

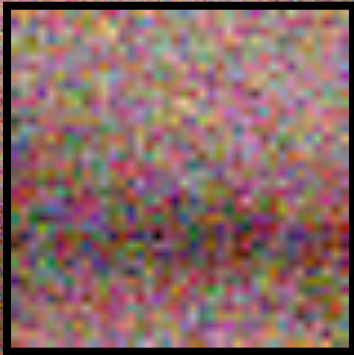
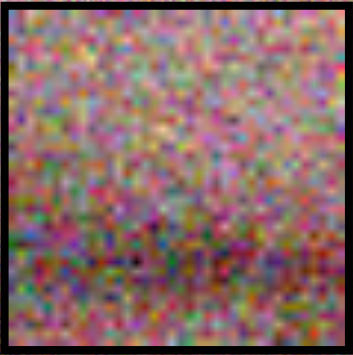
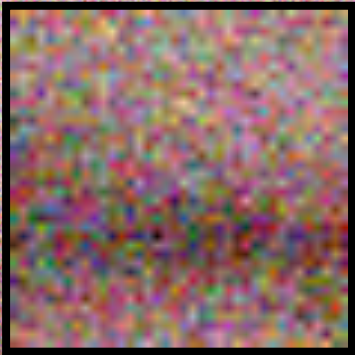
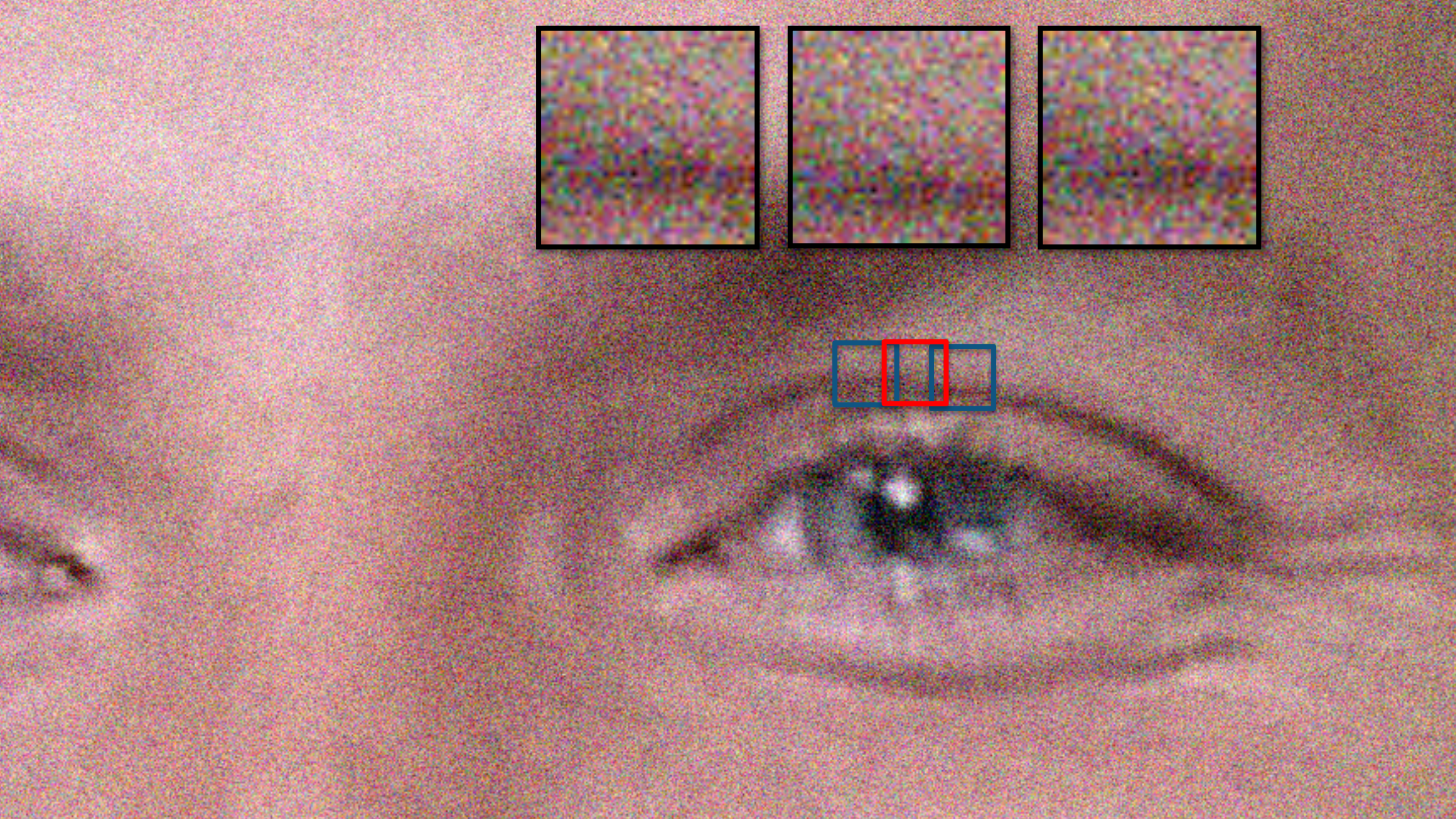


