Reduced Precision Hardware for Ray Tracing

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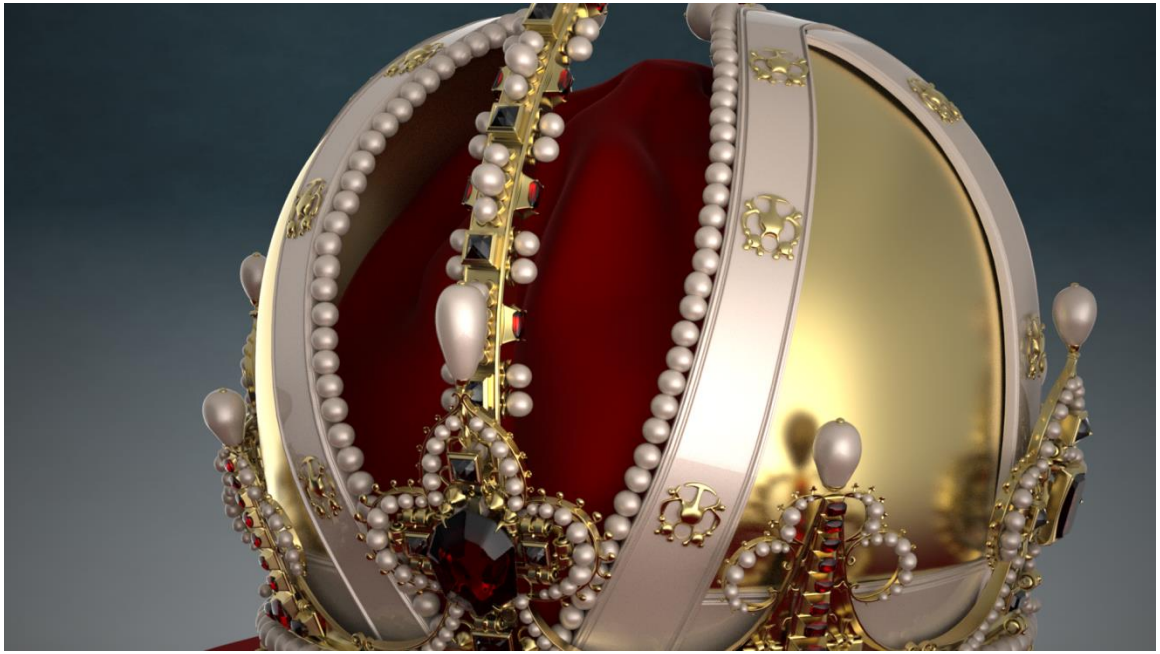
Question

Why don’t GPU’s accelerate ray tracing?

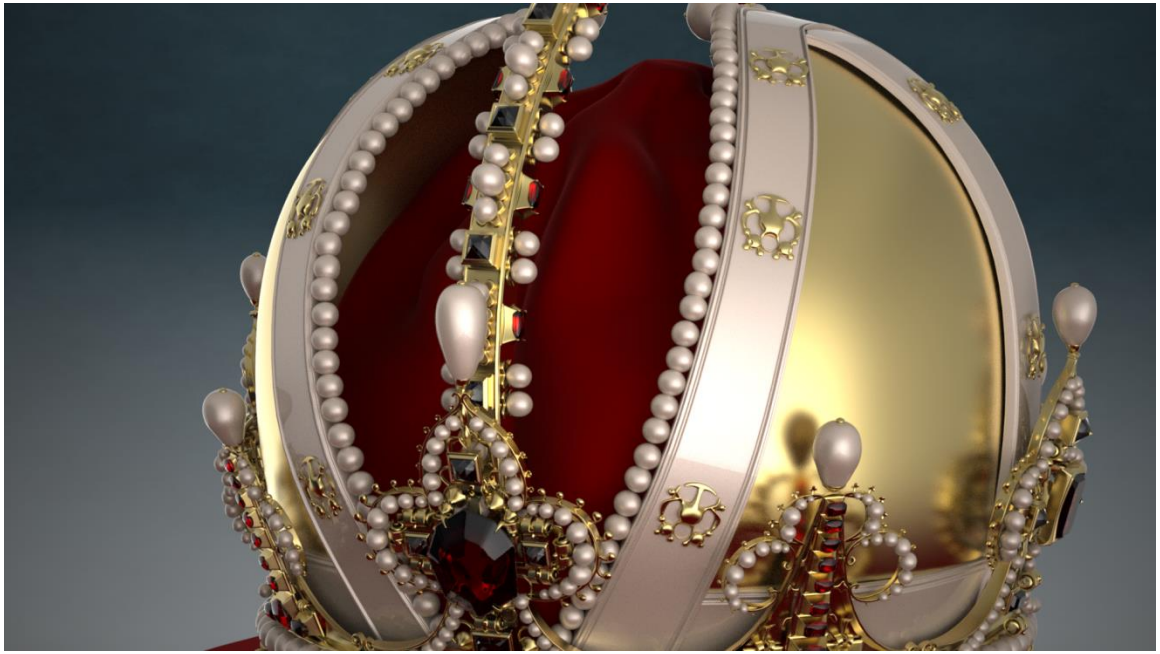
Real time ray tracing needs very high ray rate



Example Scene: 3 area lights + AO/GI

64 rays/pixel, 1080p, 30Hz -> **4 Billion Rays/s**

Real time ray tracing needs very high ray rate

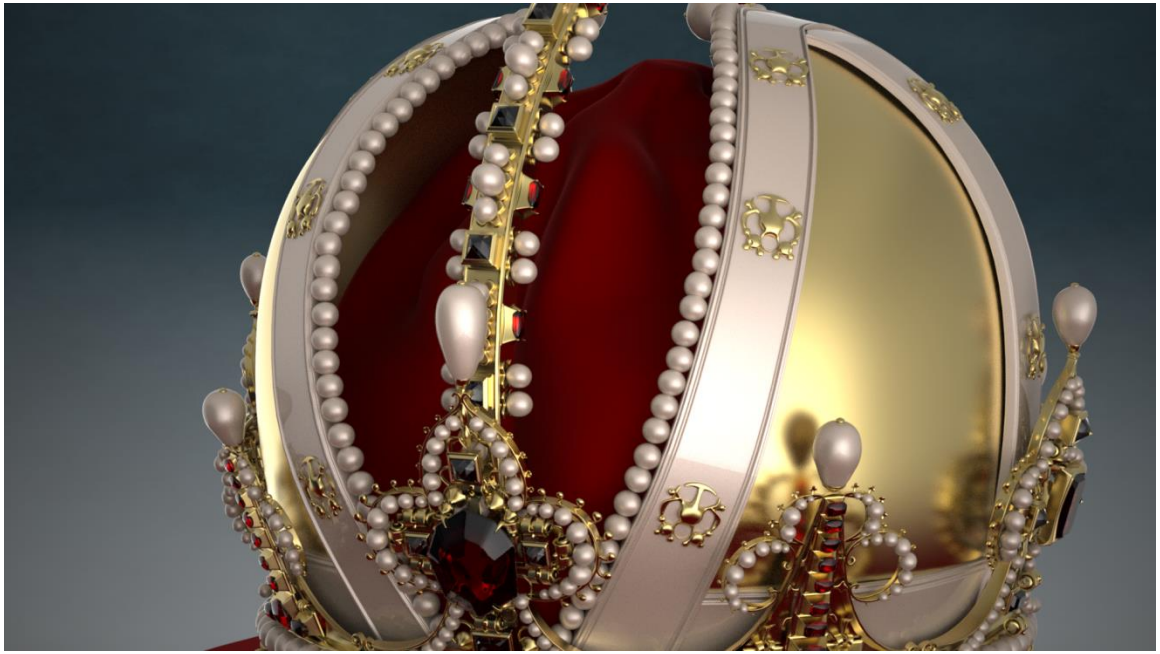


Example Scene: 3 area lights + AO/GI

64 rays/pixel, 1080p, 30Hz -> **4 Billion Rays/s**

Software approaches give 80-400M Rays/s

Single precision ASIC's will be large



Approx. 4 Tflops Trace + 2 Tflops Intersect + ?? Shading

Will need roughly the die area of a high end GPU for a trace & intersect co-processor

Previous work competes with current GPU's

- STRaTA, D. Kopta… 2013
  - MIMD configurable pipeline, avoids divergence penalty
  - Repurpose L2 as ray cache

- SGRT, W. Lee… 2014
  - MIMD co-processor design
  - Most recent work addresses the performance cost of co-processor design

Goal: Accelerate ray tracing in a GPU, not next to one

- Add high performance BVH traversal acceleration to current GPU architecture
  - MIMD traversal
  - SIMD programs

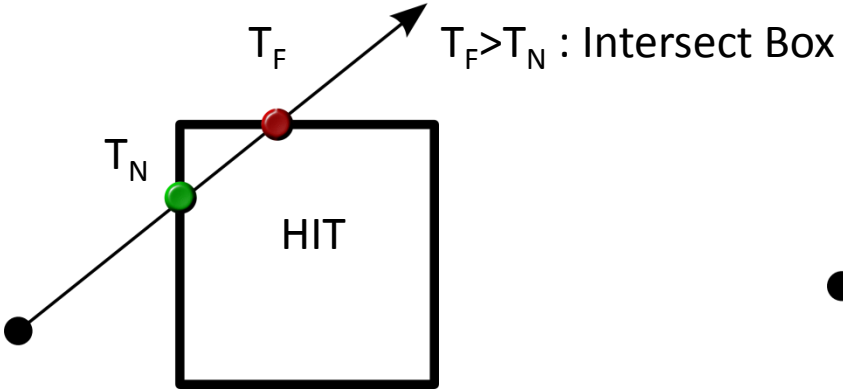
- Constraints: low impact, not a co-processor
  - small die area
  - low power
  - low bandwidth

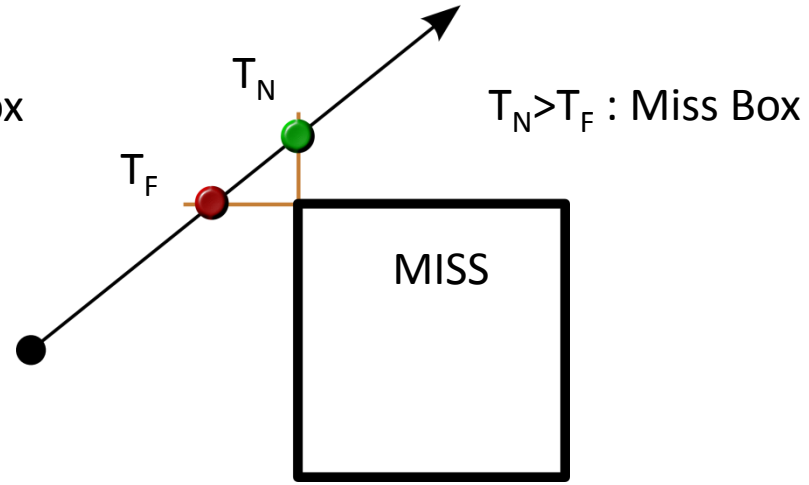
How: Reduced Precision and Integration

- 4 Billion RPS needs ~24W just for multiplies in traversal.
  - Can be reduced to ~1W with reduced precision.
- One off-chip data access is ~100x more energy than a FMA.
  - Reduced precision saves here too!
- Don’t build new registers, cache, wires…
  - Integrate to a GPU and get this for free!

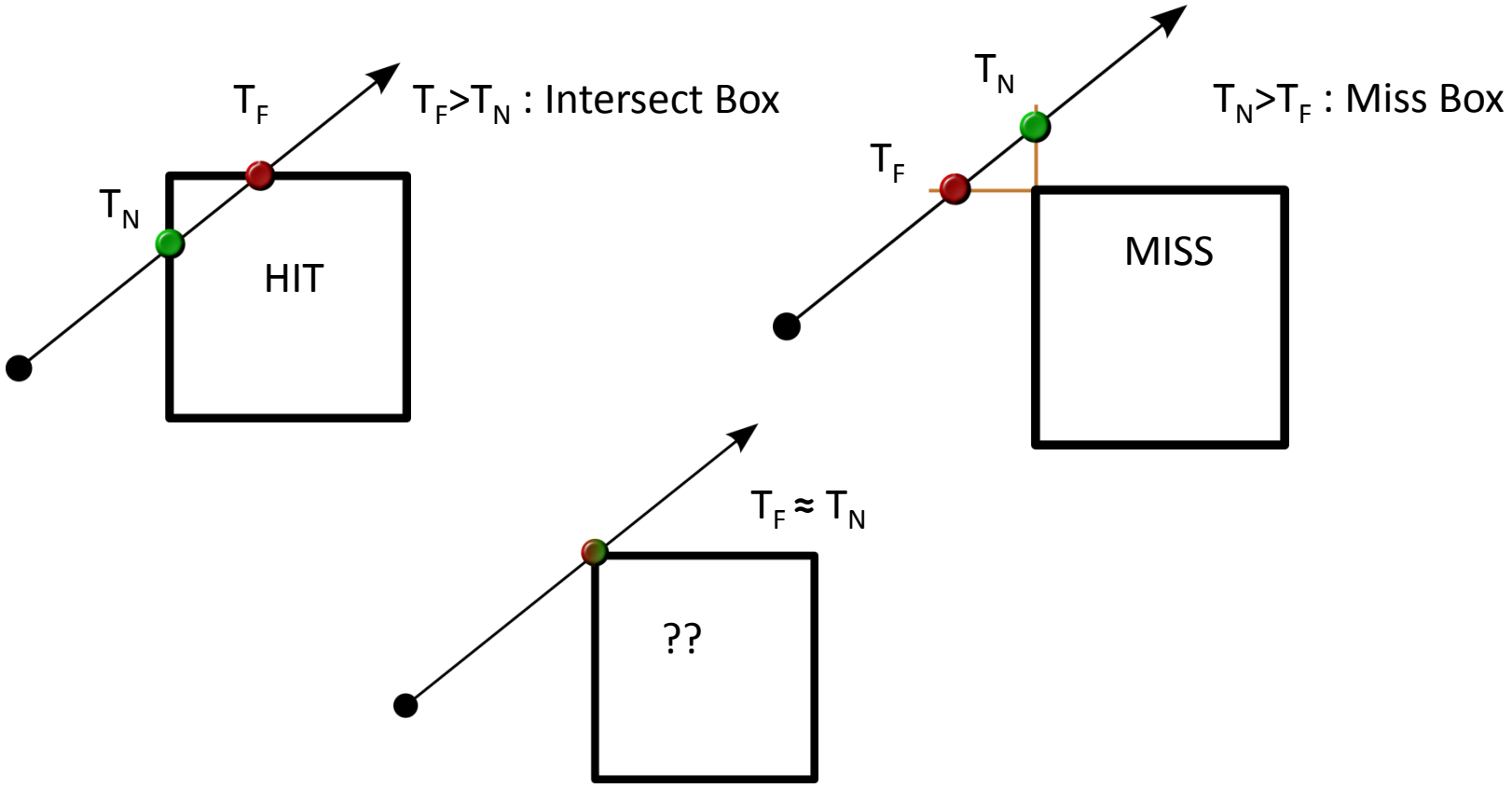
Reduced Precision BVH Traversal

Robust Ray-AABB Test





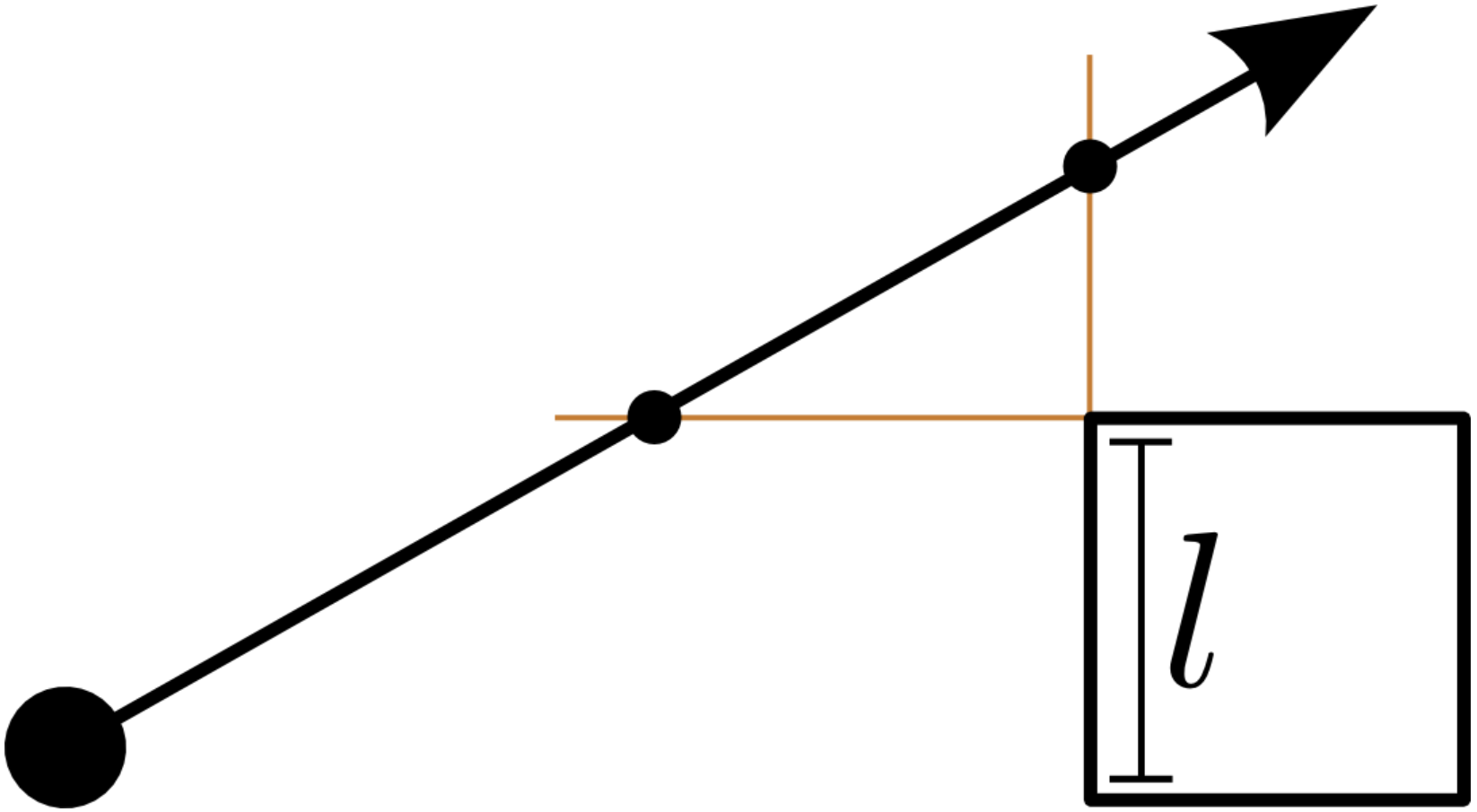
Robust Ray-AABB Test



Ambiguity if $T_F \approx T_N$.

