmap, $K = 16$	31.5 ms	37.9 ms

Roughly as fast as mipmap samples, but higher quality results and converges to ground truth faster

Table 2: Render time breakdown of our method per kernel.

Phase	Radeon 7970	GTX 580
1280(+256) × 720(+144), $K = 8 \times 2$, $B_0 = 10$:		
Scan	0.537 ms	0.489 ms
Prefix sum	0.945 ms	0.617 ms
Obscurance	5.77 ms	10.9 ms

3 RESULTS

1280(+256)x720(+144), 4.6ms/frame, Radeon 7970

Screen-Space Far-Field Ambient Obscurance

4 LEFT OUT FROM THE PRESENTATION

4 LEFT OUT FROM THE PRESENTATION

- The obscurance estimator
- Fixed thickness depth fields
- Multiple levels of detail for the projection intervals
- Interleaved sampling (quick preview next)
- Combining with a near field search (quick preview next)

4 LEFT OUT FROM THE PRESENTATION

Preview: *Interleaved sampling*

4.6 ms/frame, interleaved

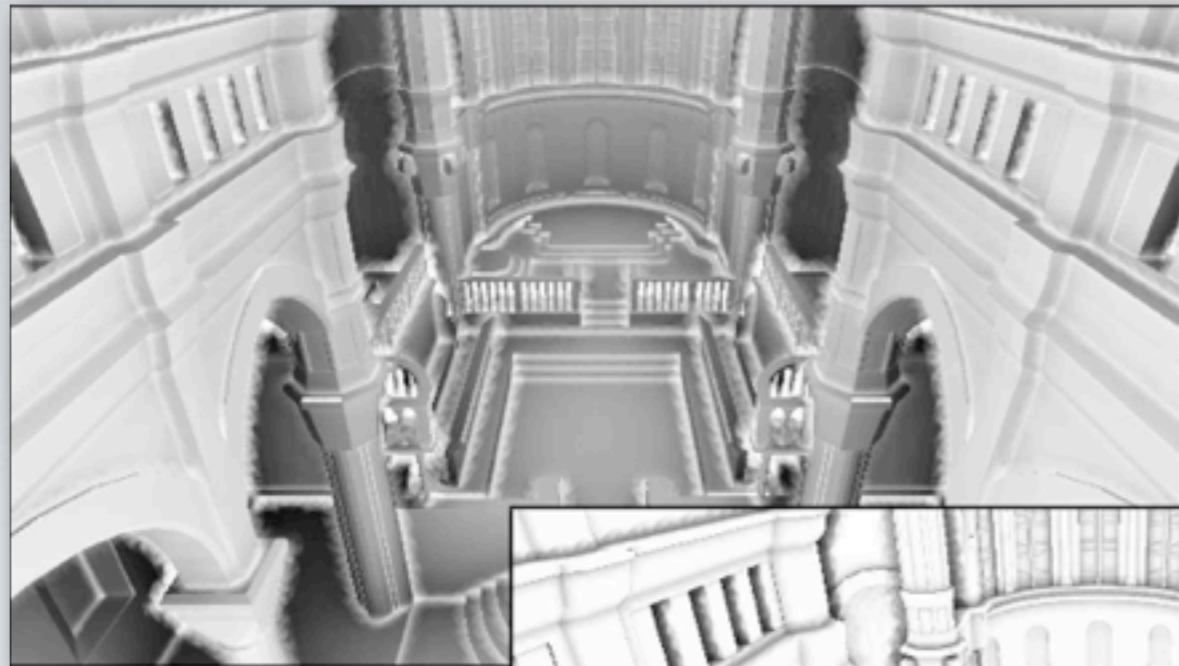
ray traced



- Evaluate a subset of sectors per pixel, gather in a selective box filter pass
- Used in the video as well