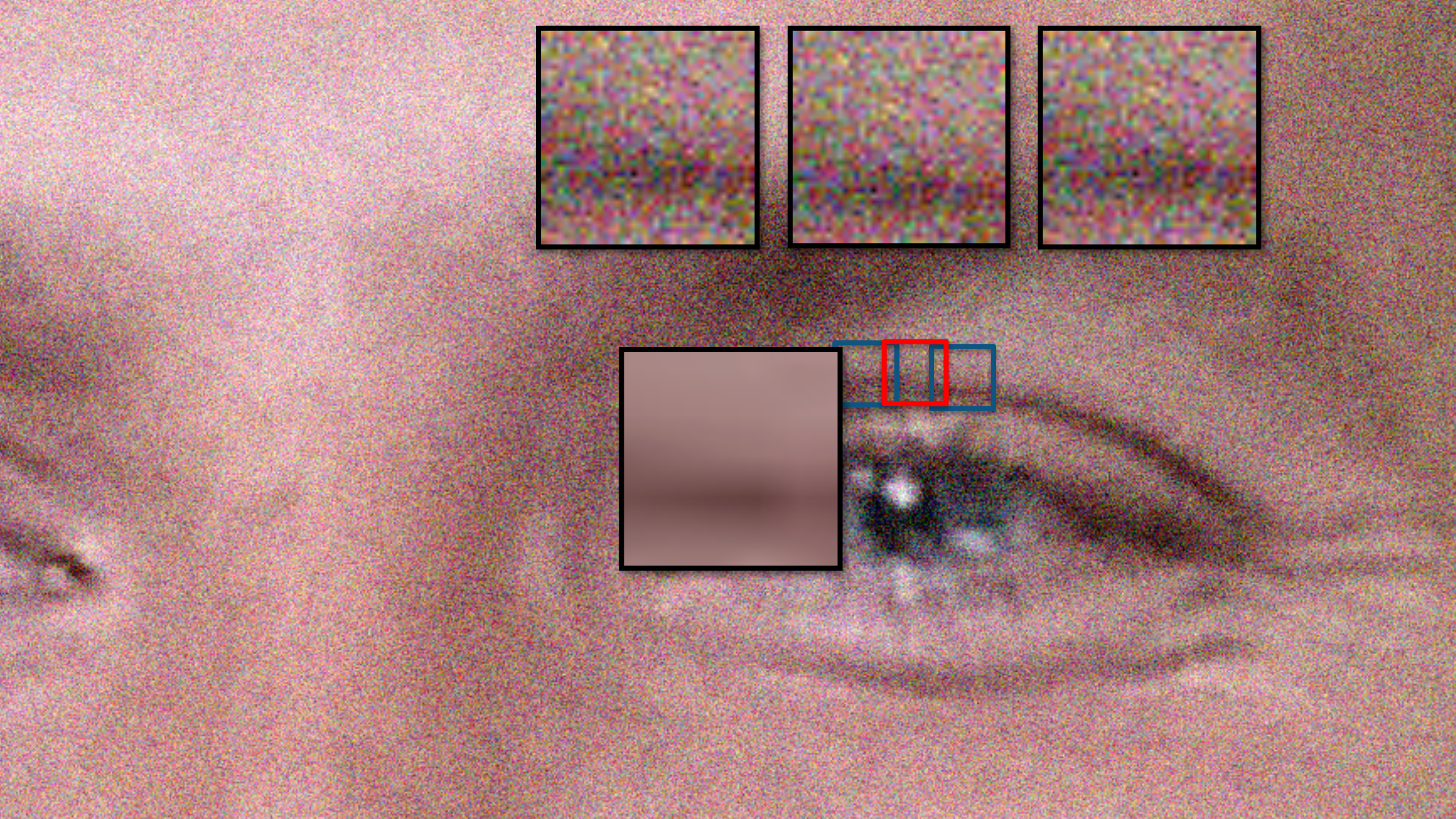
nVIDIA®

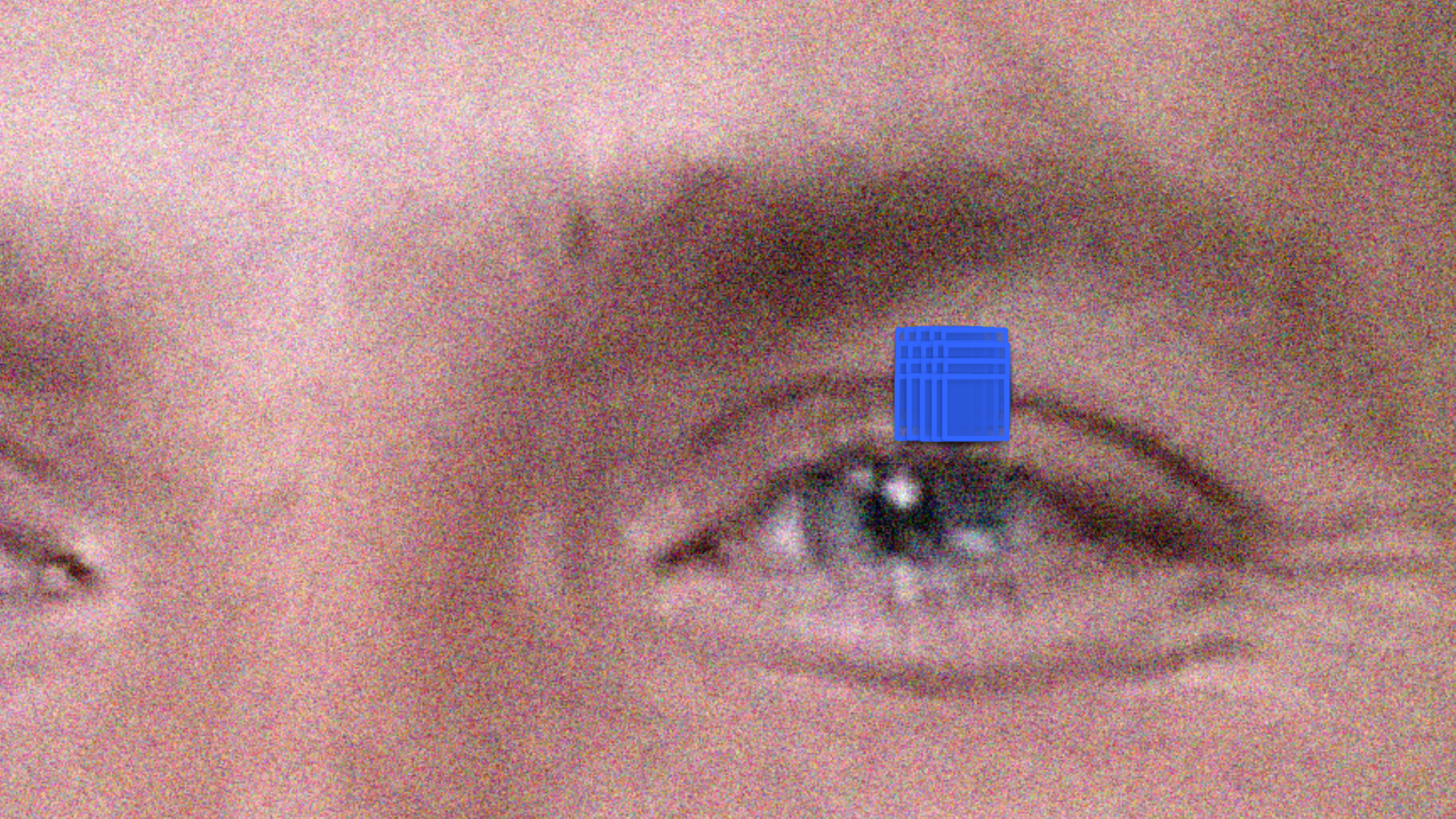
FASTANN FOR HIGH QUALITY COLLABORATIVE FILTERING
Yun-Ta Tsai, Markus Steinberger, Dawid Pająk, Kari Pulli













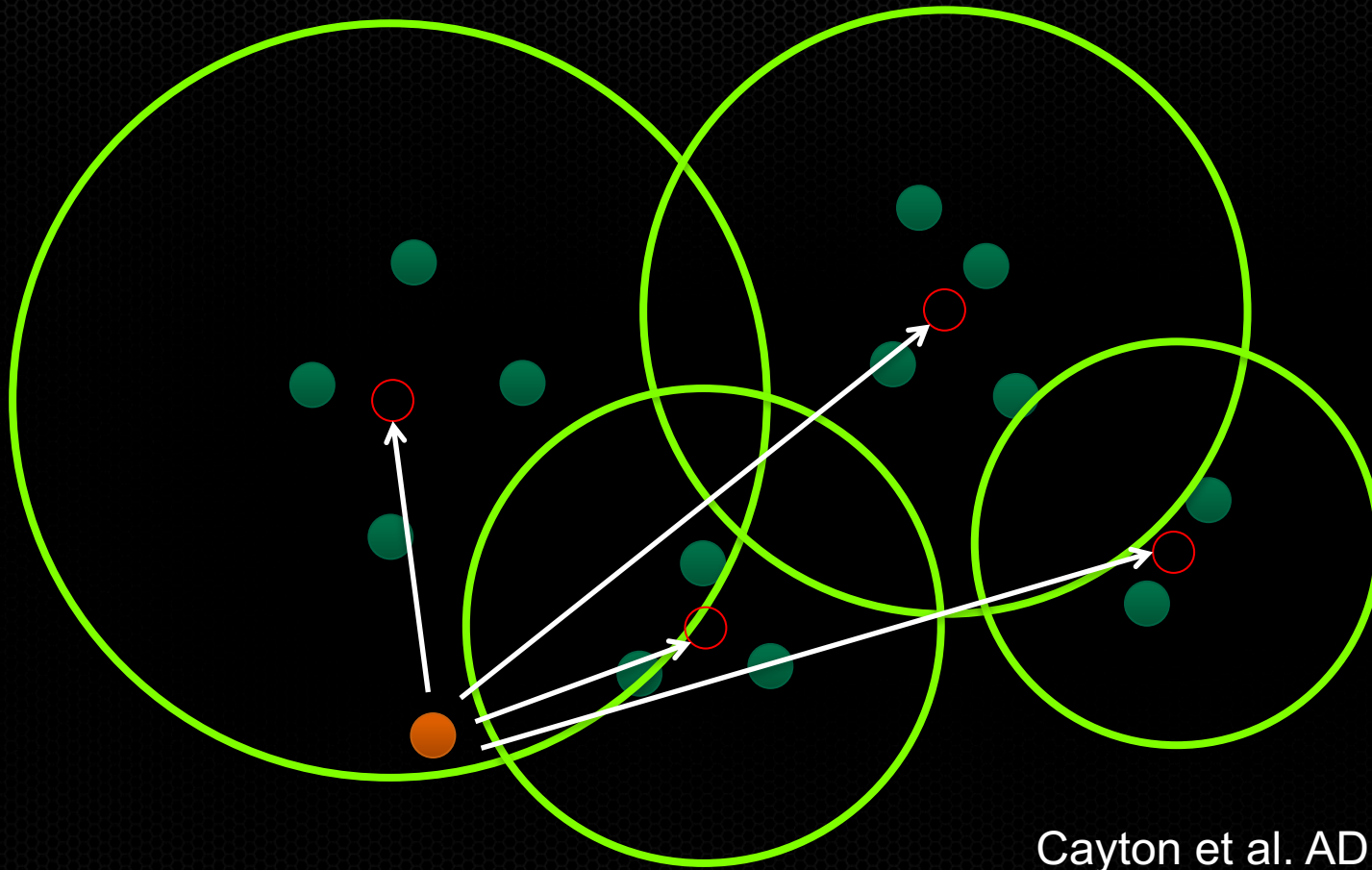


Related Work

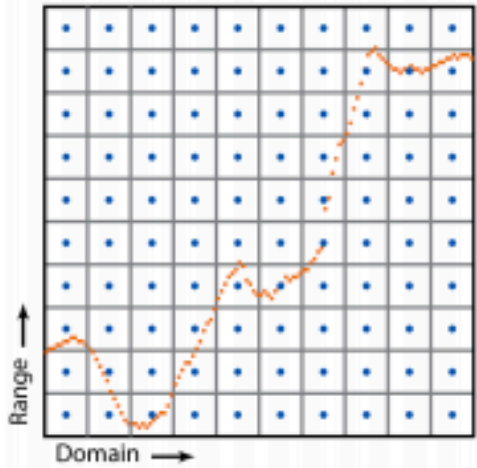
Distance Table (sorted)

0.13	0.48	0.98	1.33	1.43	2.33
0.22	0.45	0.48	2.02	1.75	0.08
0.21	0.32	0.92	3.18	0.33	0.26