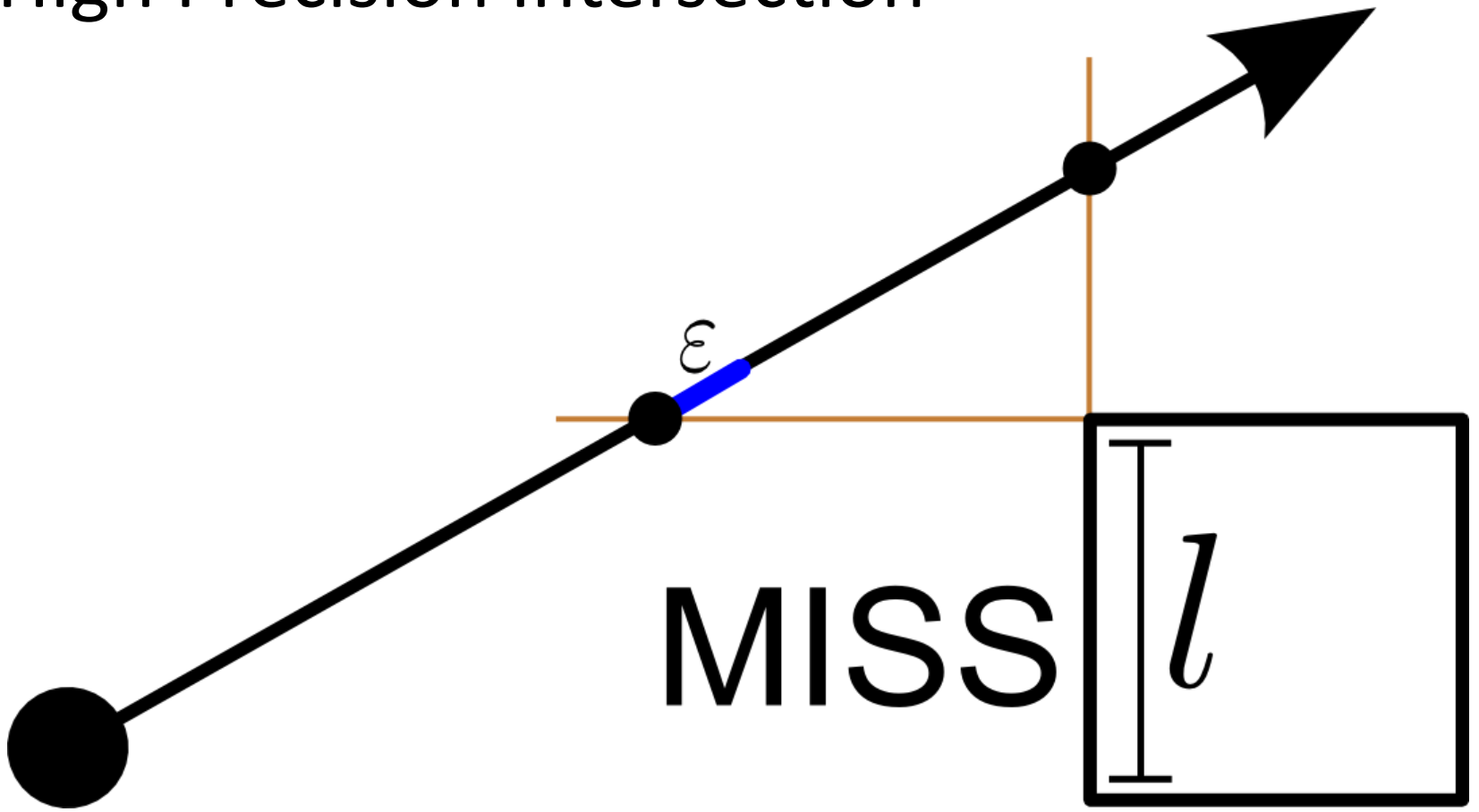
Need $T_N > T_F + \varepsilon$, $\varepsilon = 2 * ULP(T_F)$ to declare a miss [T. Ize, '13].

Hit or Miss?



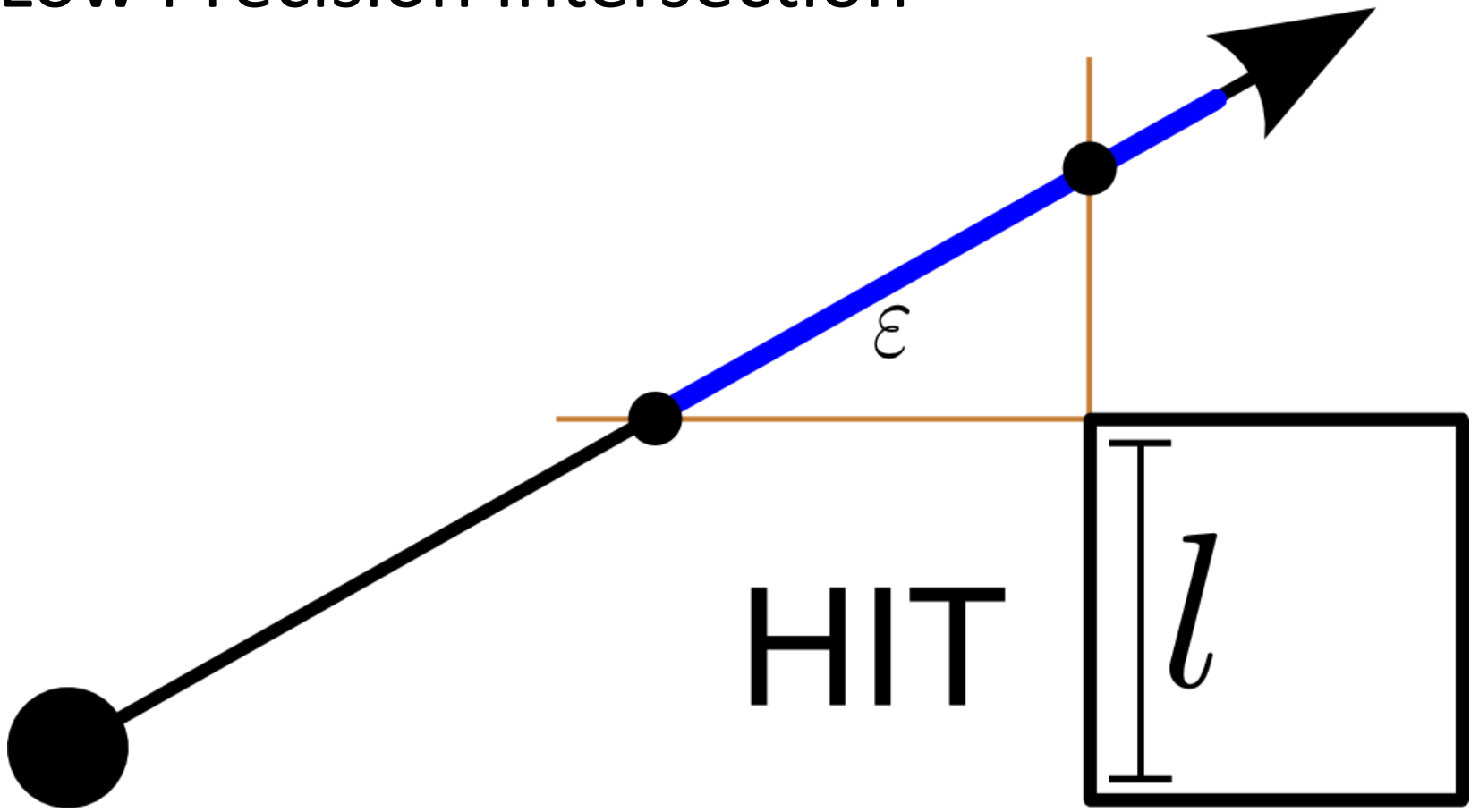
Hit or Miss?

High Precision Intersection



Hit or Miss?

Low Precision Intersection



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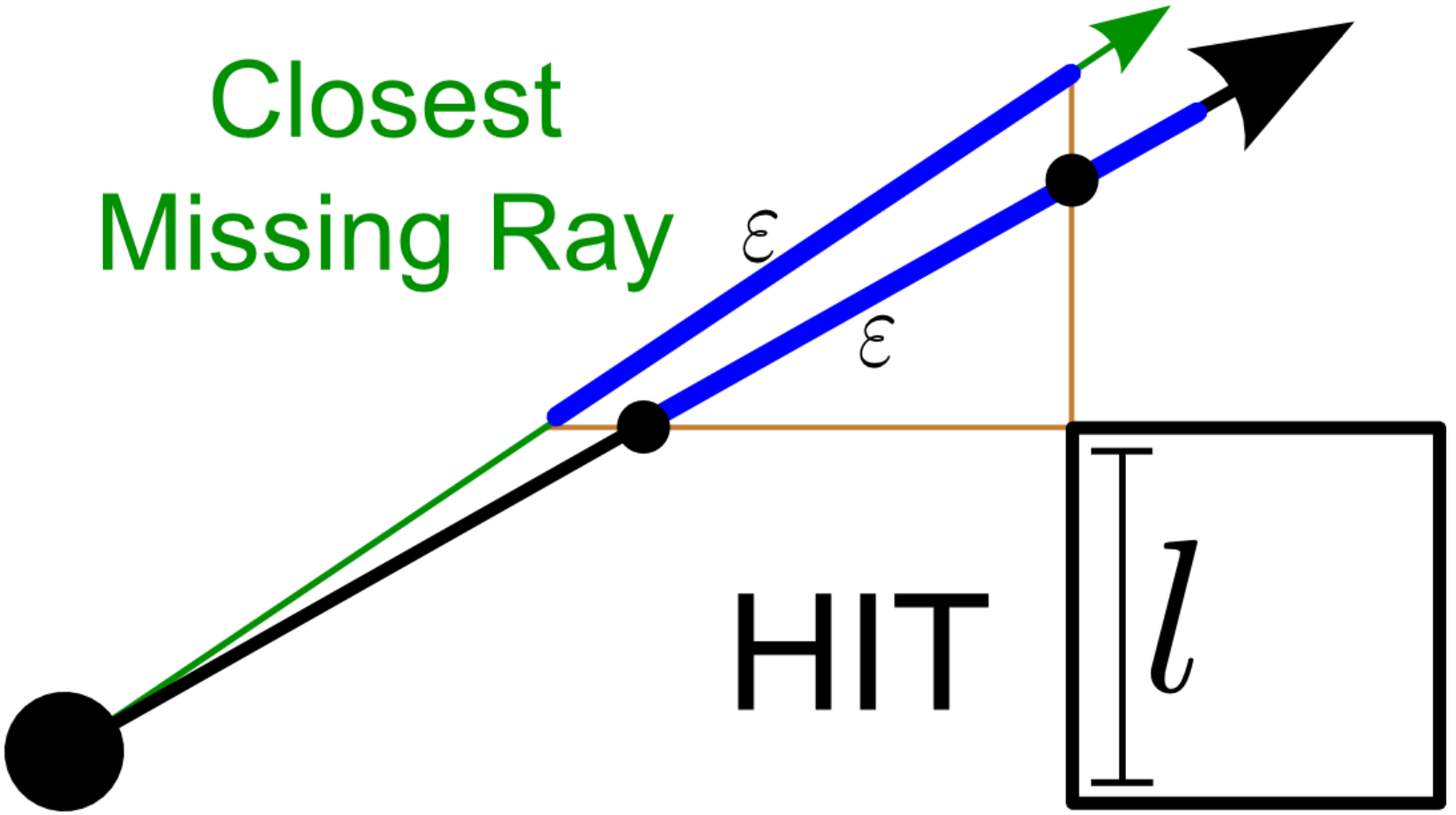

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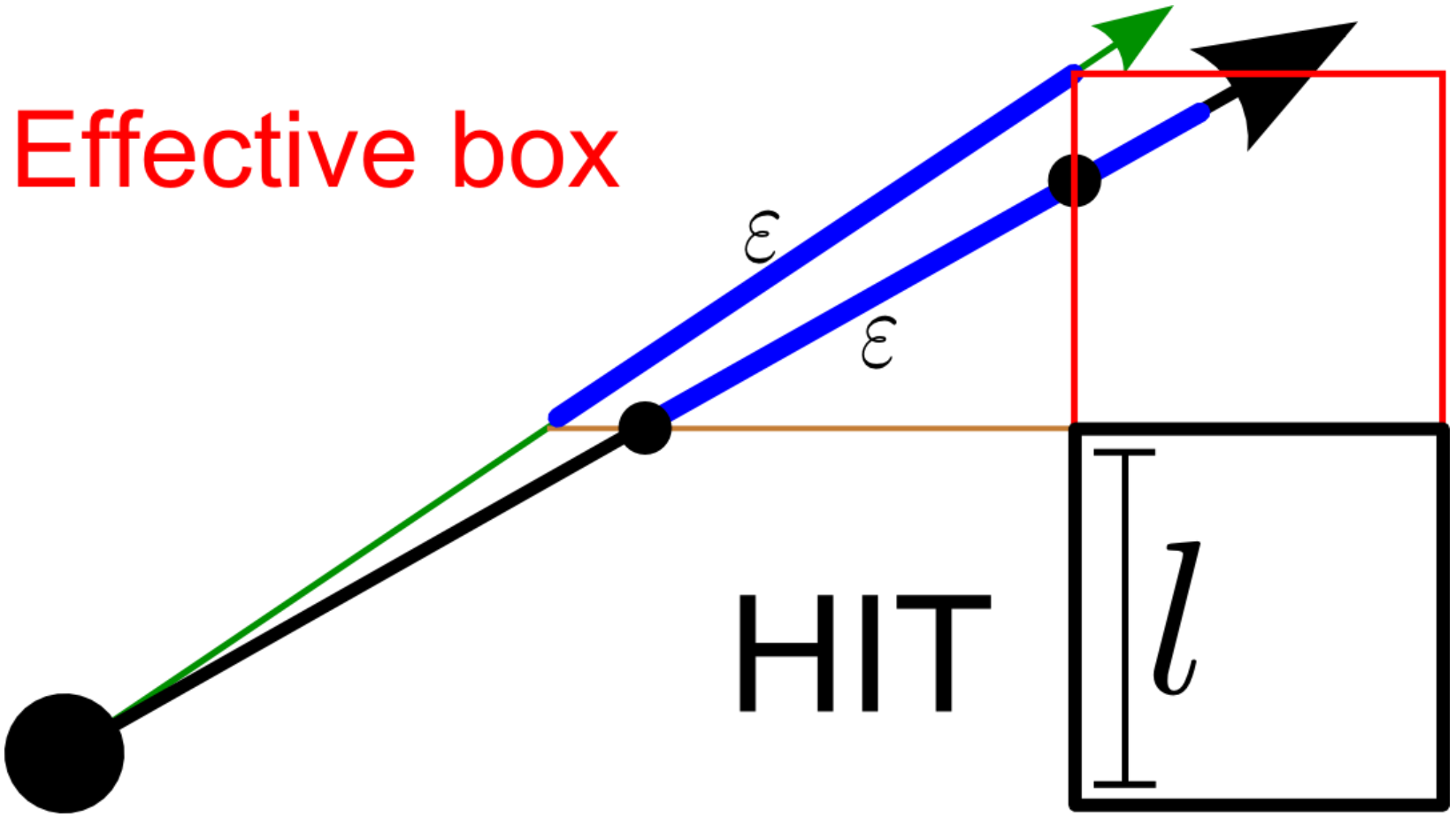