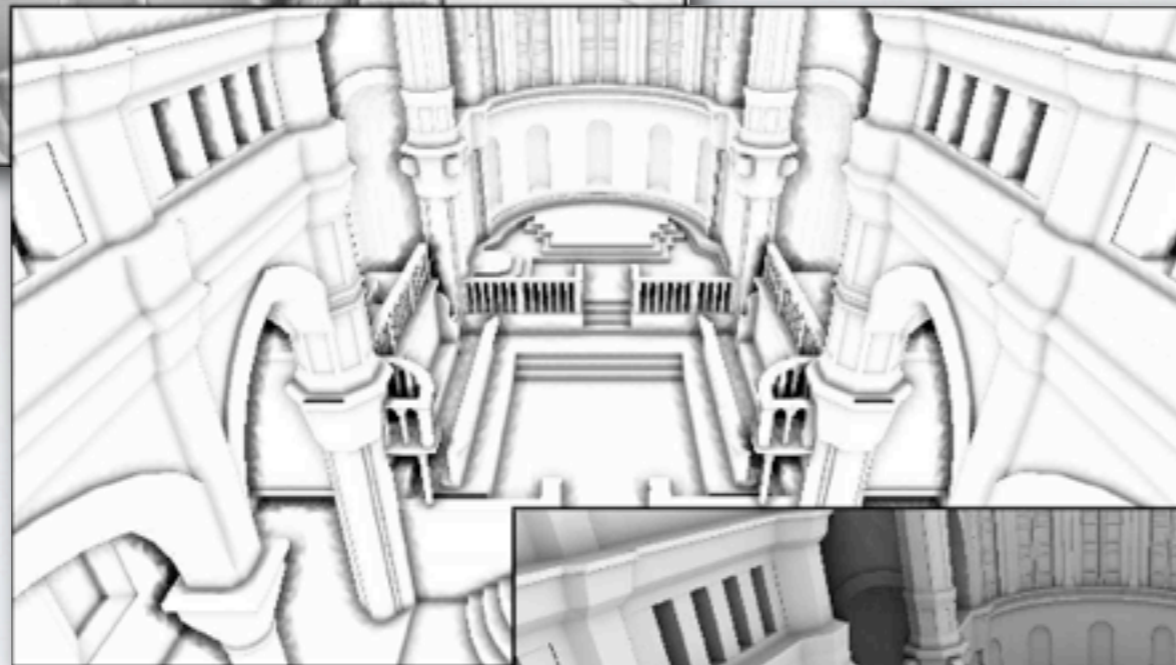
4 LEFT OUT FROM THE PRESENTATION

Preview: *Combining with a near field search*



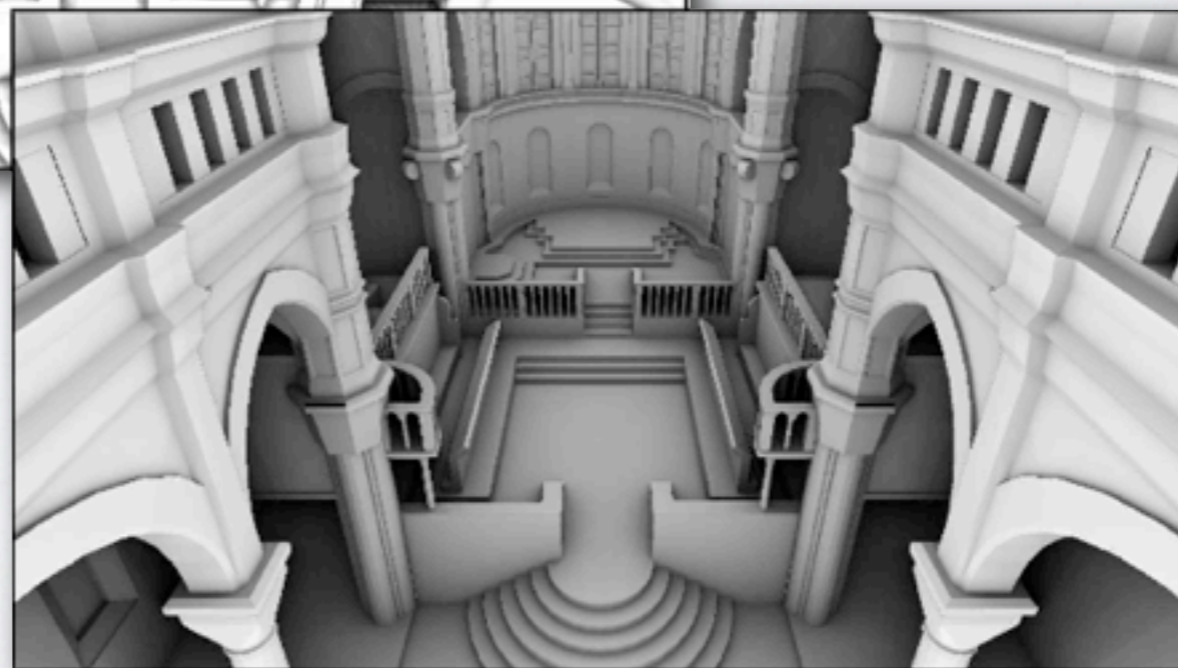
Far field $\geq 15\text{px}$ (our method)

+



Near field $< 15\text{px}$

=



Final
result

5 QUESTIONS

Or comments...



Sources available online, under the BSD license

<http://wili.cc/research/ffao/>