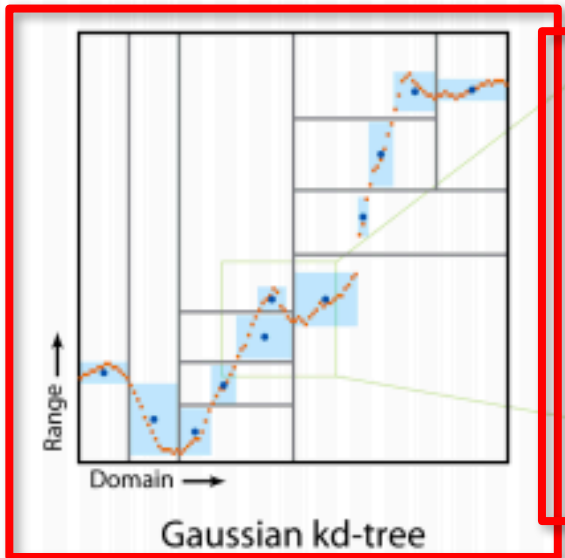
Garcia et al. ICIP 2010



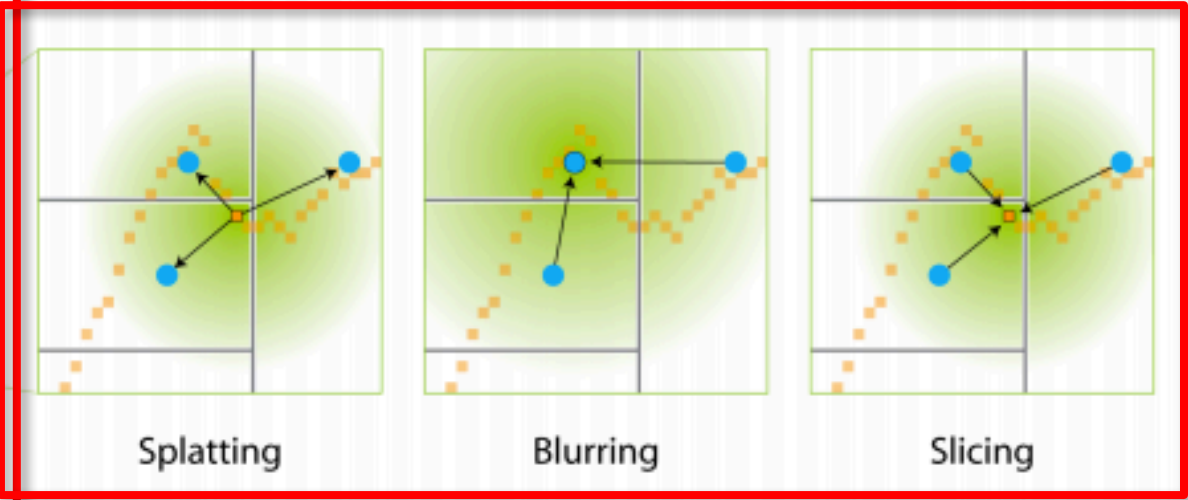
Cayton et al. ADMS 2010



Bilateral grid



Gaussian kd-tree



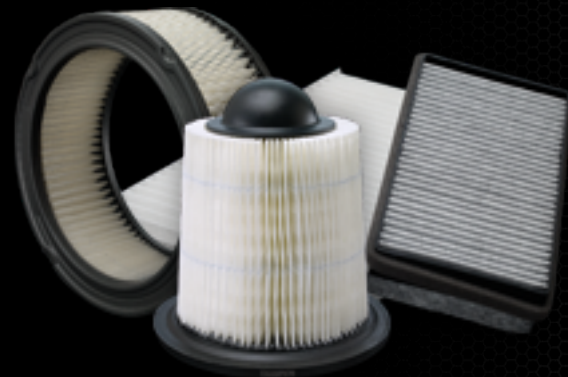
Splatting

Blurring

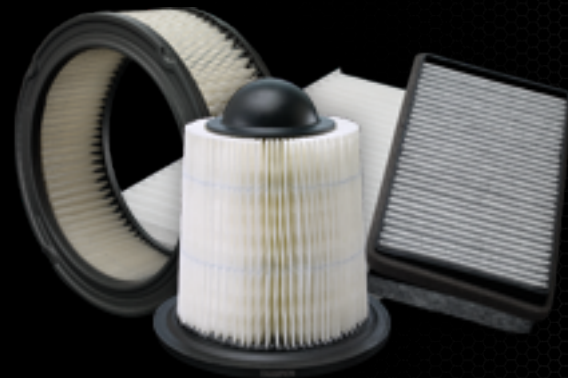
Slicing

Adams et al. SIGGRAPH 2009

Limitation

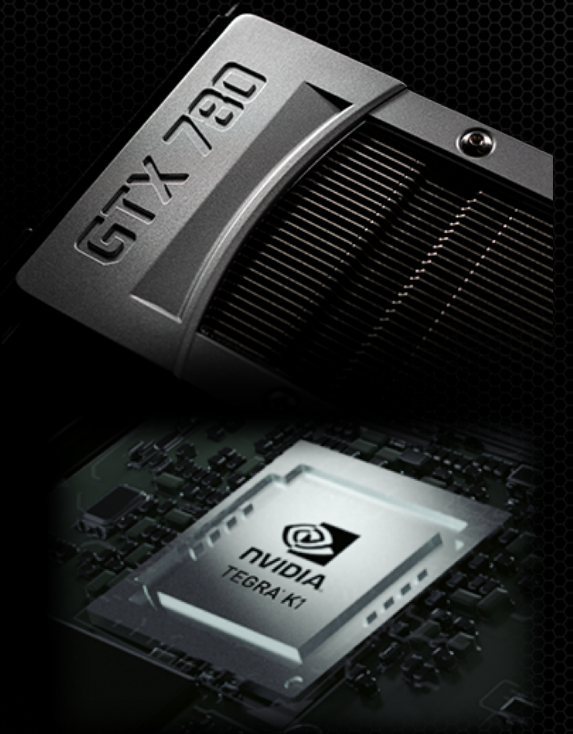
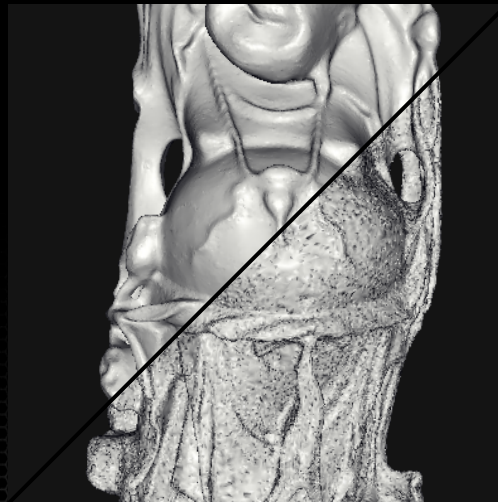