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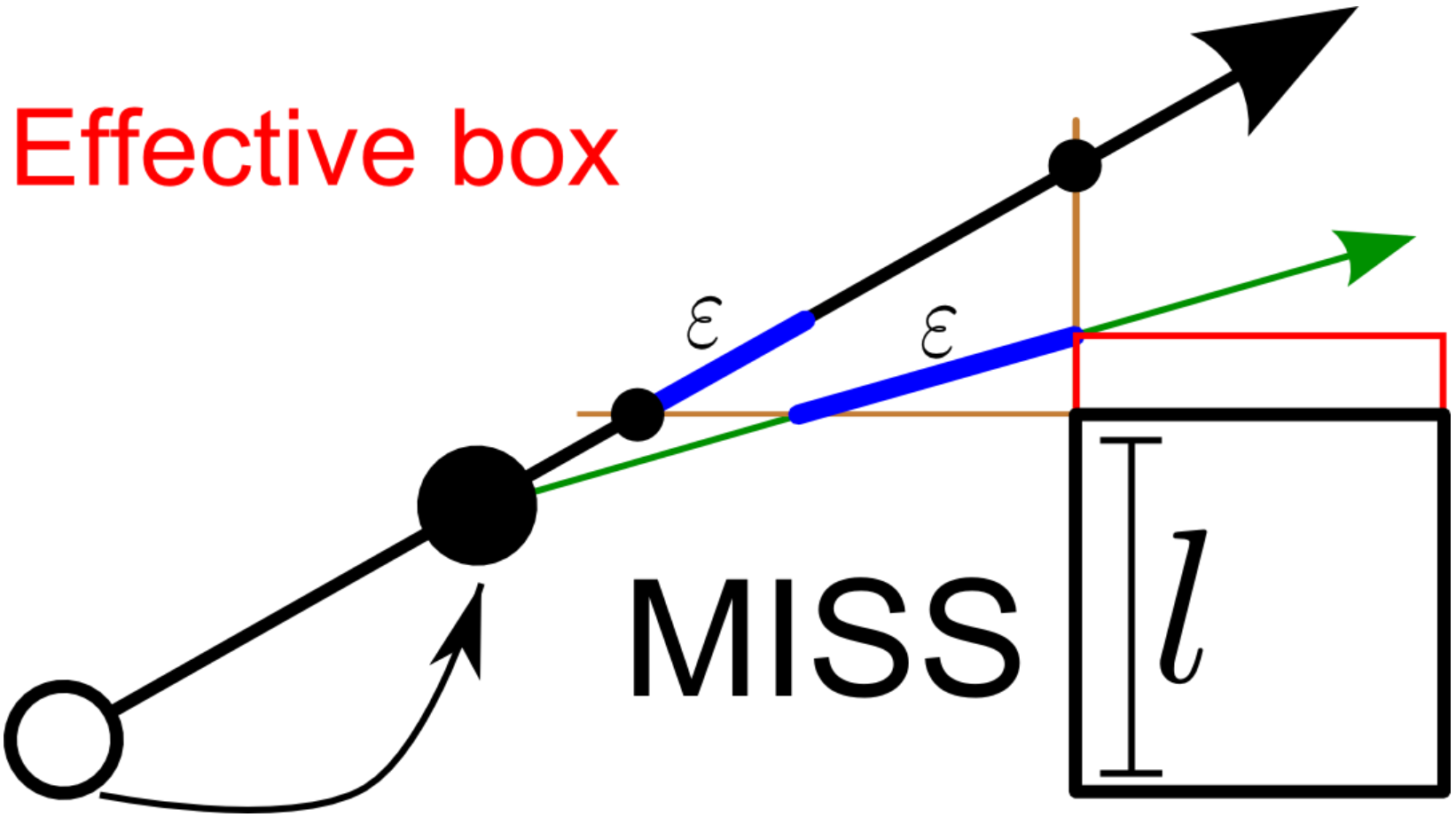


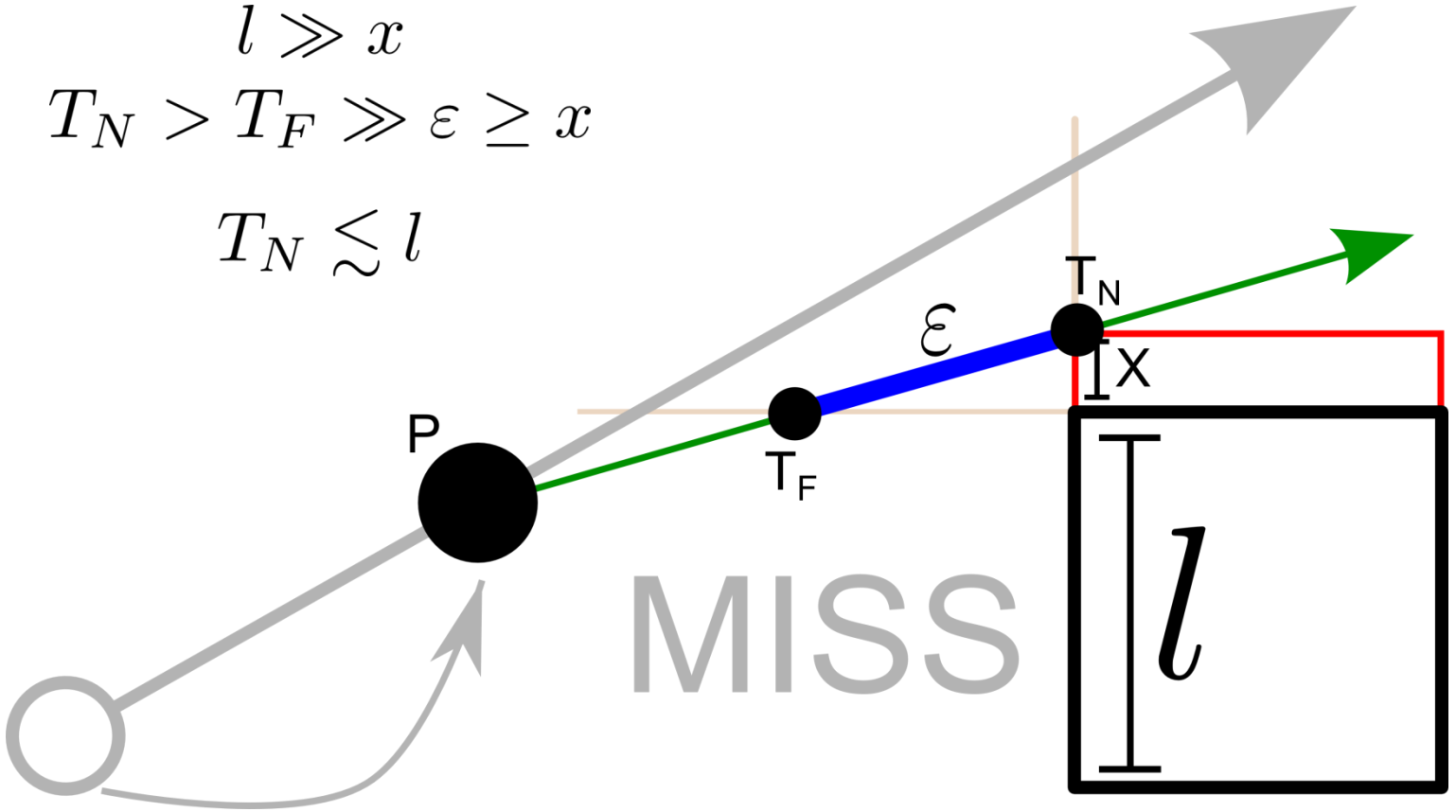
Minimize the *effective* box size

Seek P such that $l + x \approx l$

$$l \gg x$$

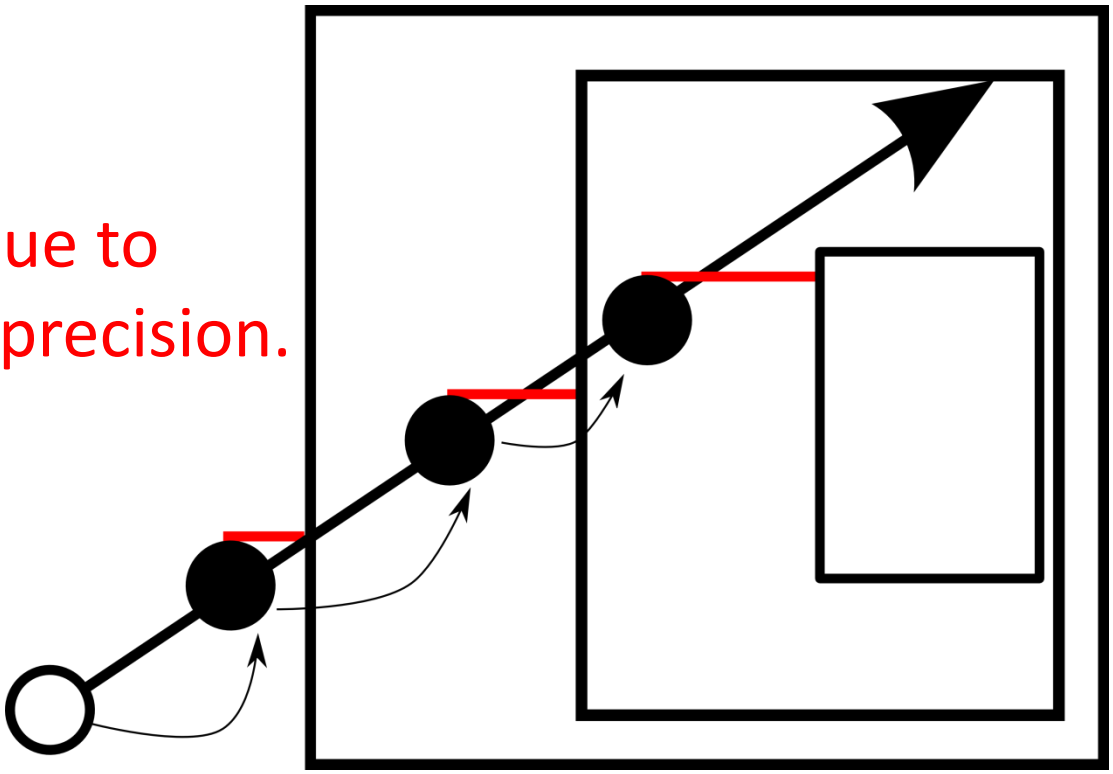
$$T_N > T_F \gg \varepsilon \geq x$$

$$T_N \lesssim l$$



Traversal Point Update

Gap due to
finite precision.



Problems

- Computing T_N needs multiplies
- Unbounded box size
- Multiple applications

Traversal Point Update

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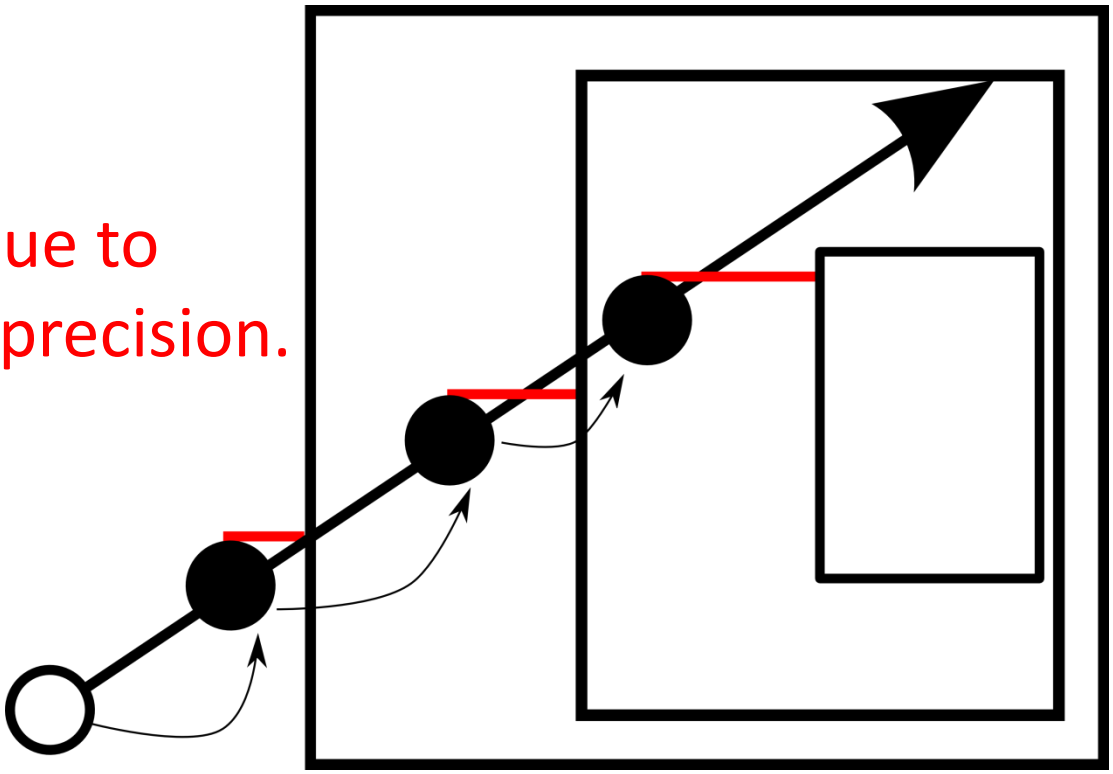

$$f(C+S)=1$$

f Precision of update procedure

S Maximum parent-child edge ratio

C Maximum internal parent-child offset

Traversal Point Update

- 5 bit child boxes -> S=32
  - Need 8 bit arithmetic to guarantee $x \ll l$
- Can actually use just **1 bit**!
  - Incorrectly taken paths are quickly aborted
  - Much smaller than even 8 bit arithmetic
- Reduces precision of the adds and divides as well
  - No need to share divider, replaced with LUT.

Reduced Precision Traversal Unit

- Fixed function traversal unit implements:
  1. **Two 1 bit precision traversal point updates**
  2. Two 5 bit precision robust Ray-AABB tests
  3. Near child detection
  4. Single bit traversal stack
  5. …

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- Fixed function traversal unit implements:
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  5. **…**

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  4. Single bit traversal stack
  5. …

- A fully pipelined traversal unit is roughly 6% the area of a single SIMD FPU in a current GPU.

BVH Compression

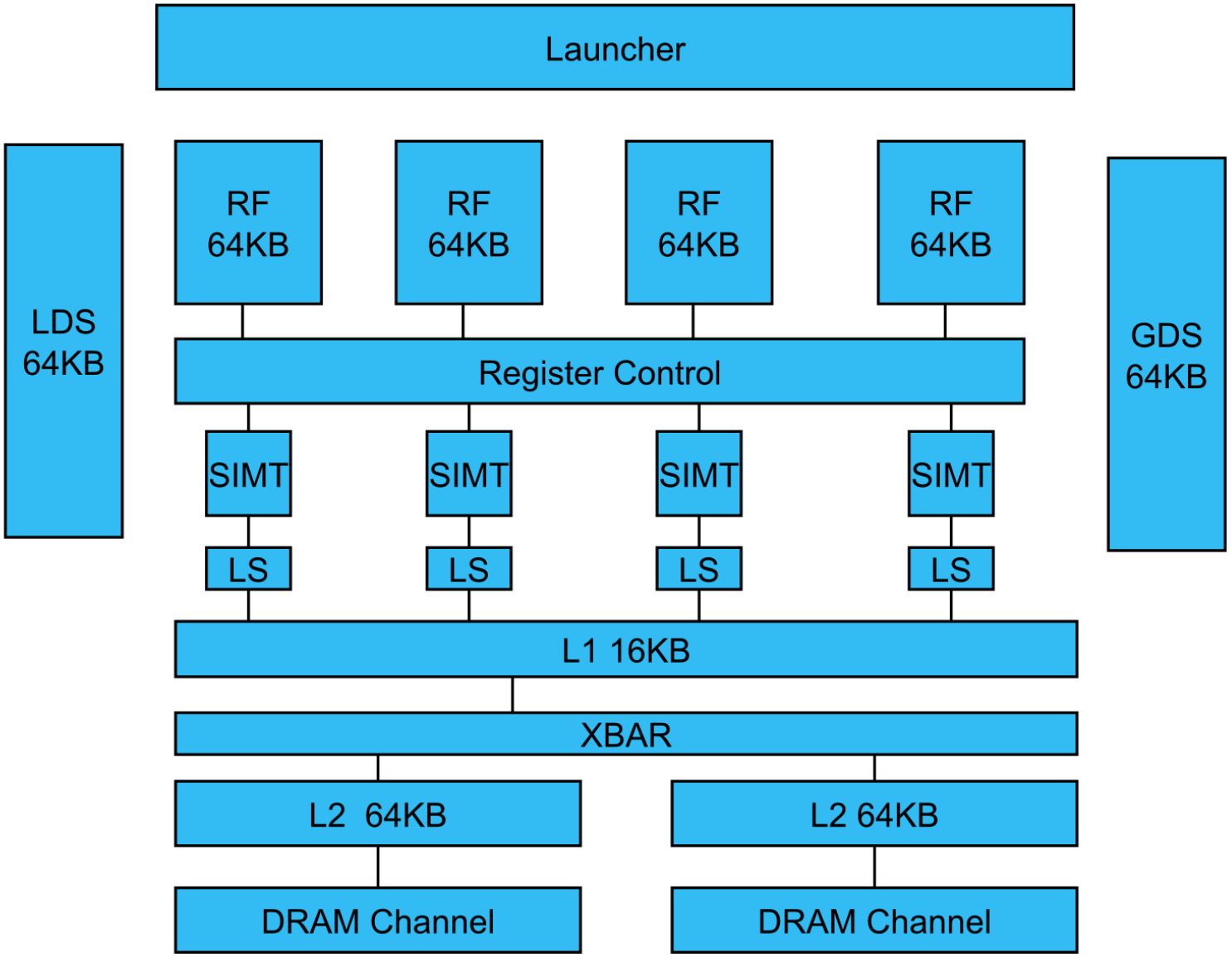
- Traversal inputs drop to 5 bits early on
  - Can’t distinguish all boxes
- Opportunity to save bandwidth!
- BVH boxes are quantized to 5 bits
  - 12 byte node format holding two boxes

GPU Integration & Scheduling

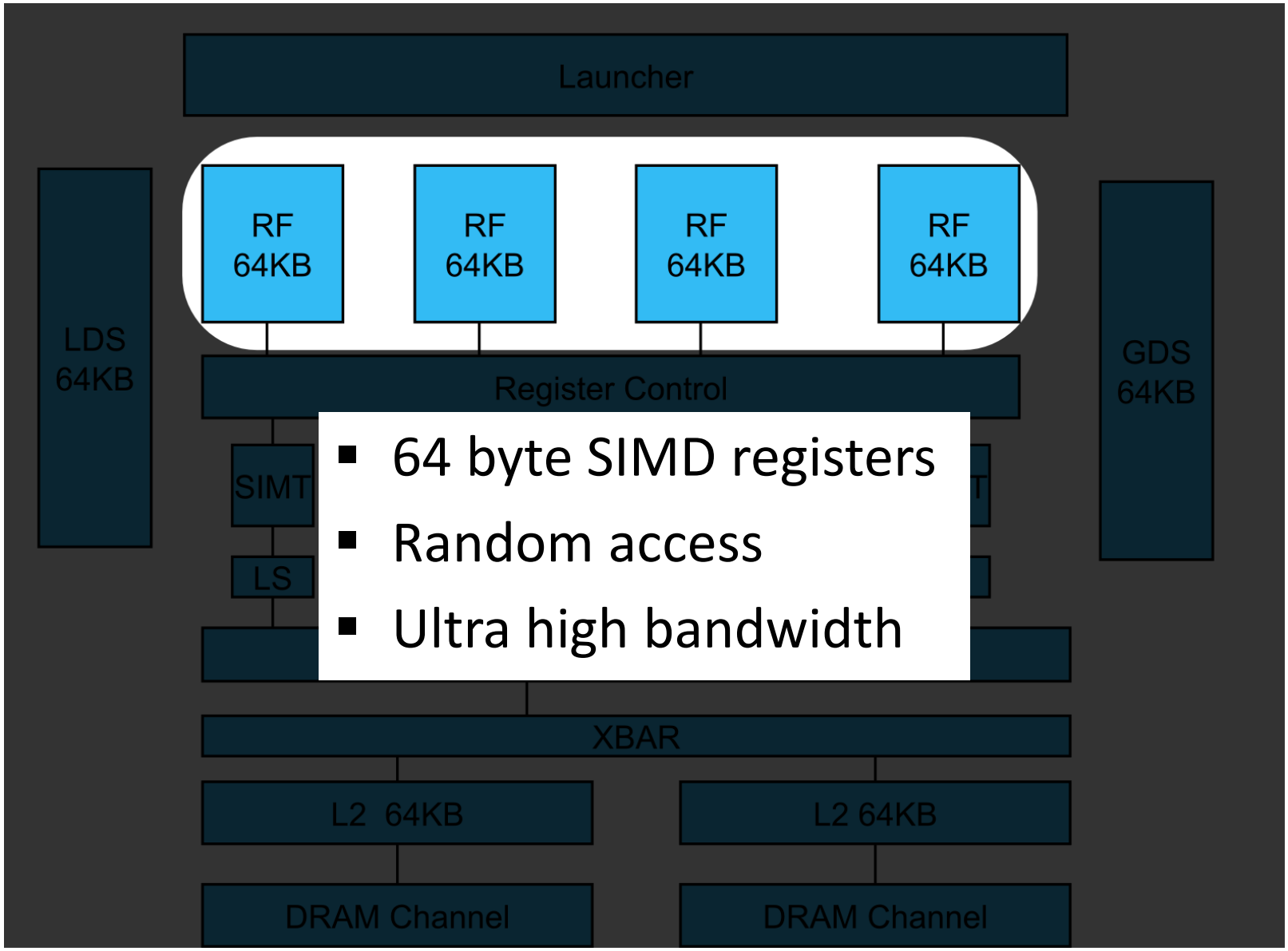
Schedule to minimize off chip traffic

- Treelet scheduling [T. Aila,... ‘10]
  - Smaller is better…but for queuing traffic.
- Stay out of memory!
  - On chip queuing.
- Lots of rays
  - Improve odds of reuse.

We can use everything here

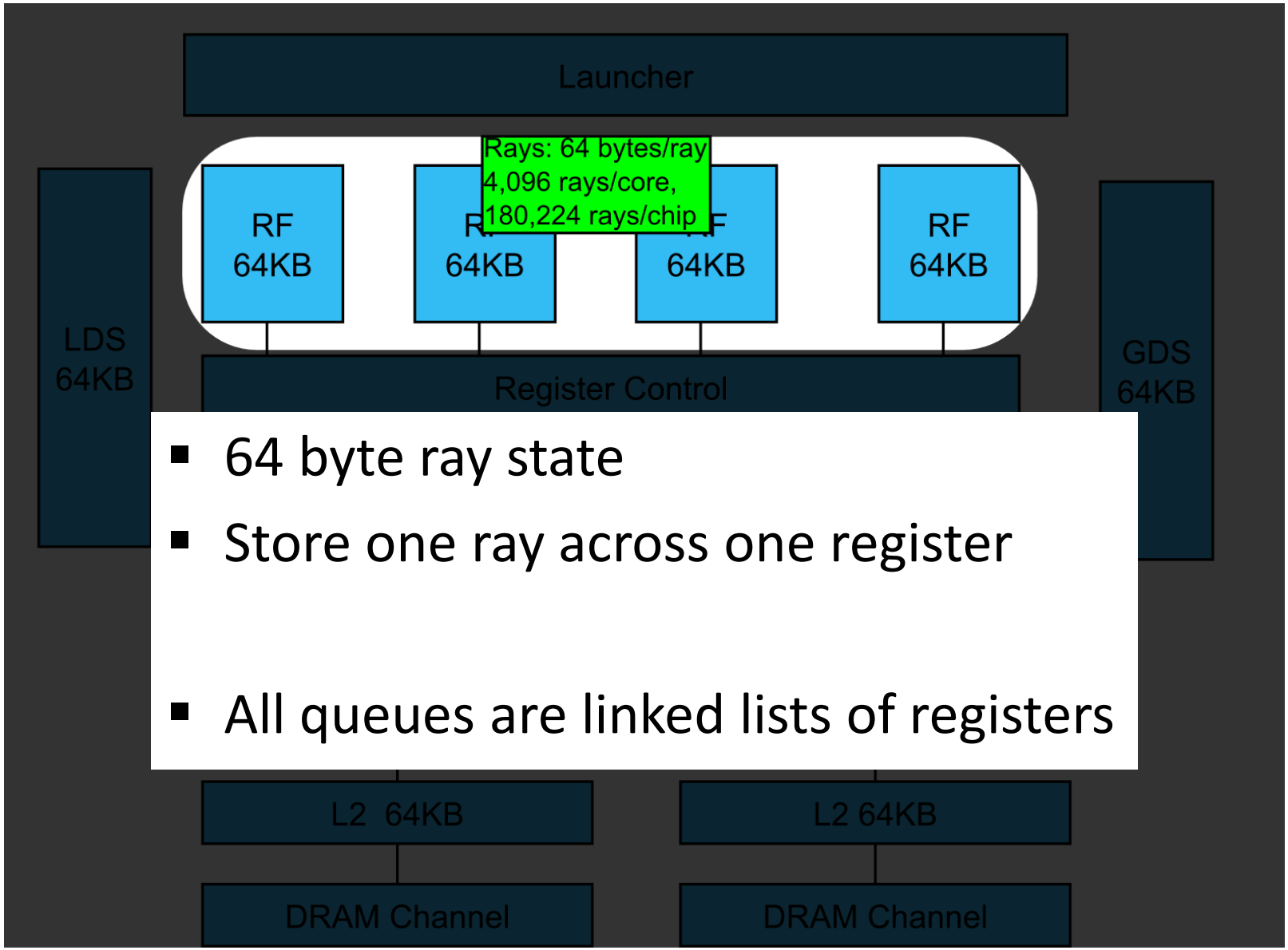


Registers are great for rays



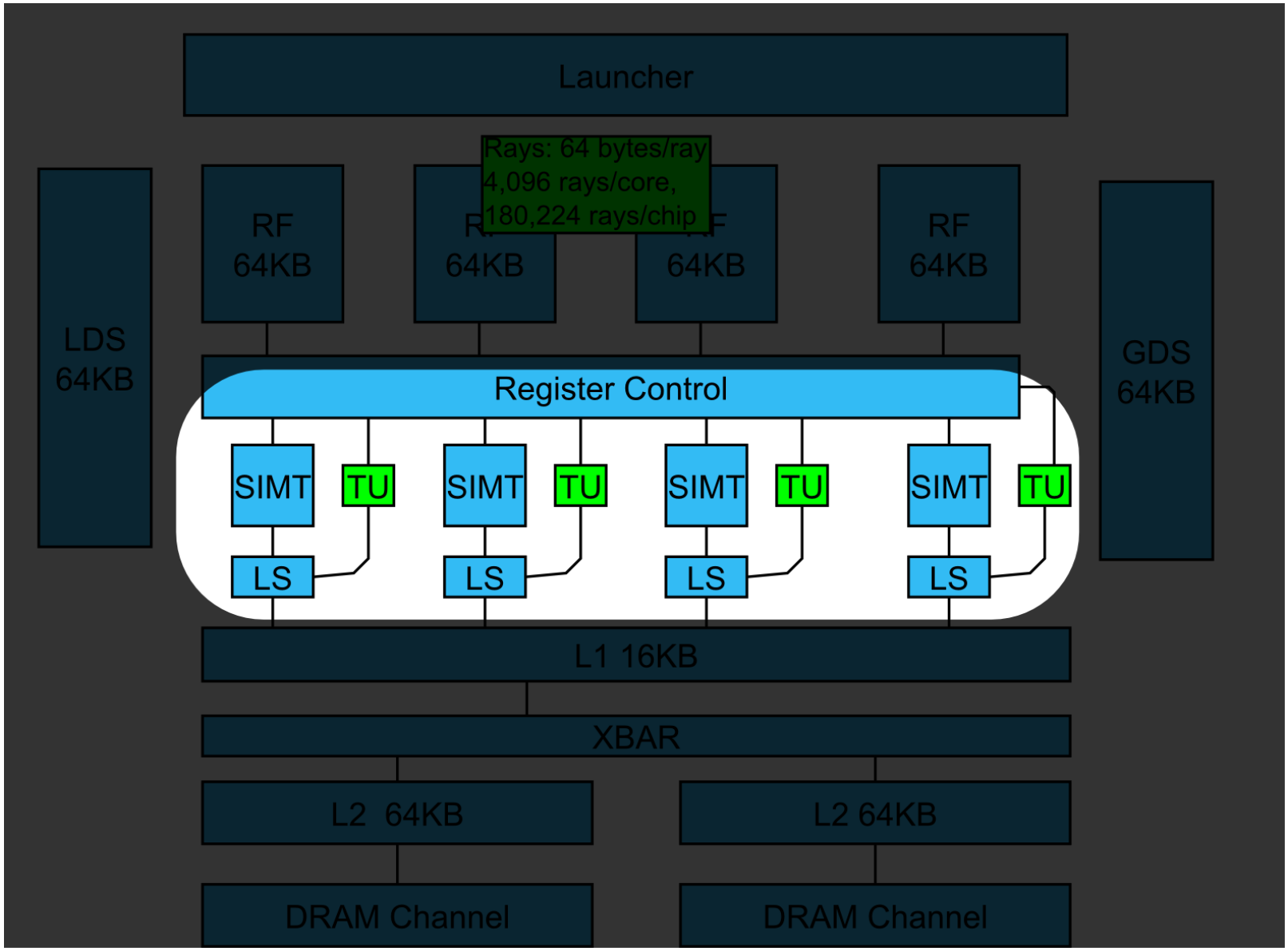
- 64 byte SIMD registers
- Random access
- Ultra high bandwidth

Registers are great for rays

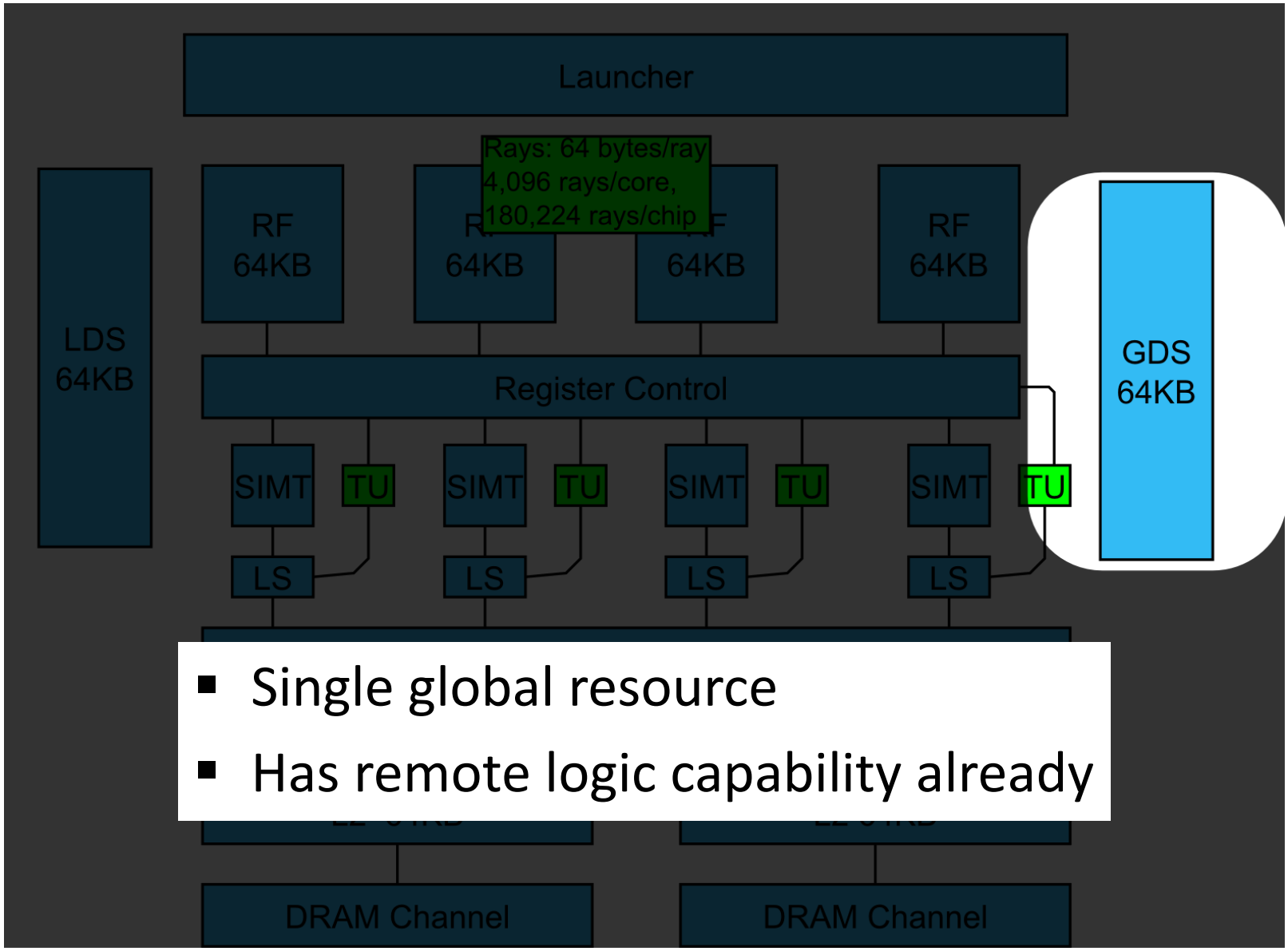


- 64 byte ray state
- Store one ray across one register
- All queues are linked lists of registers

MIMD traversal shares with SIMD core.