Our solution

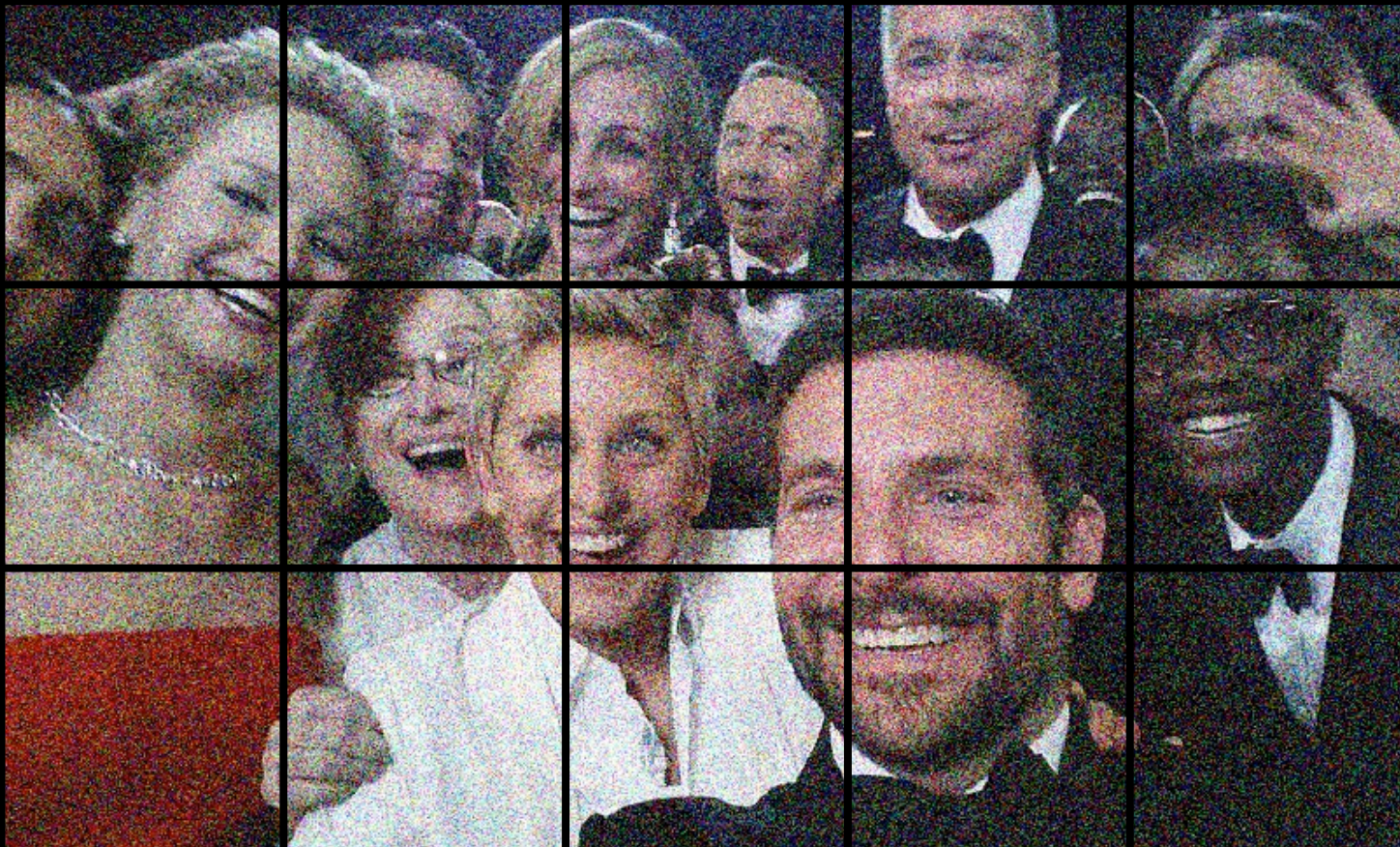


Our solution

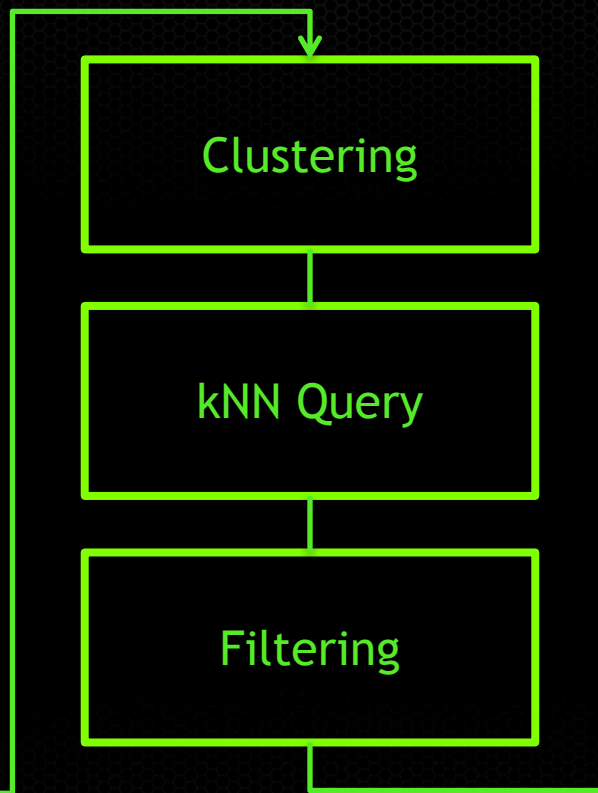
- Efficient implementation on GPU
- General solution for different filters
- High image quality
- Applicable to different applications



Our solution



Our solution

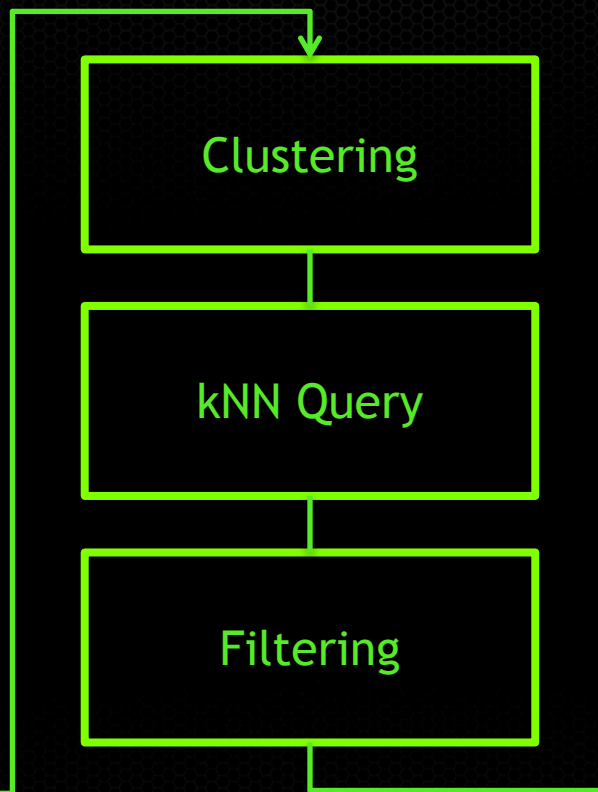


Design challenges

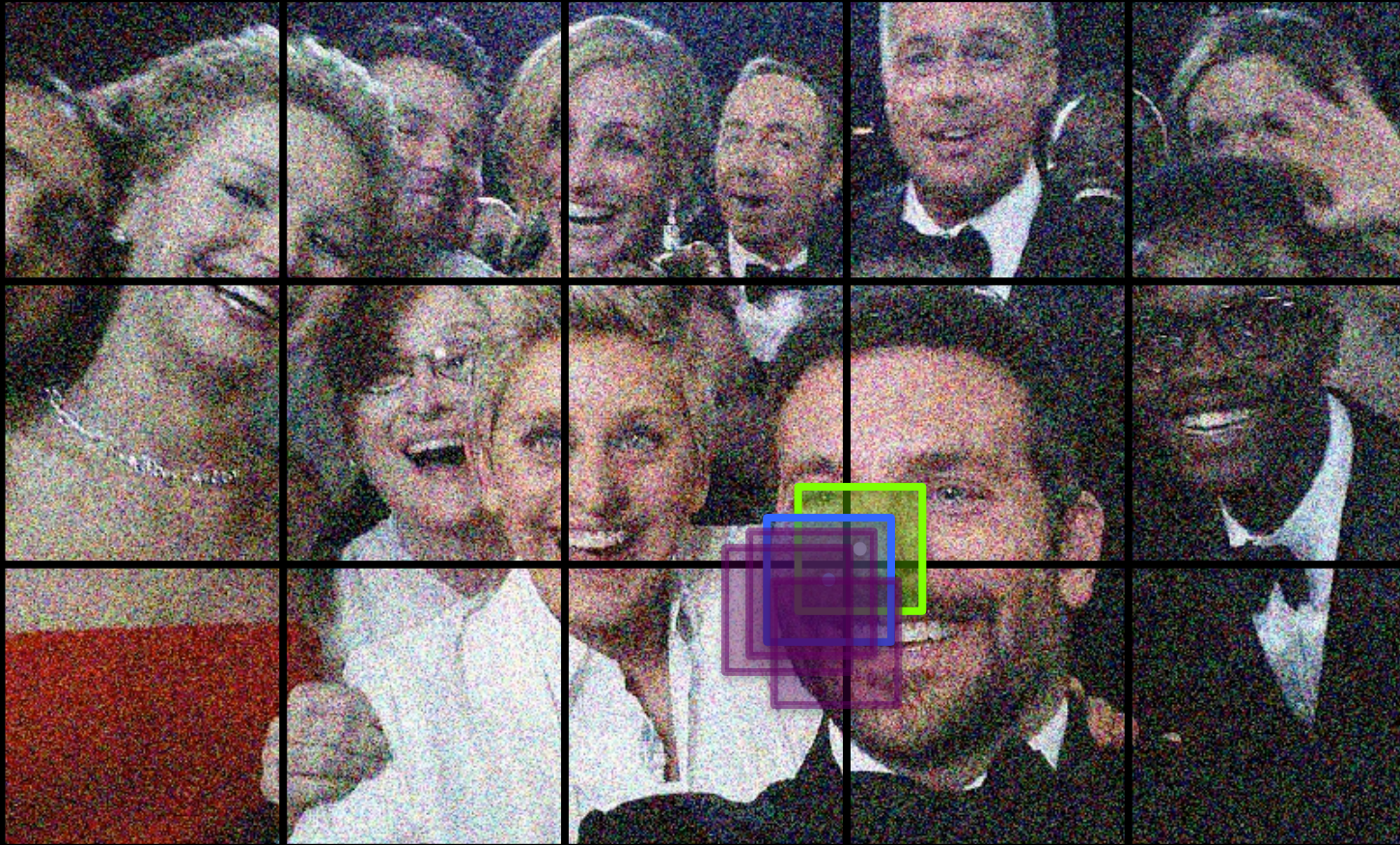
- Register pressure
- Memory access pattern
- Thread divergence
- Kernel launch overhead
- Memory footprint