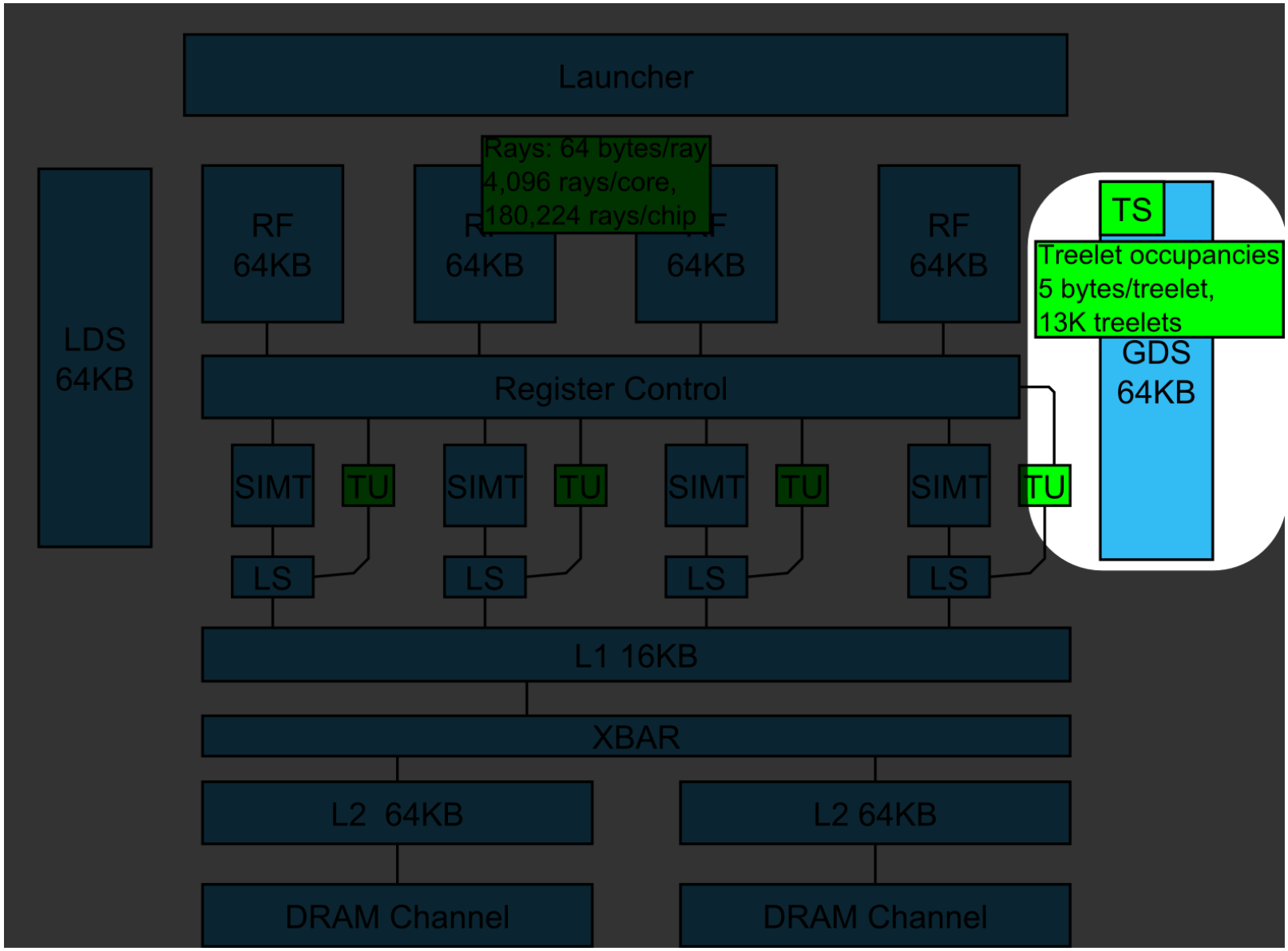


Queue data stays on chip



- Single global resource
- Has remote logic capability already

Queue data stays on chip



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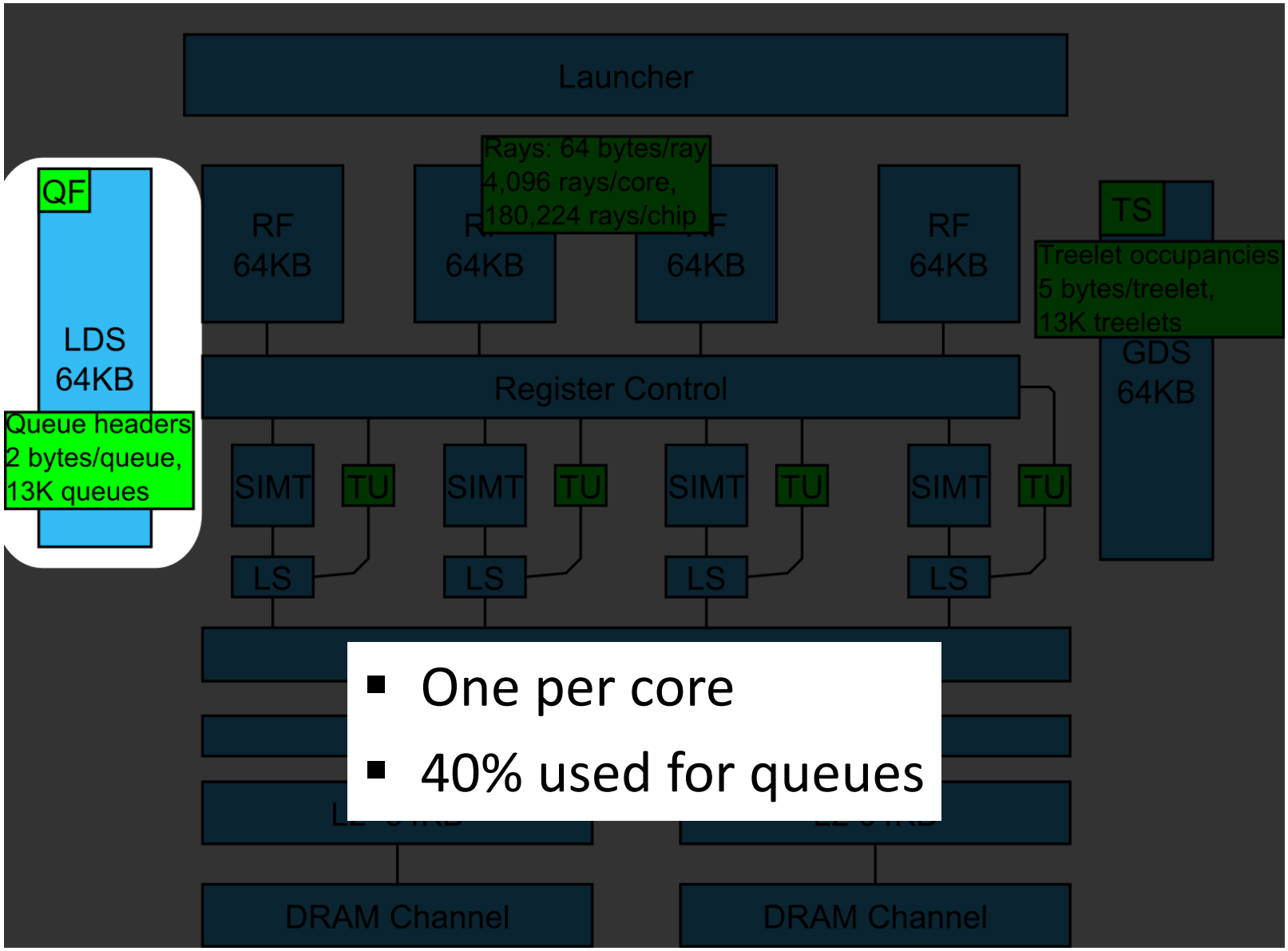
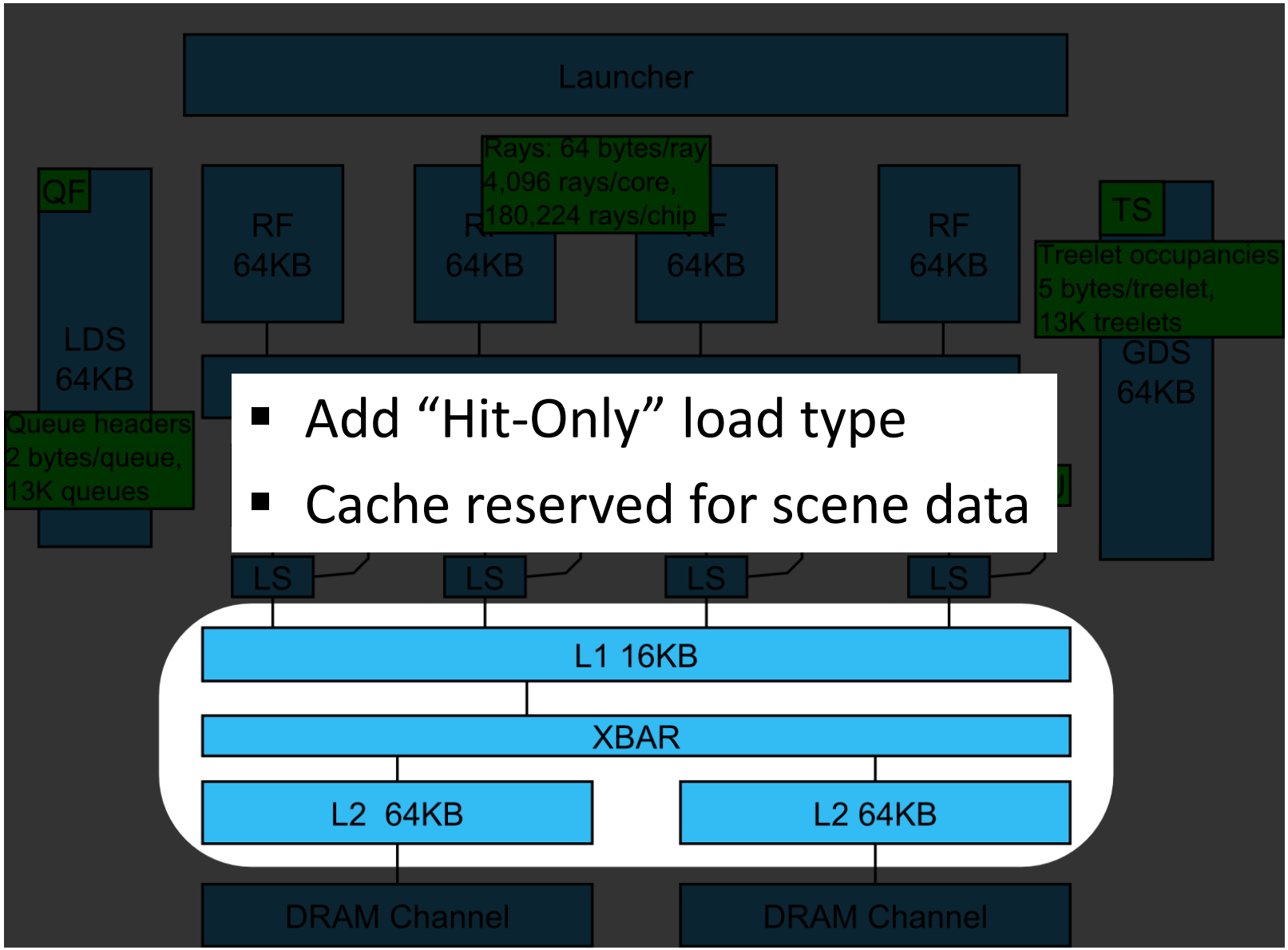
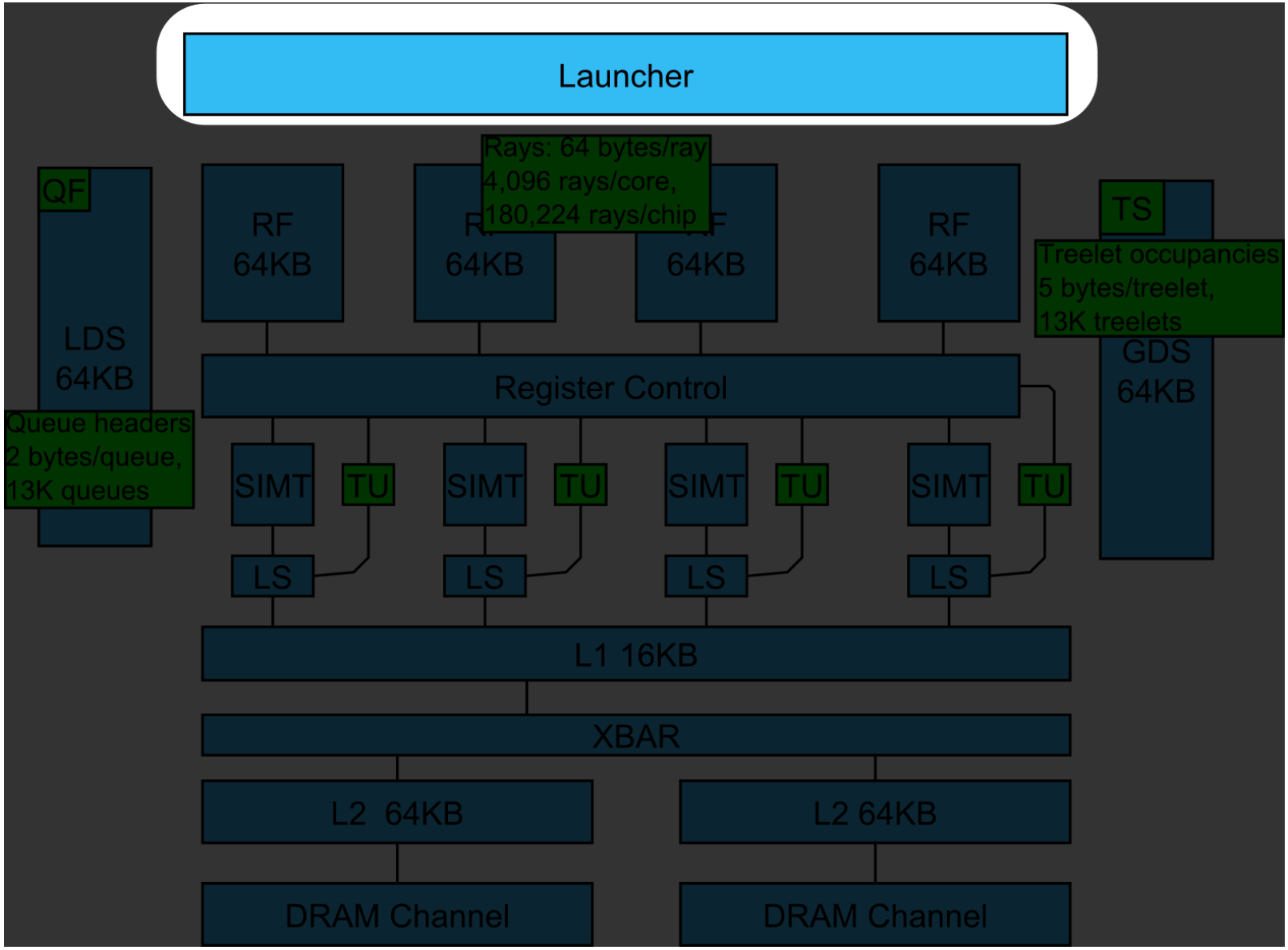


- One per core
- 40% used for queues

Queue rays when data is expensive



Queue based intersect and shading



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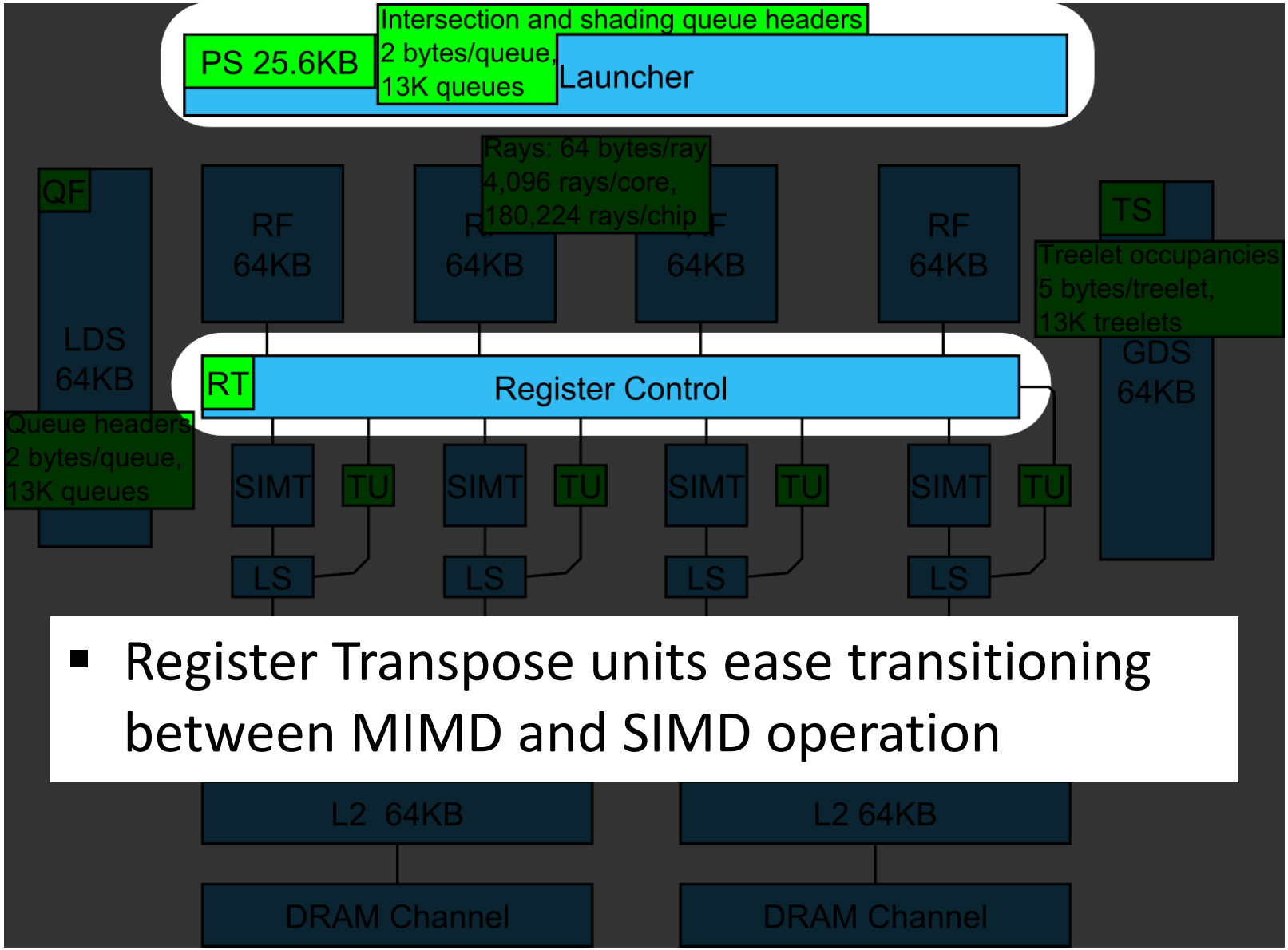
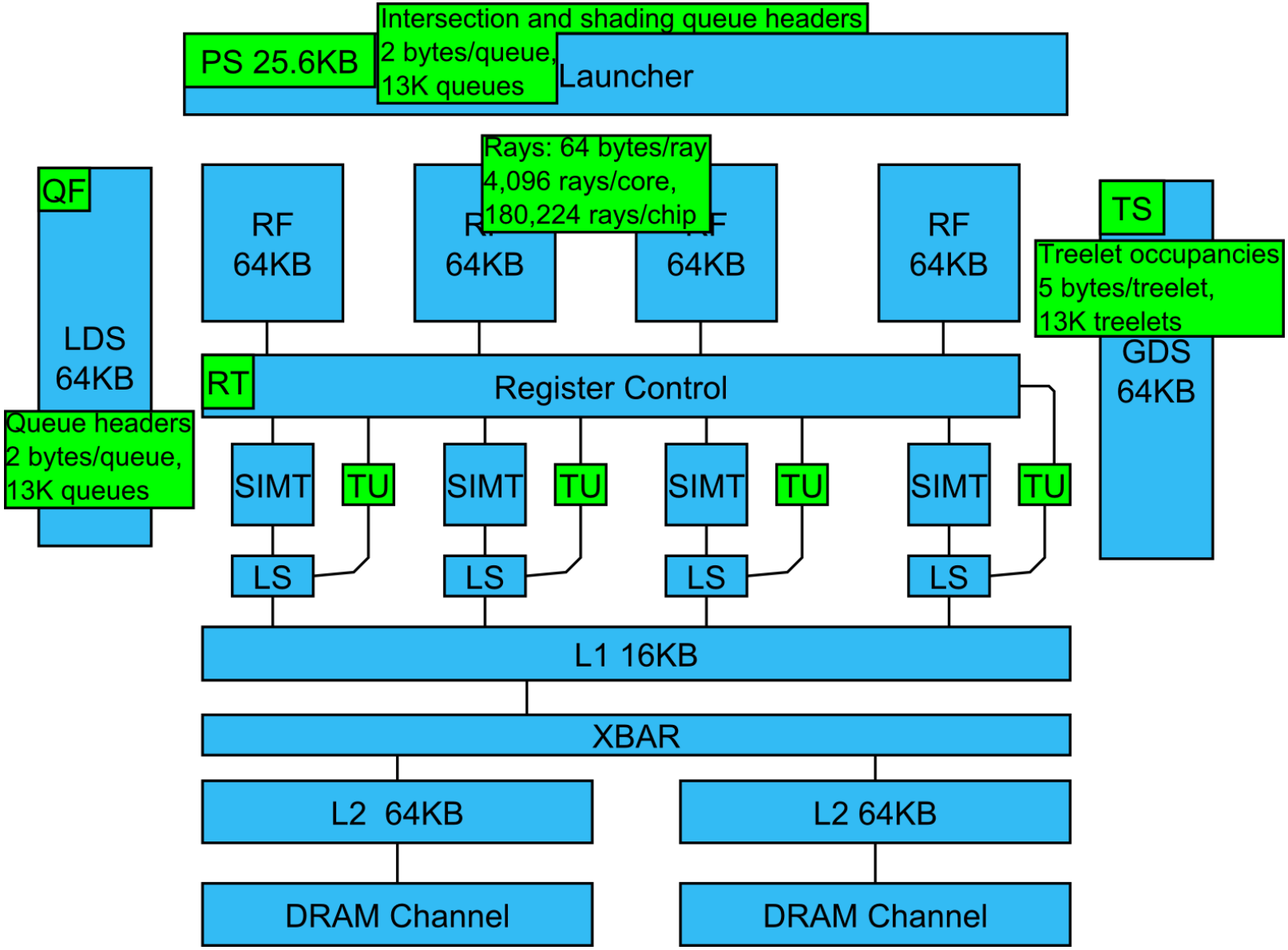


- Register Transpose units ease transitioning between MIMD and SIMD operation

Ray tracing fits in current GPUs

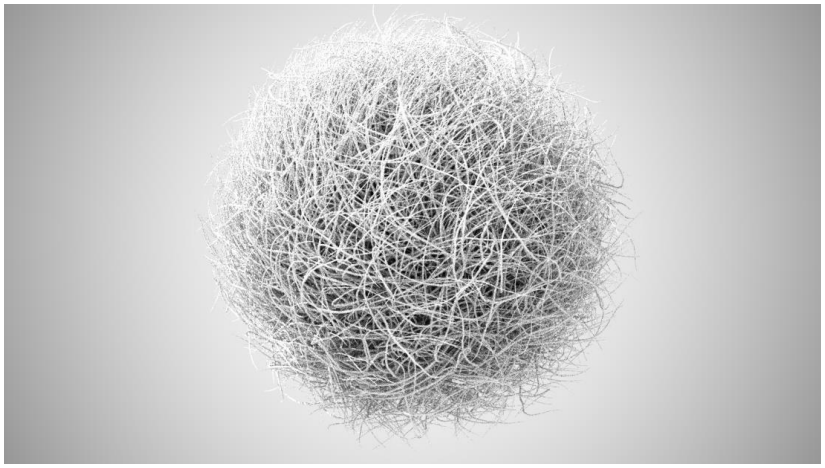


Evaluation

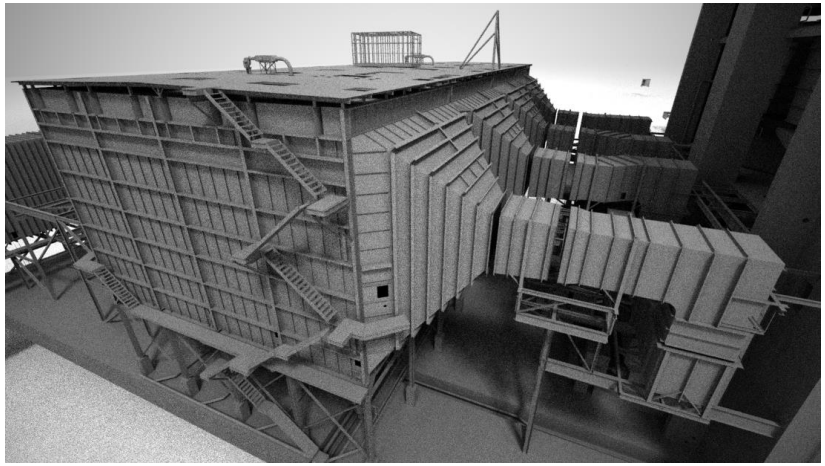
Experimental setup

Two simulators measure key metrics

Crown: 4.9M Triangles



Hairball: 2.9M Triangles

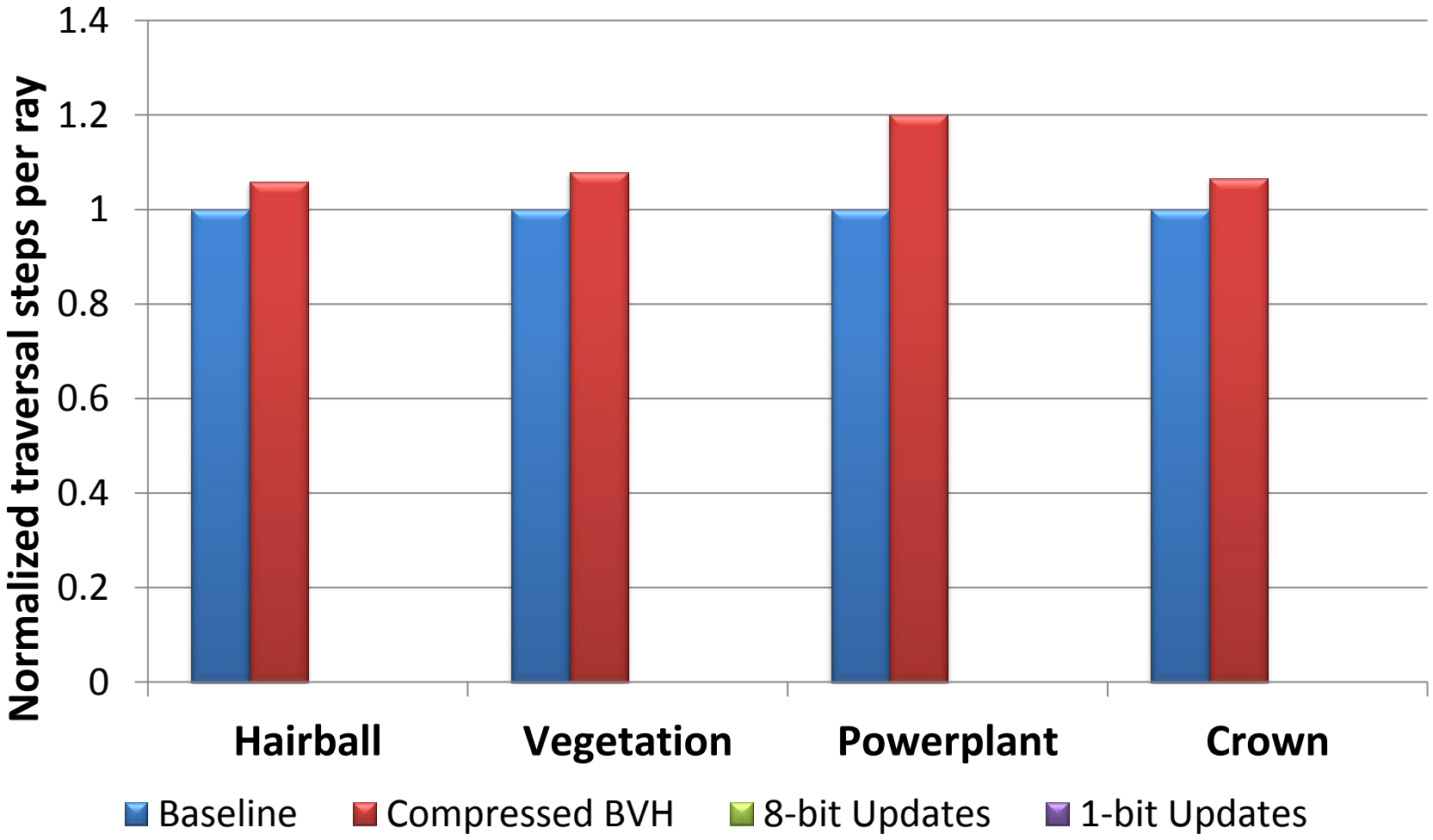


Powerplant: 12.8M Triangles

Vegetation: 1.1M Triangles

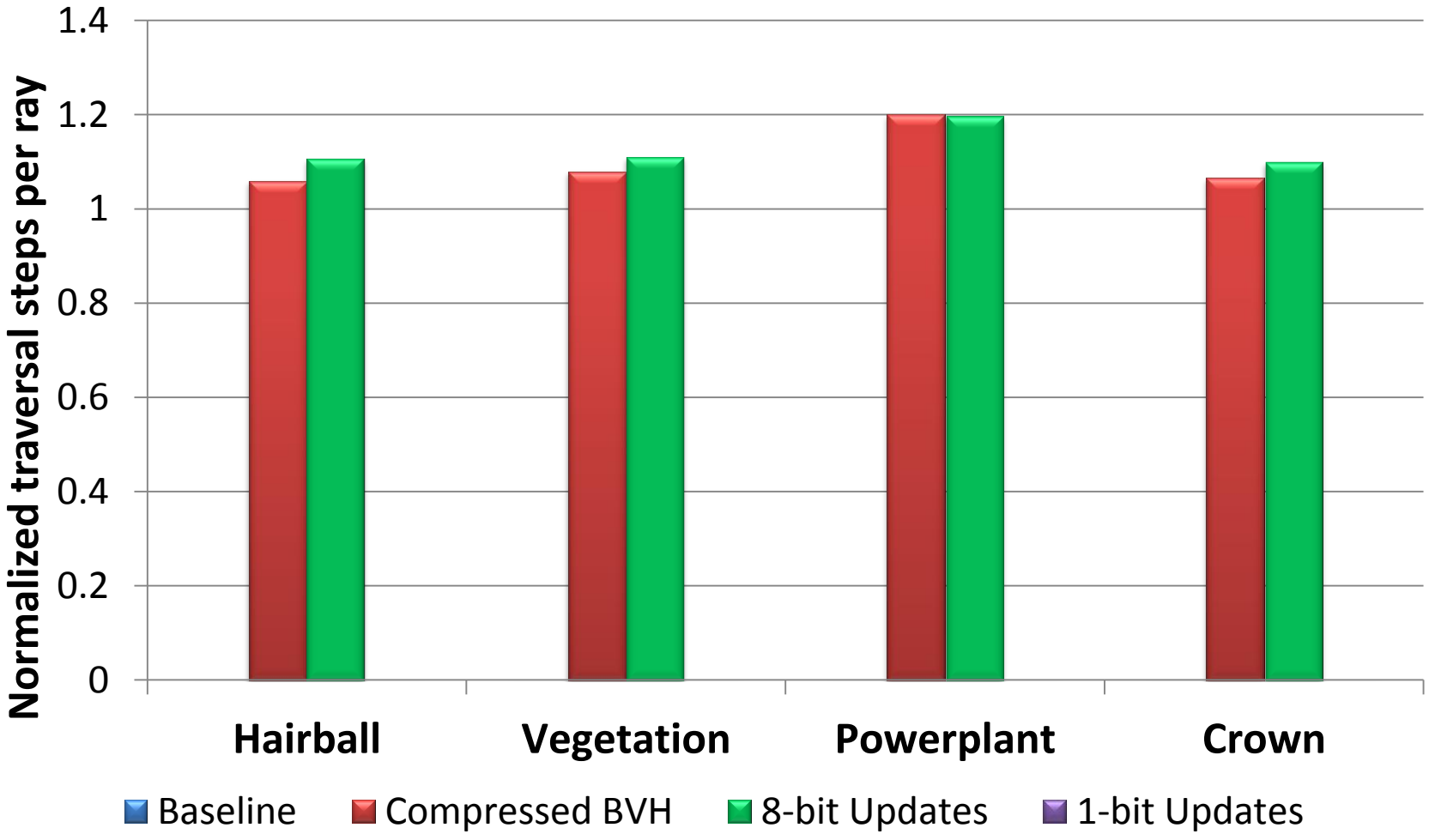
Reduced precision has low costs

Compressed BVH: 7% more work (usually)