Our solution



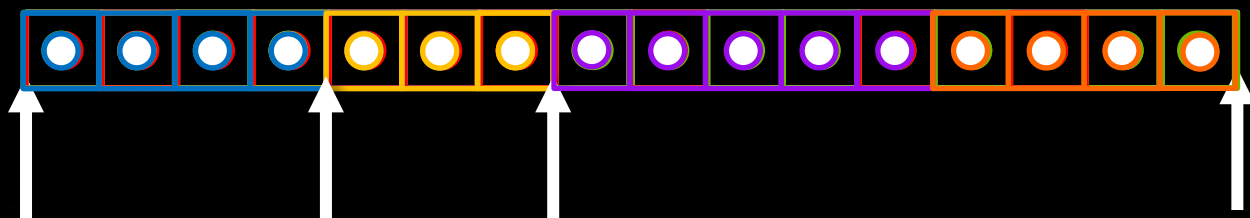
Tiling



Clustering



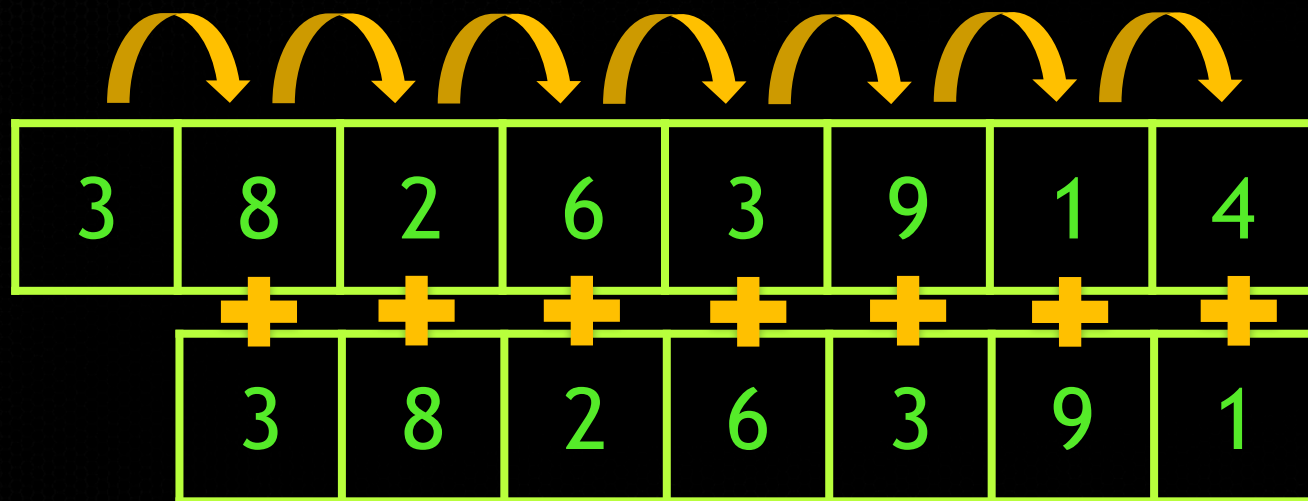
Clustering



Warp-wide operation

3	8	2	6	3	9	1	4
---	---	---	---	---	---	---	---

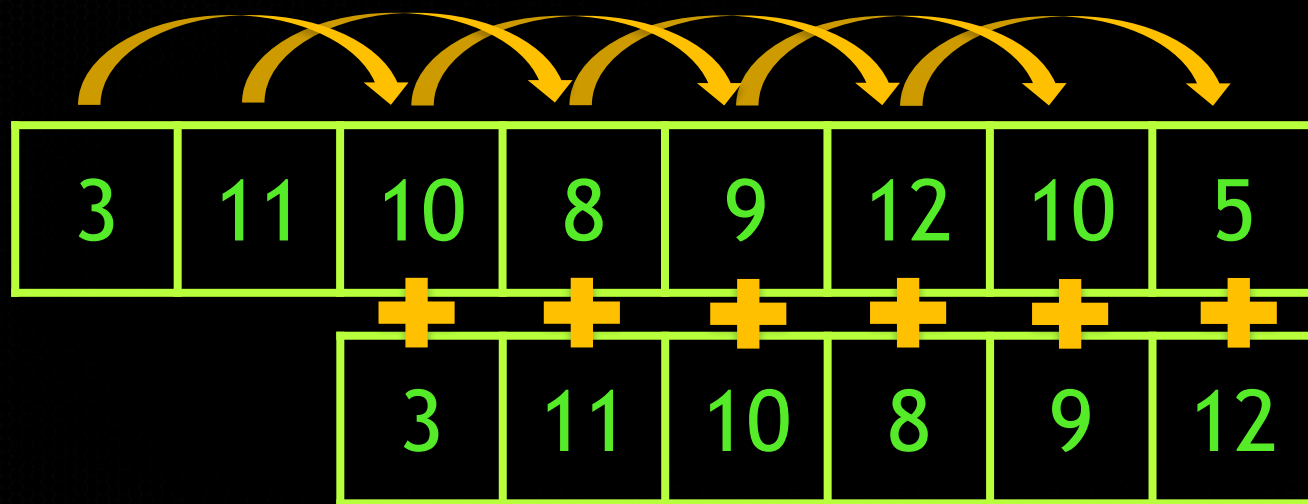
Warp-wide operation



Warp-wide operation

3	11	10	8	9	12	10	5
---	----	----	---	---	----	----	---

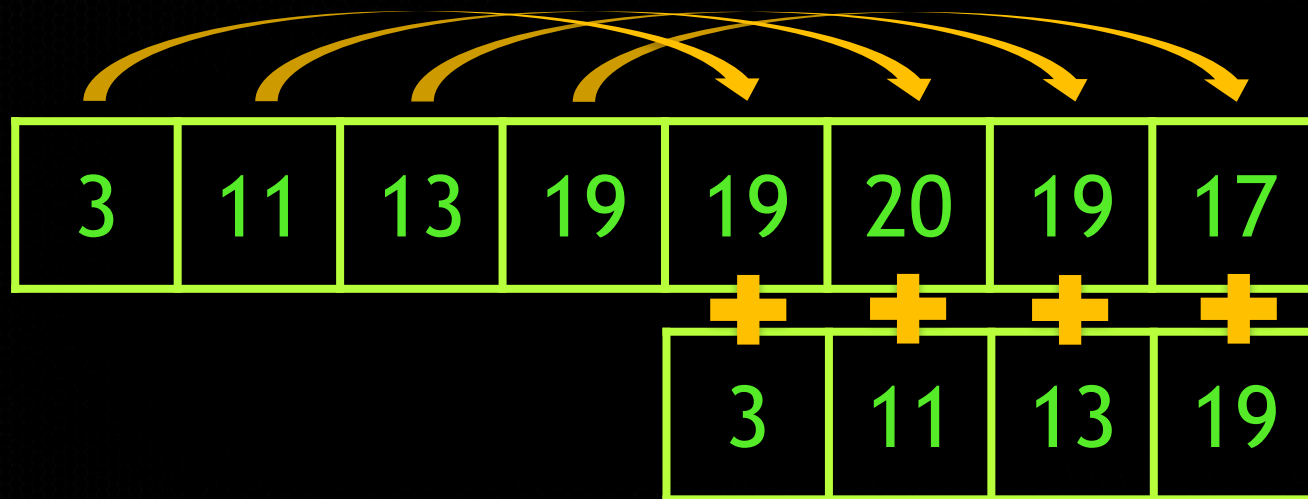
Warp-wide operation



Warp-wide operation

3	11	13	19	19	20	19	17
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Warp-wide operation

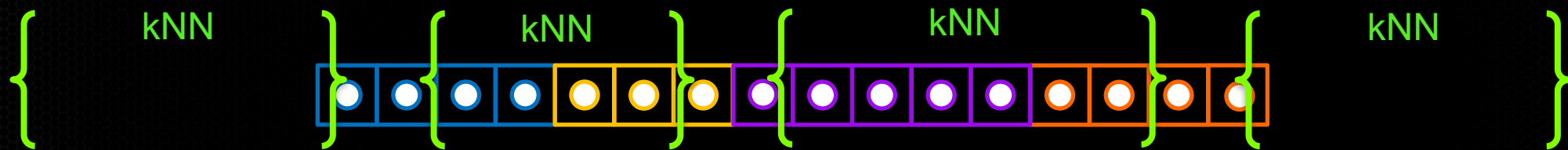


Warp-wide operation

3	11	13	19	22	31	32	36
---	----	----	----	----	----	----	----

- Reduce **register usage**
- Better **parallelism**
- Minimize thread and warp **divergence**