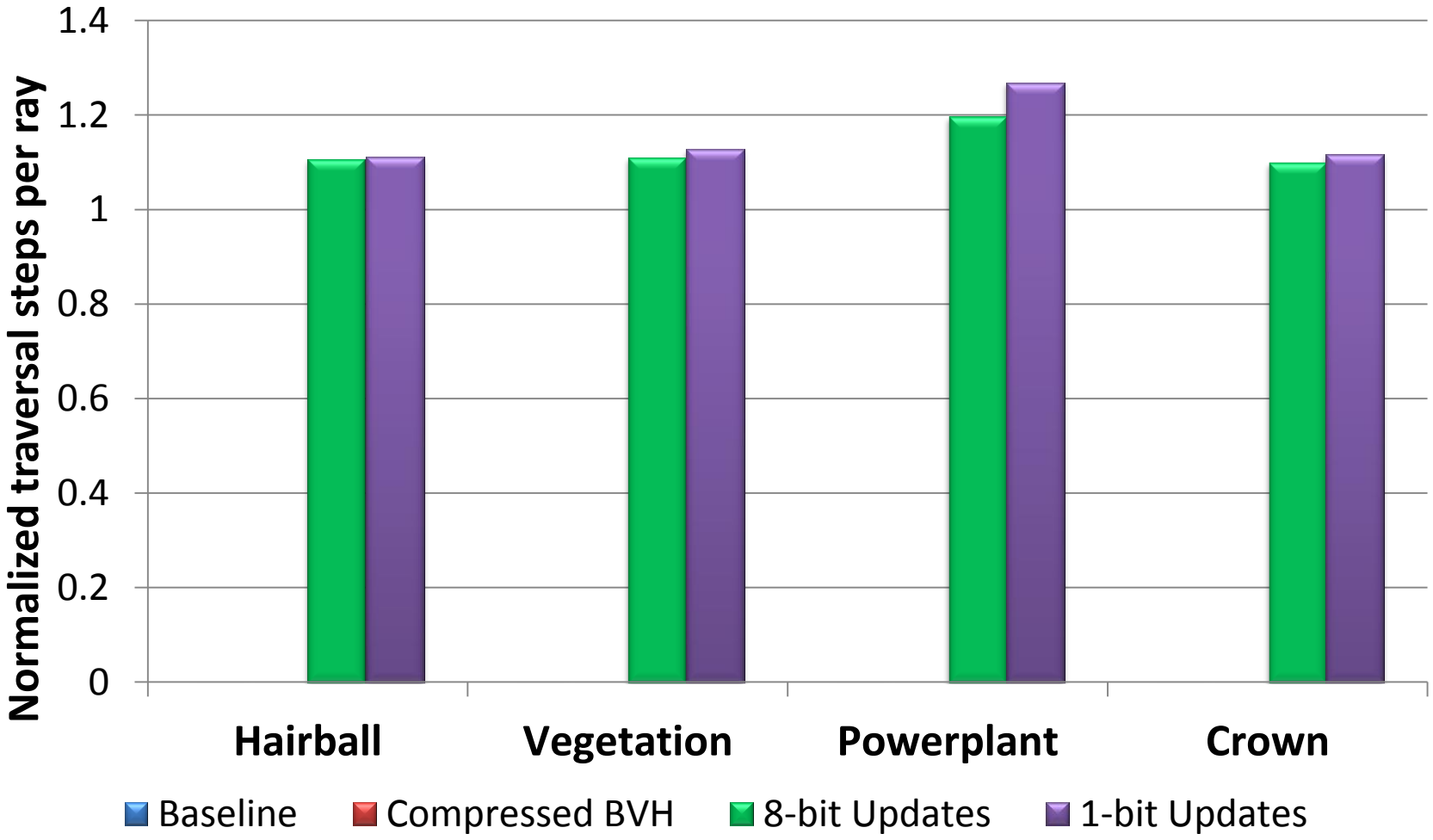
Reduced precision has low costs

Reduced Precision Traversal: 3% more work



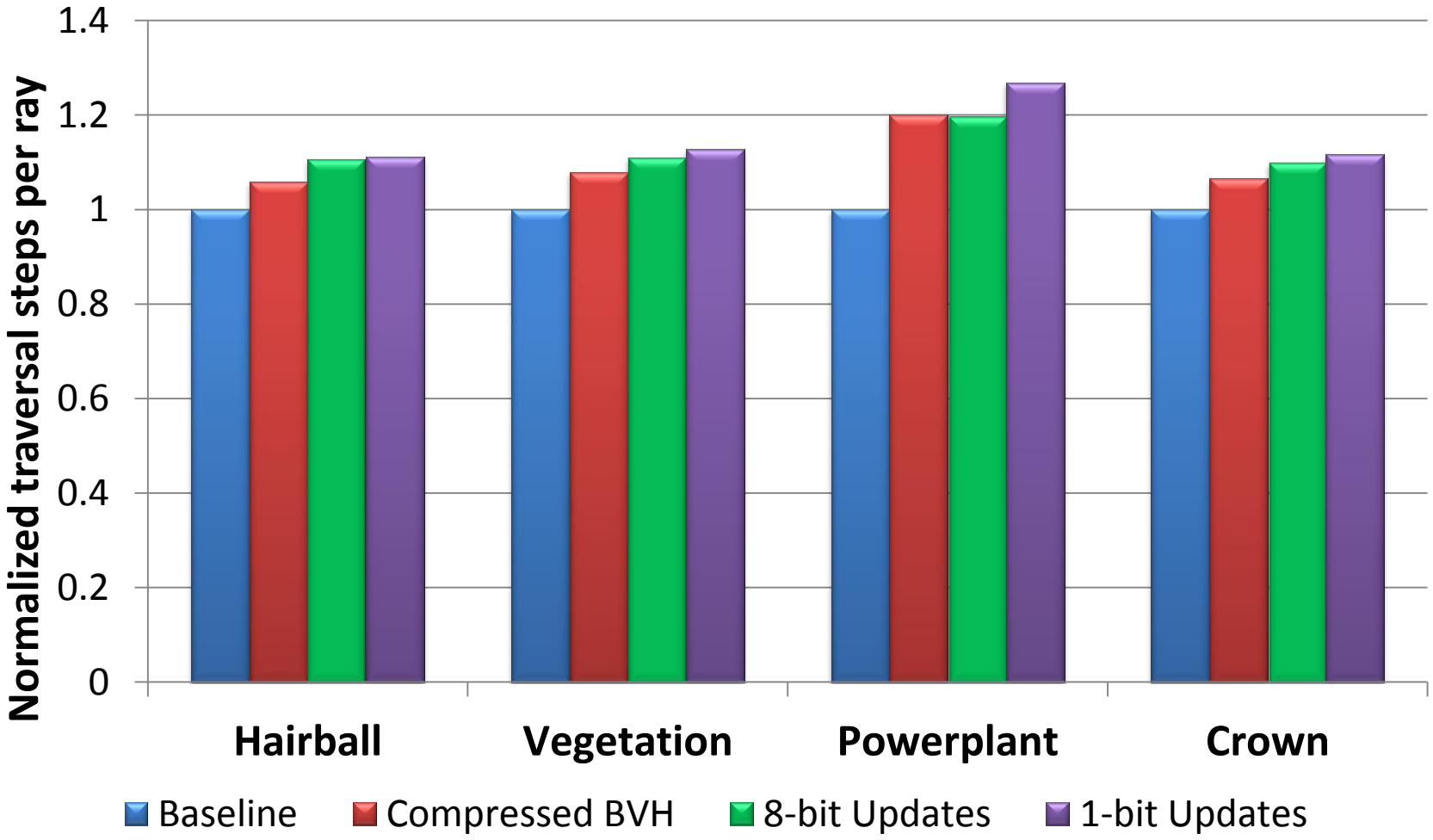
Reduced precision has low costs

1-bit Traversal Point Update: 1-2% more work



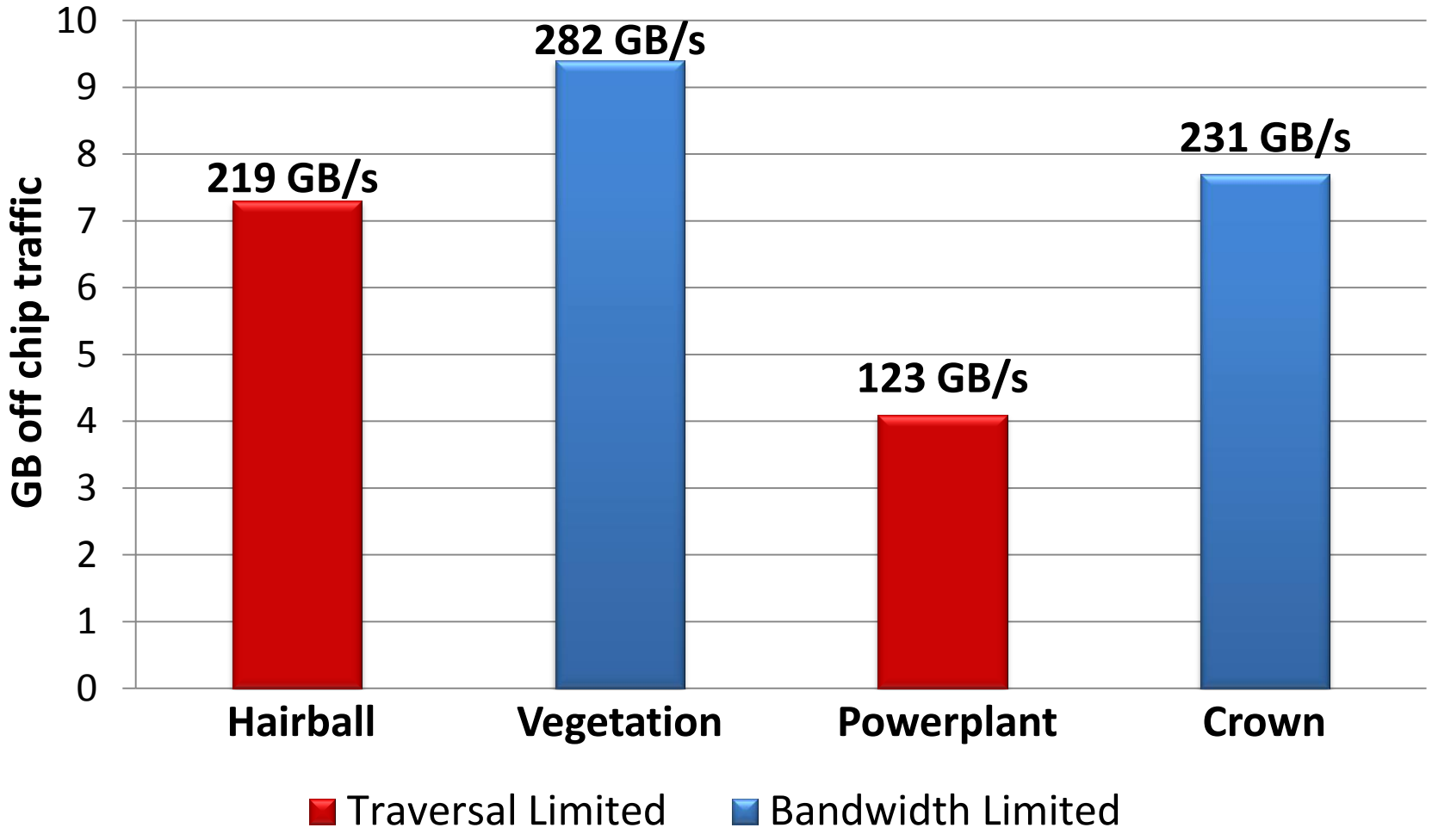
Total overhead is small

10-15% (usually)



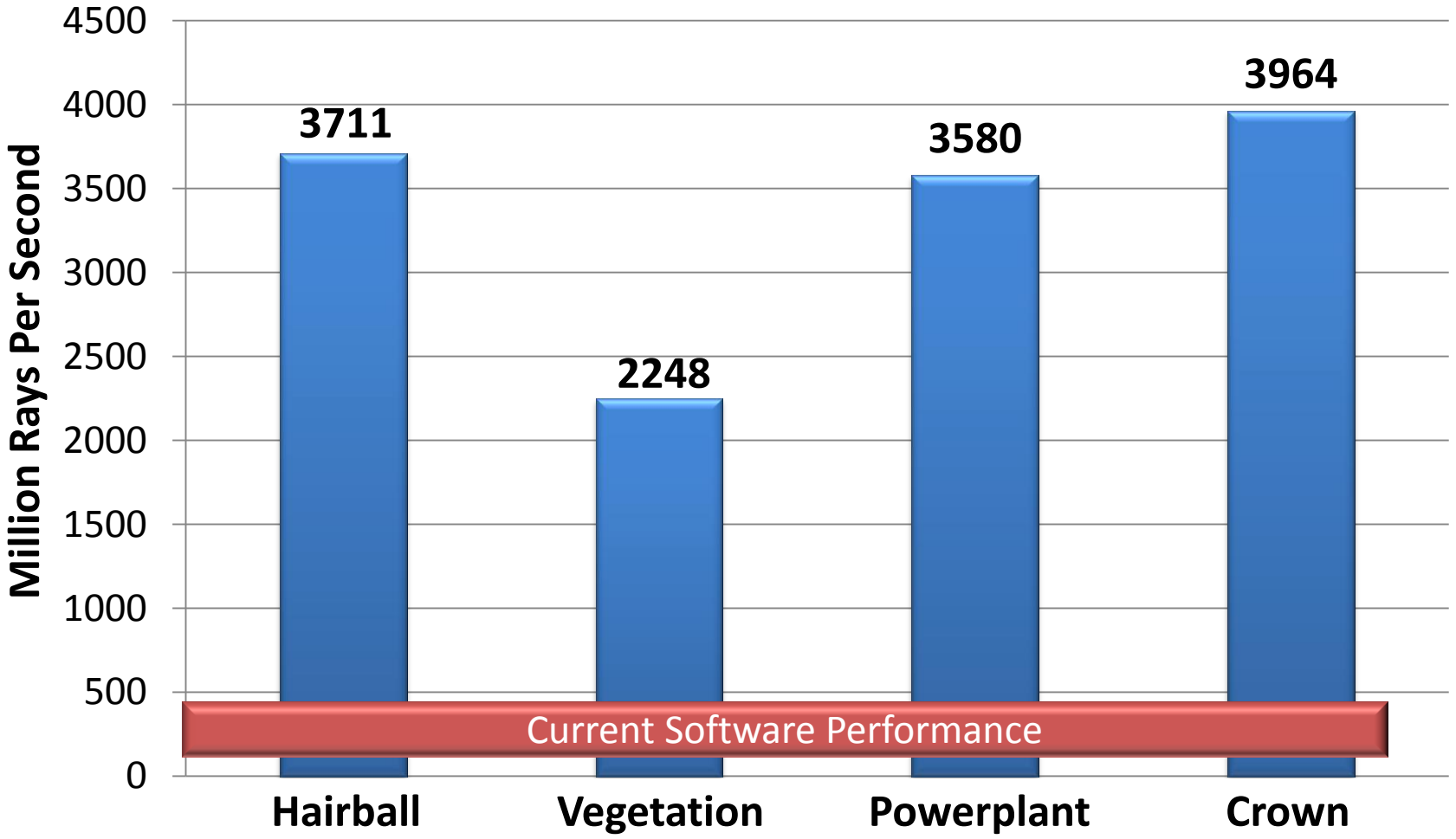
Off chip traffic is in the real time range

Simulated workload set to 30 frames per second



Simulated ray rate

Average ray rate: 3.4 Billion rays/s



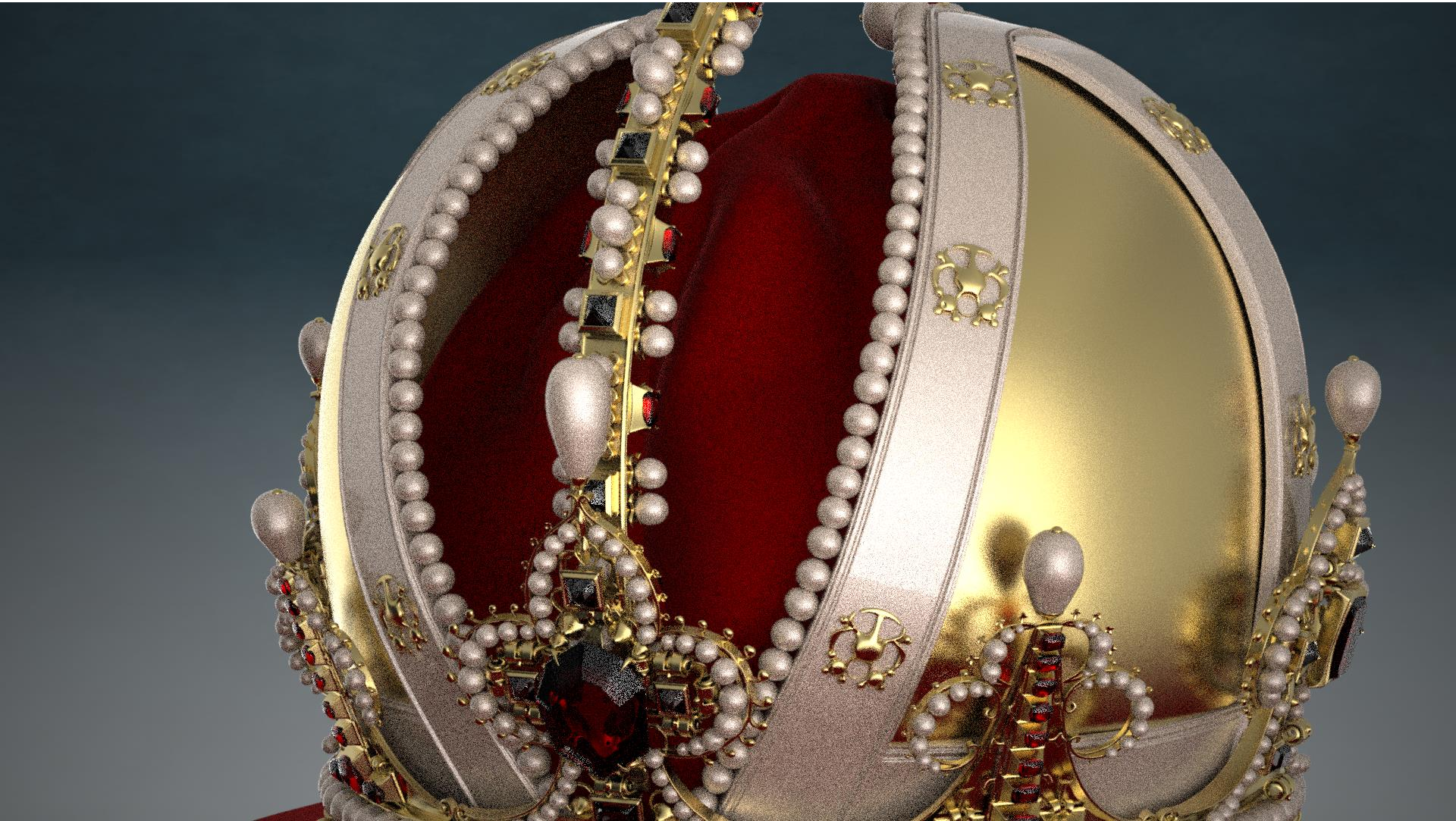
Conclusion

- Reduced precision yields surprising performance benefits…roughly 20x.
- Hardware ray tracing acceleration can be a lightweight feature of modern GPUs.

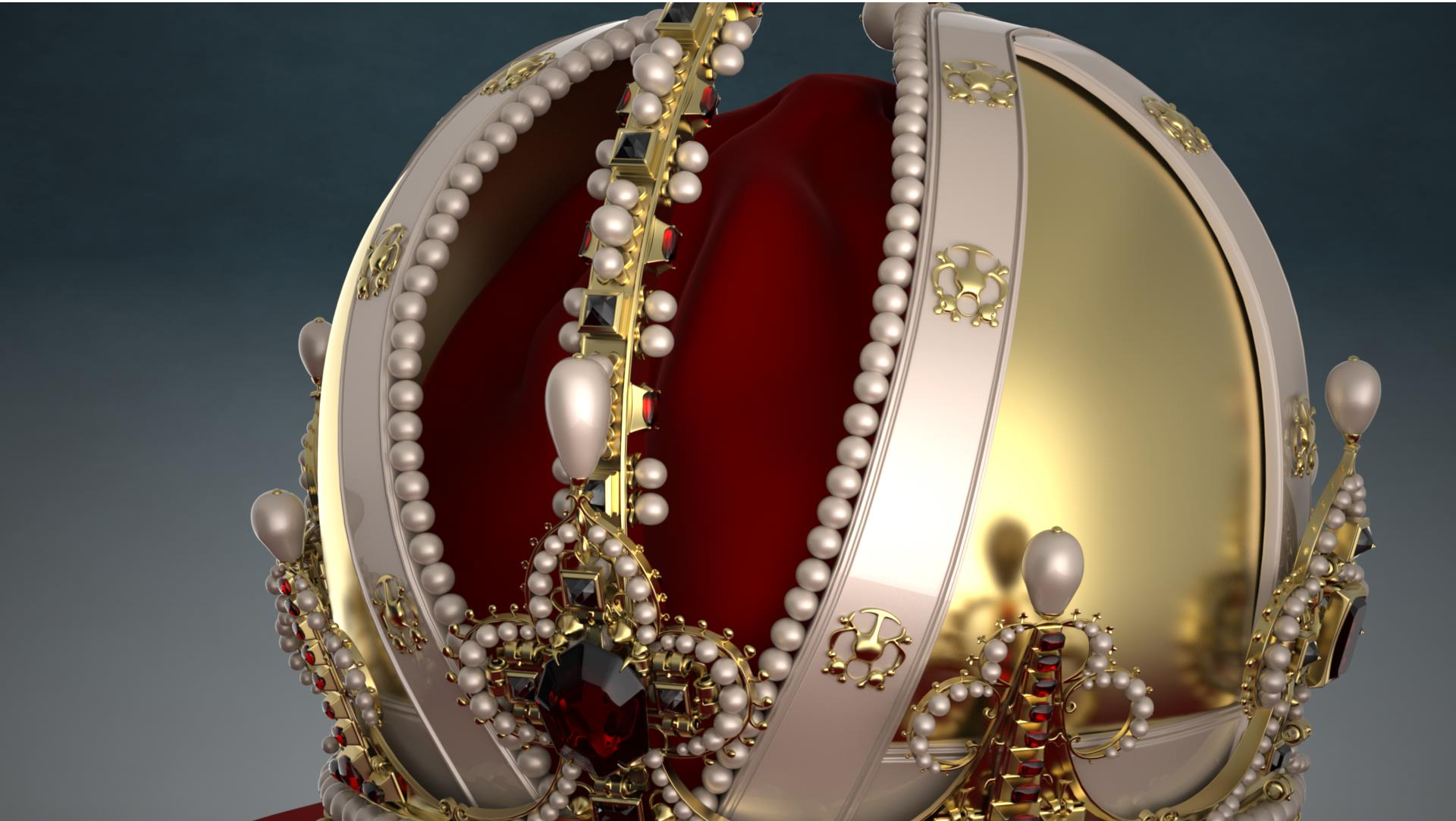
Acknowledgements

- Samuli Laine for use of Vegetation and Hairball
- Martin Lubich & Intel for use of Crown
- Daniel Kopta for assistance with comparisons in the paper
- UT Graphics group and others for many useful discussions

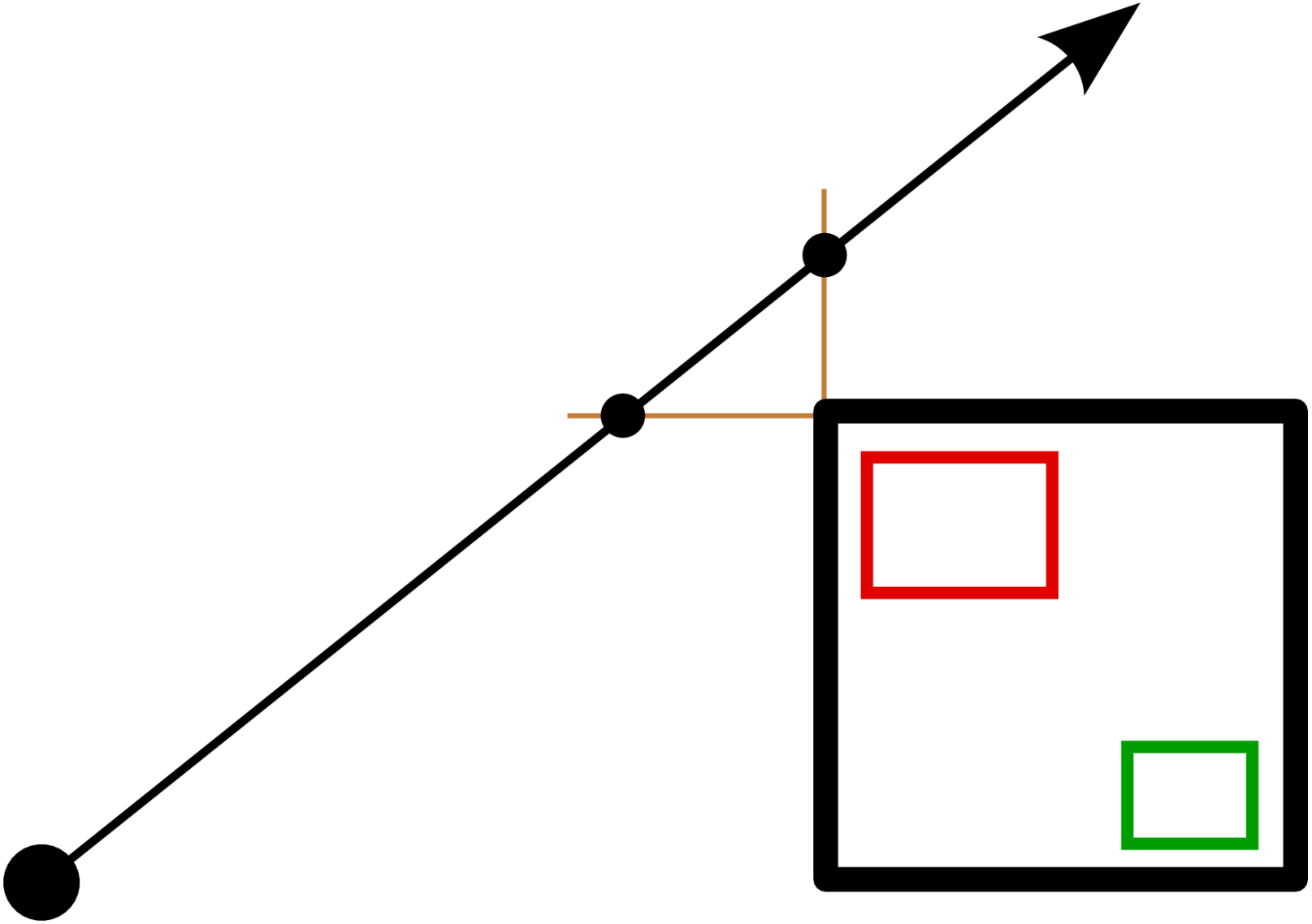
Questions?



Ground Truth



Incorrectly taken paths abort quickly



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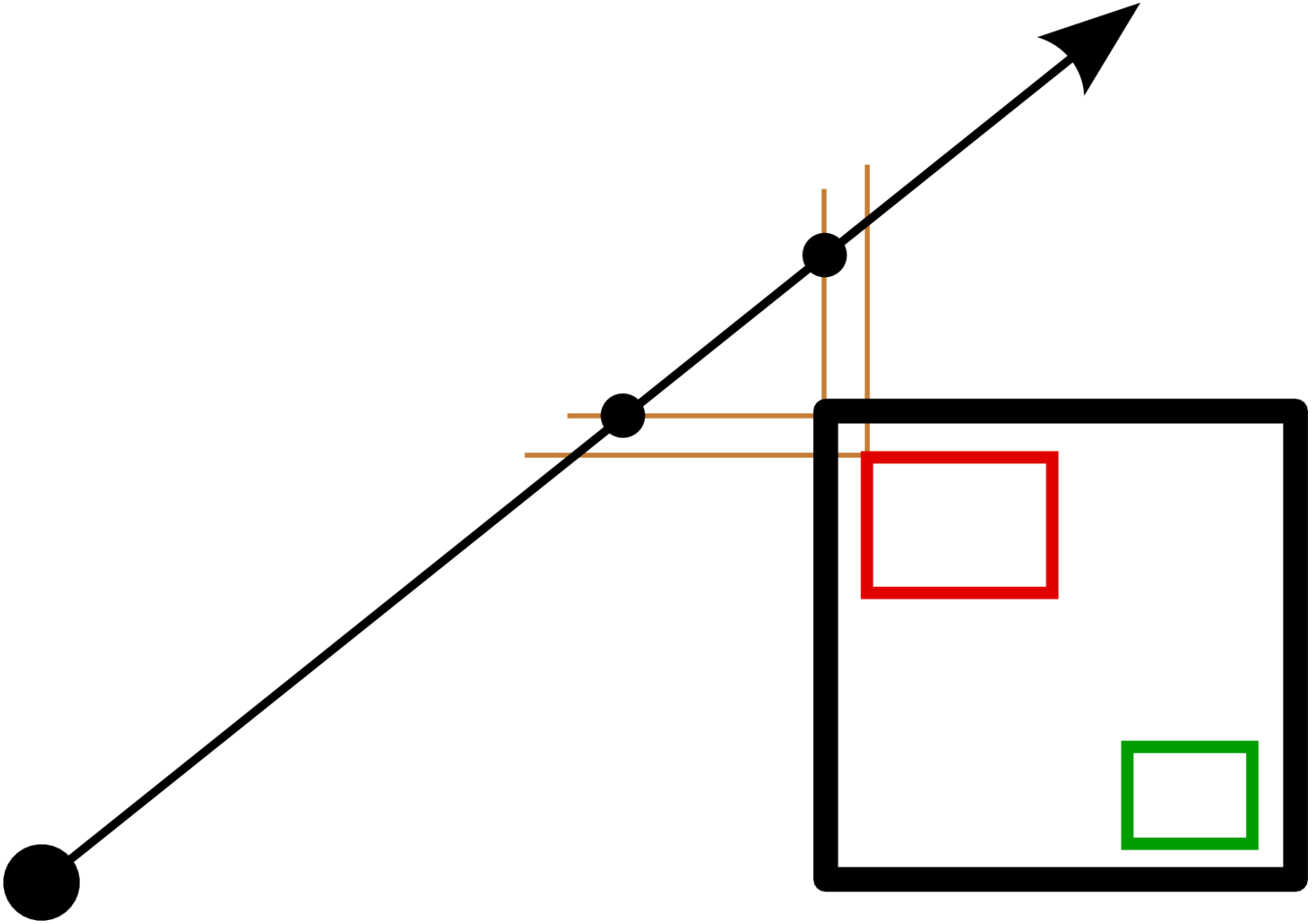

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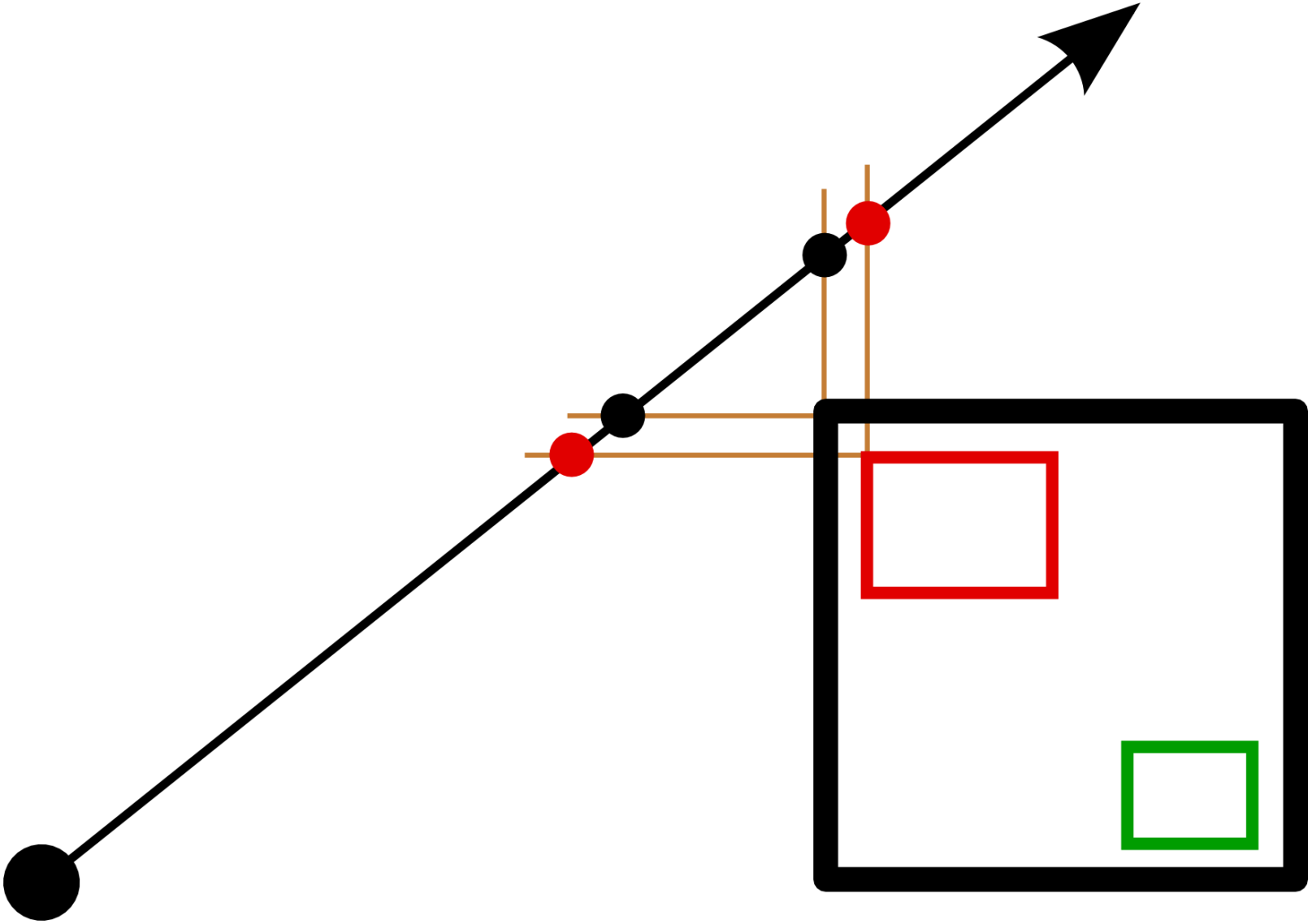

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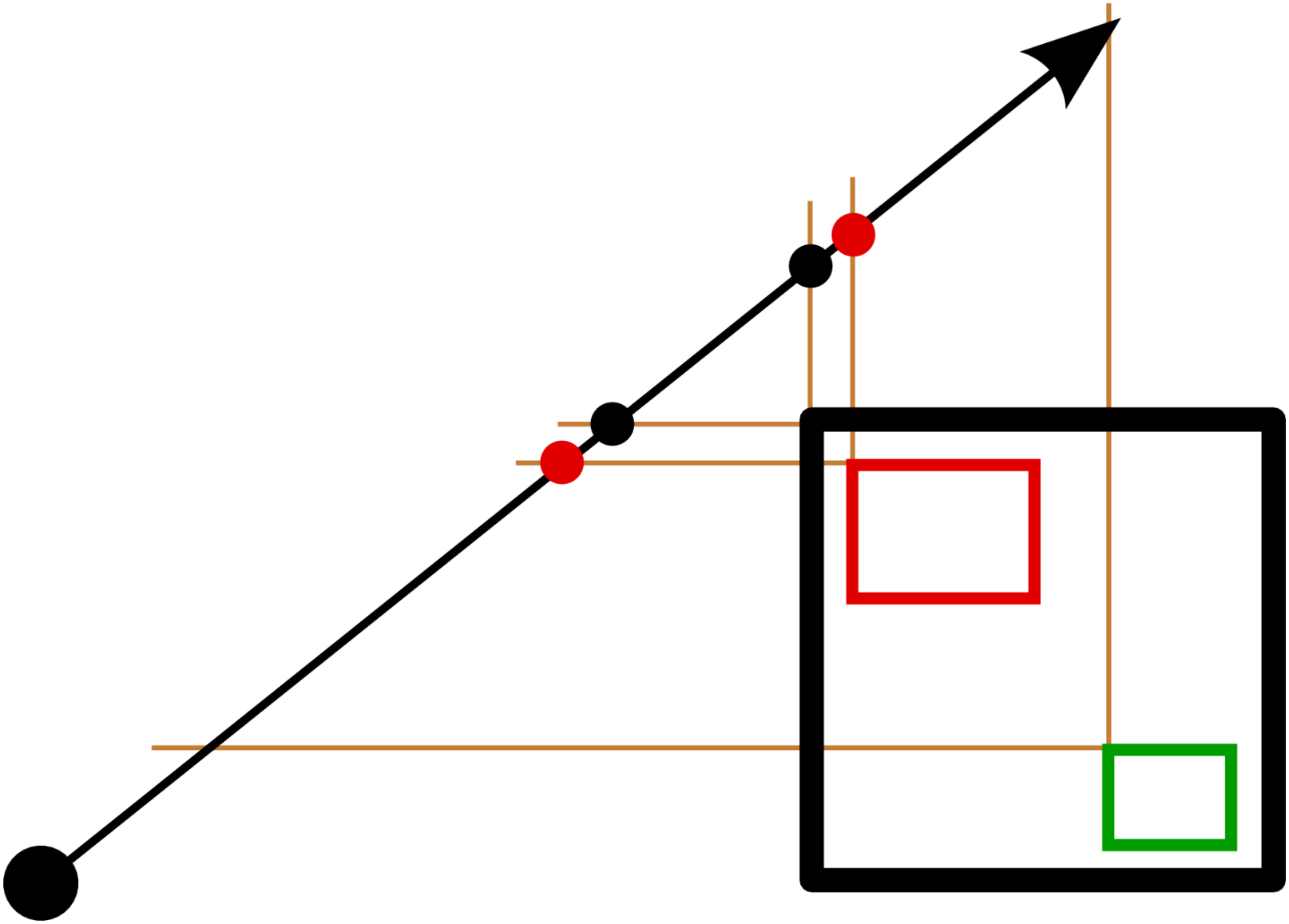

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