Clustering



Our solution



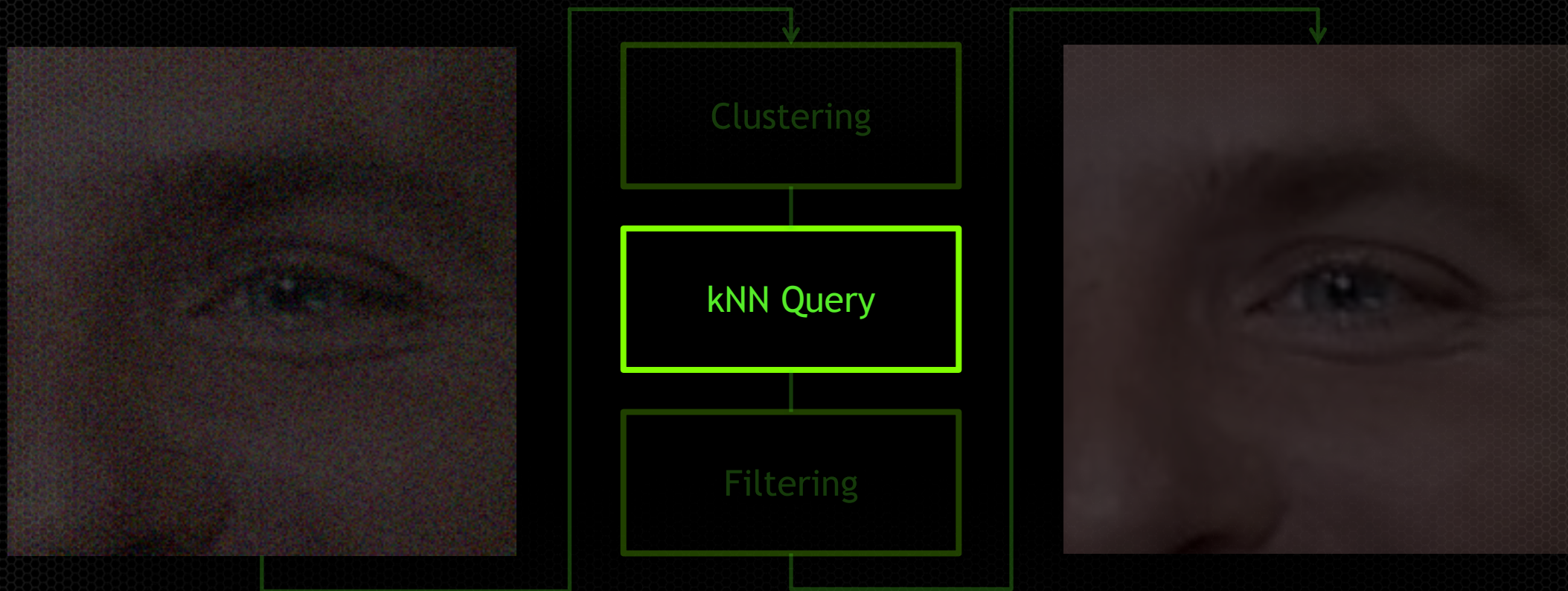
Clustering

kNN Query

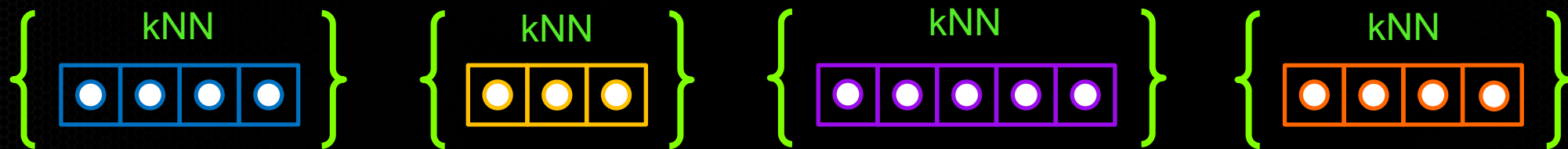
Filtering



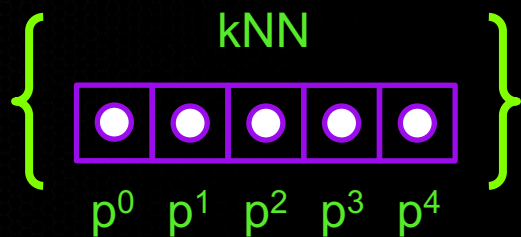
Our solution



kNN Query

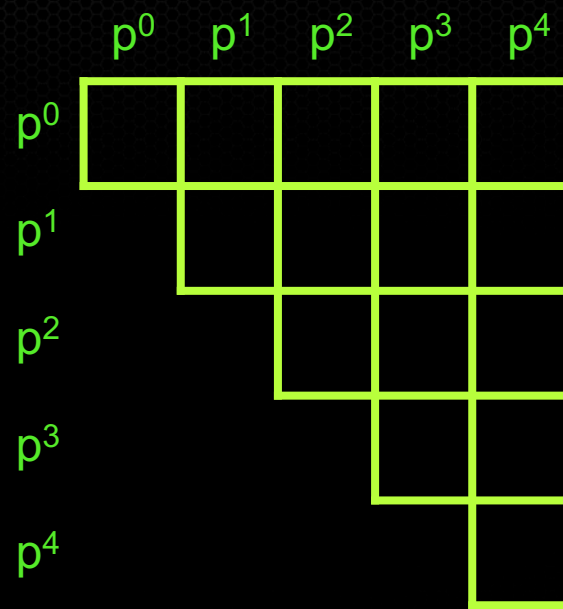
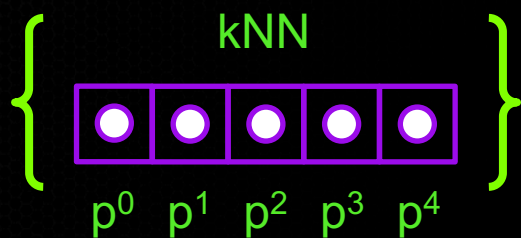


kNN Query



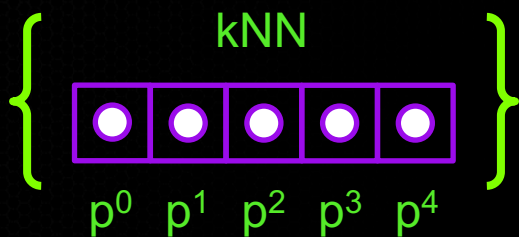
	p^0	p^1	p^2	p^3	p^4
p^0					
p^1					
p^2					
p^3					
p^4					

kNN Query



kNN Query

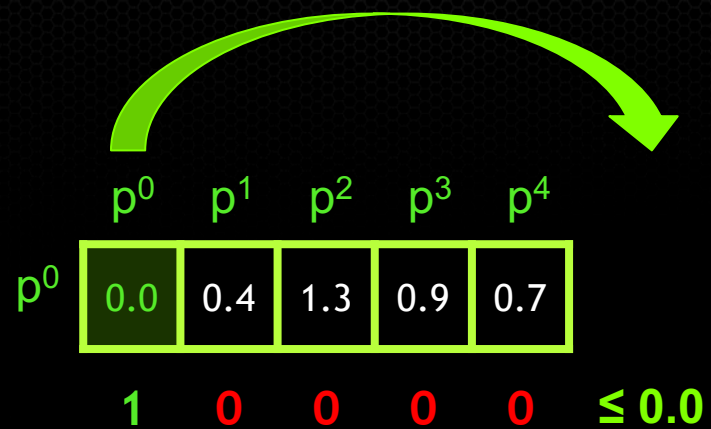
	p^0	p^1	p^2	p^3	p^4
p^0	0.0	0.4	1.3	0.9	0.7



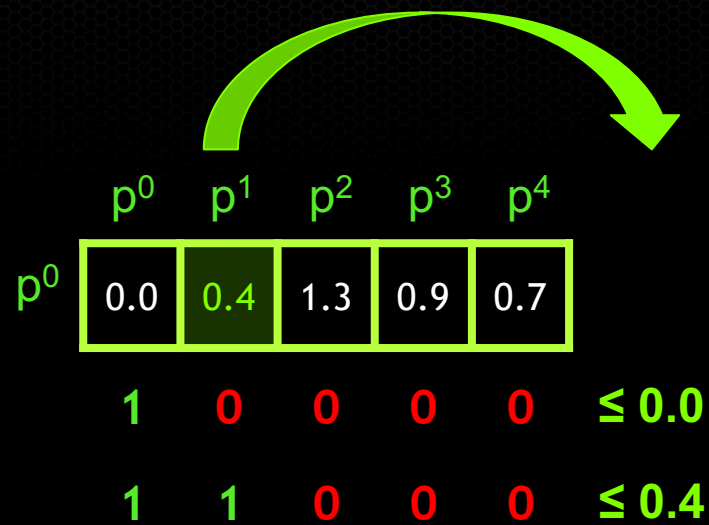
kNN Query

	p^0	p^1	p^2	p^3	p^4	
p^0	0.0	0.4	1.3	0.9	0.7	
	1	1	0	0	1	≤ 0.8

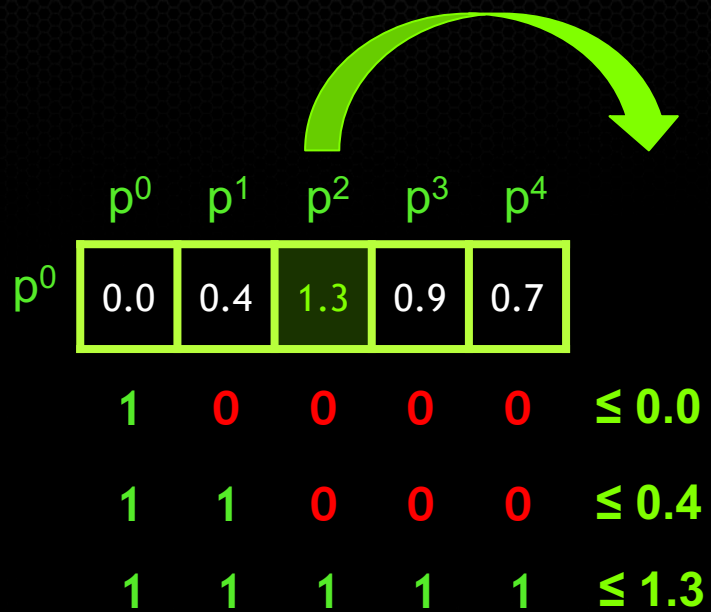
kNN Query



kNN Query



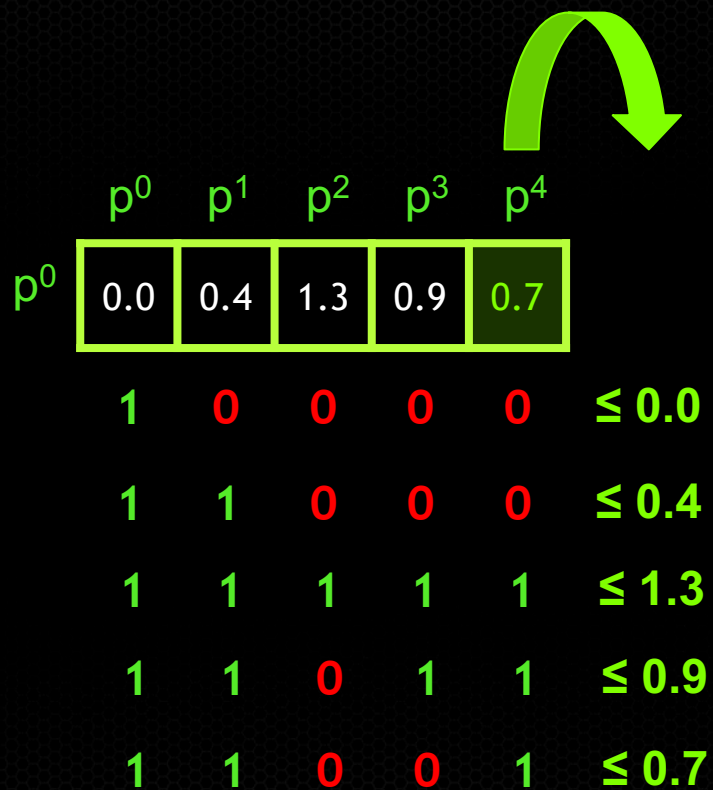
kNN Query



kNN Query



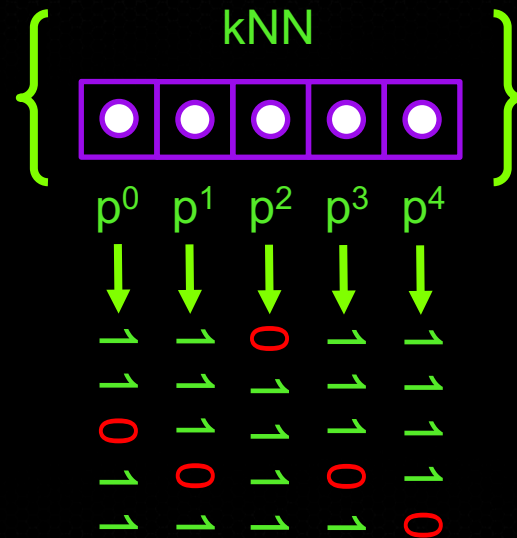
kNN Query



kNN Query

	p^0	p^1	p^2	p^3	p^4	
p^0	0.0	0.4	1.3	0.9	0.7	
	1	0	0	0	0	≤ 0.0
	1	1	0	0	0	≤ 0.4
	1	1	1	1	1	≤ 1.3
	1	1	0	1	1	≤ 0.9
	1	1	0	0	1	≤ 0.7

kNN Query

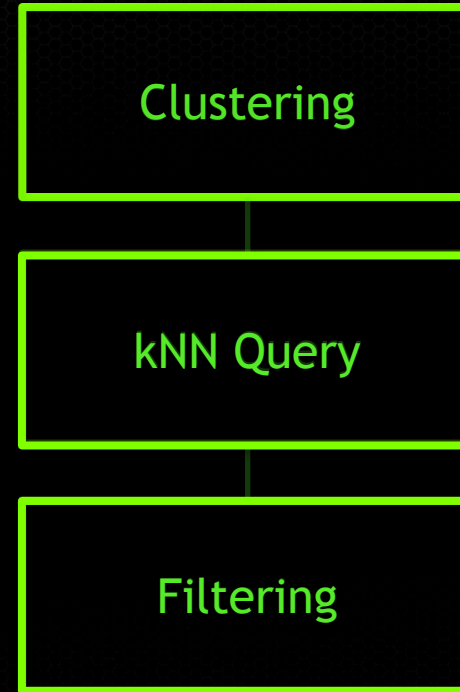


Filtering



Our solution

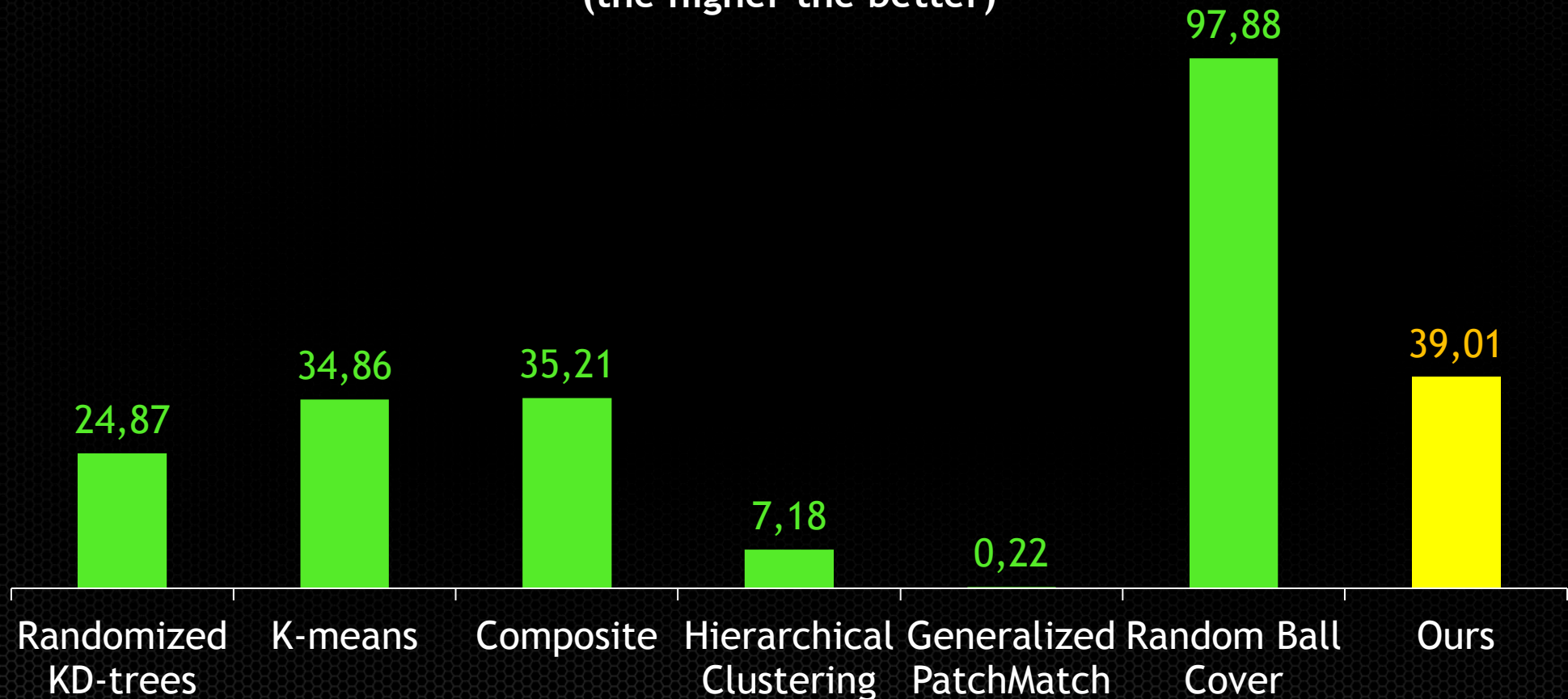
- Hierarchical 2-mean clustering
- Warp-wide operators
- kNN search
- Distance table
- Voting
- Binary coding
- Filtering and aggregation



Results

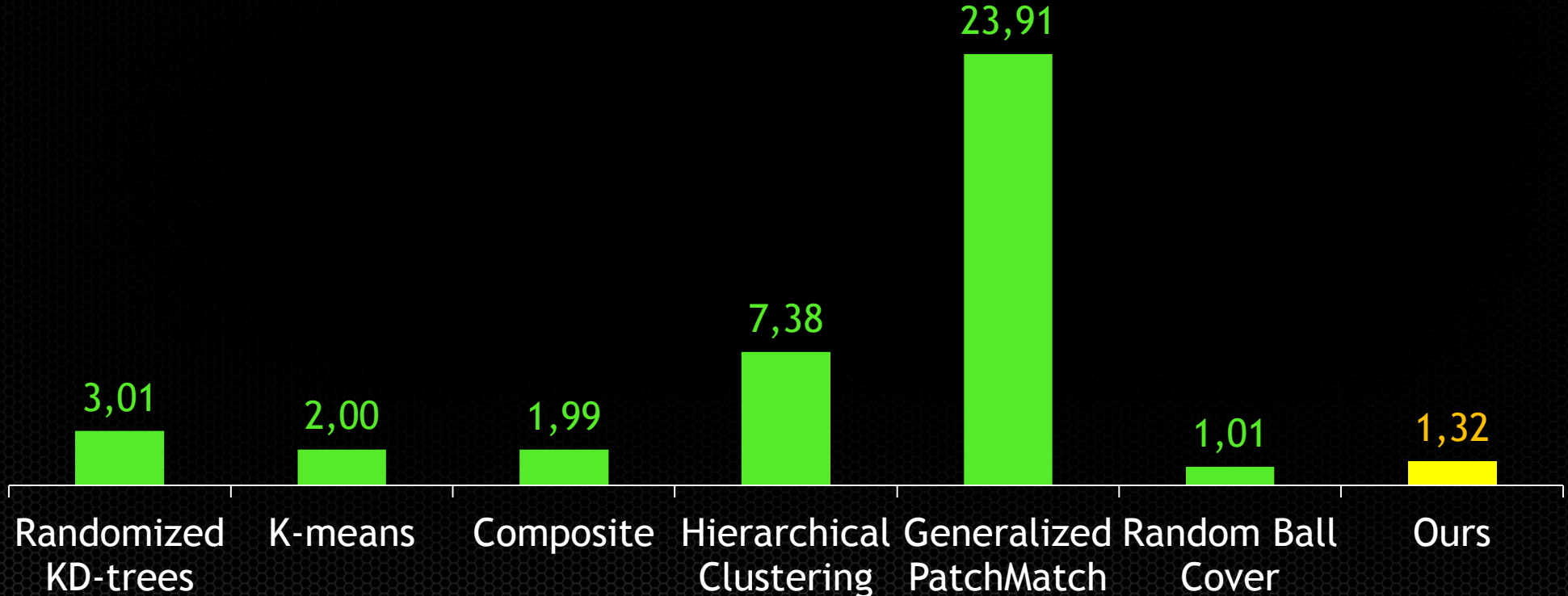
NN quality

% of patches matching the kNN result, k=16
(the higher the better)



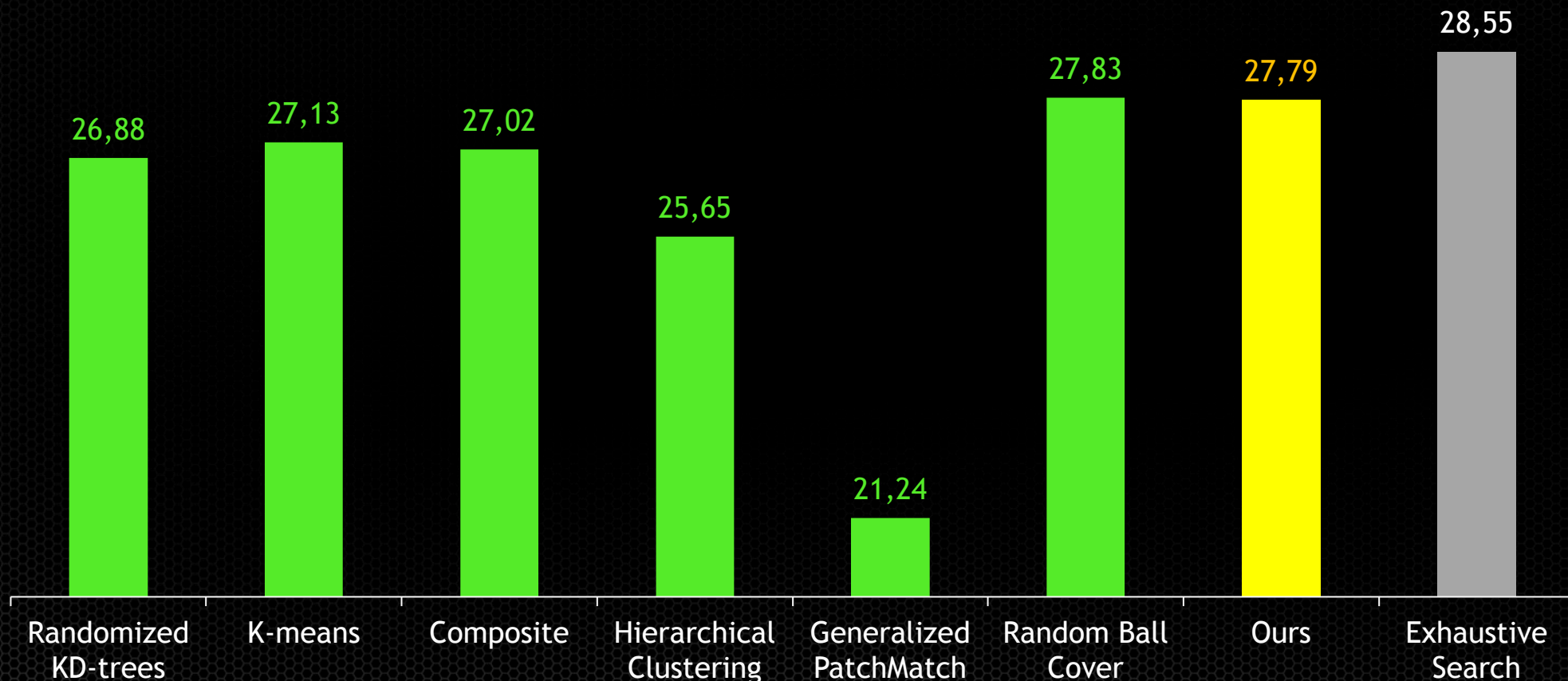
NN quality

$D_{\text{ann}}/D_{\text{knn}}$, $k=16$
(the lower the better)



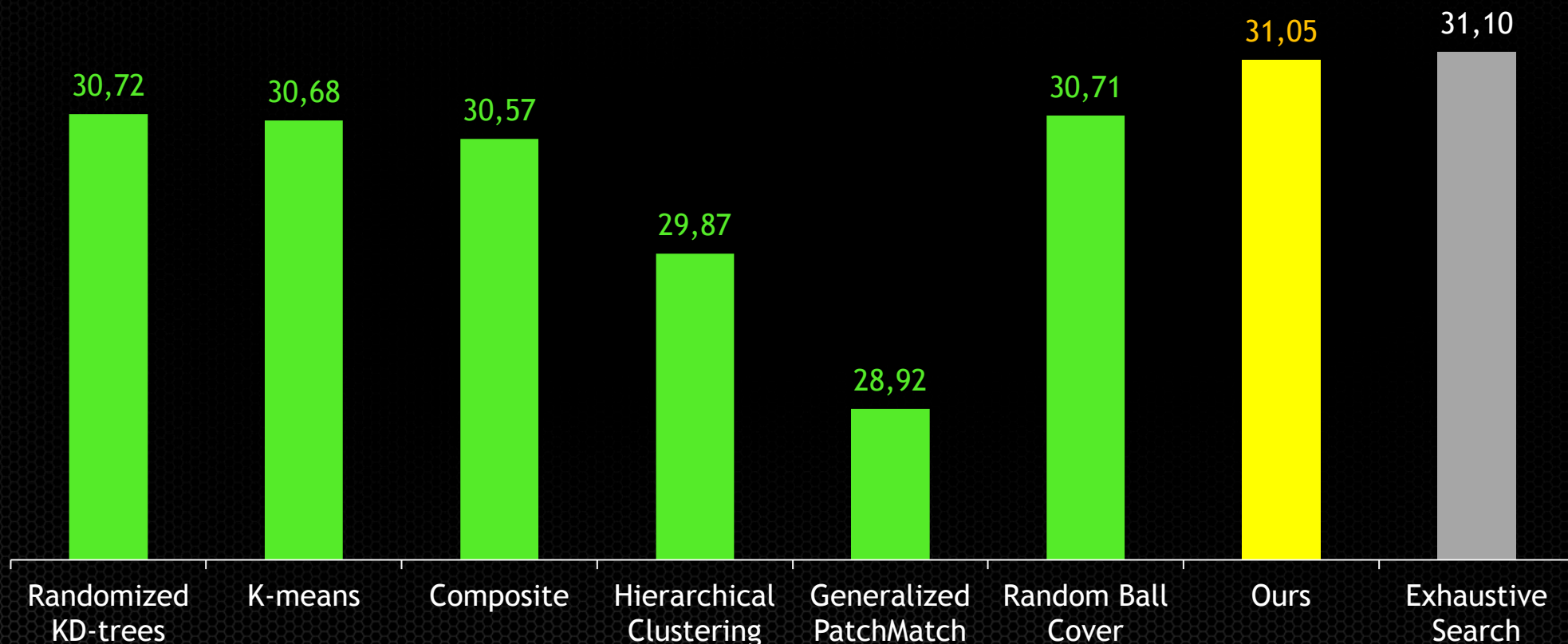
Single Frame Noise Reduction

Nonlocal Means - PSNR [dB], k=16
(the higher the better)



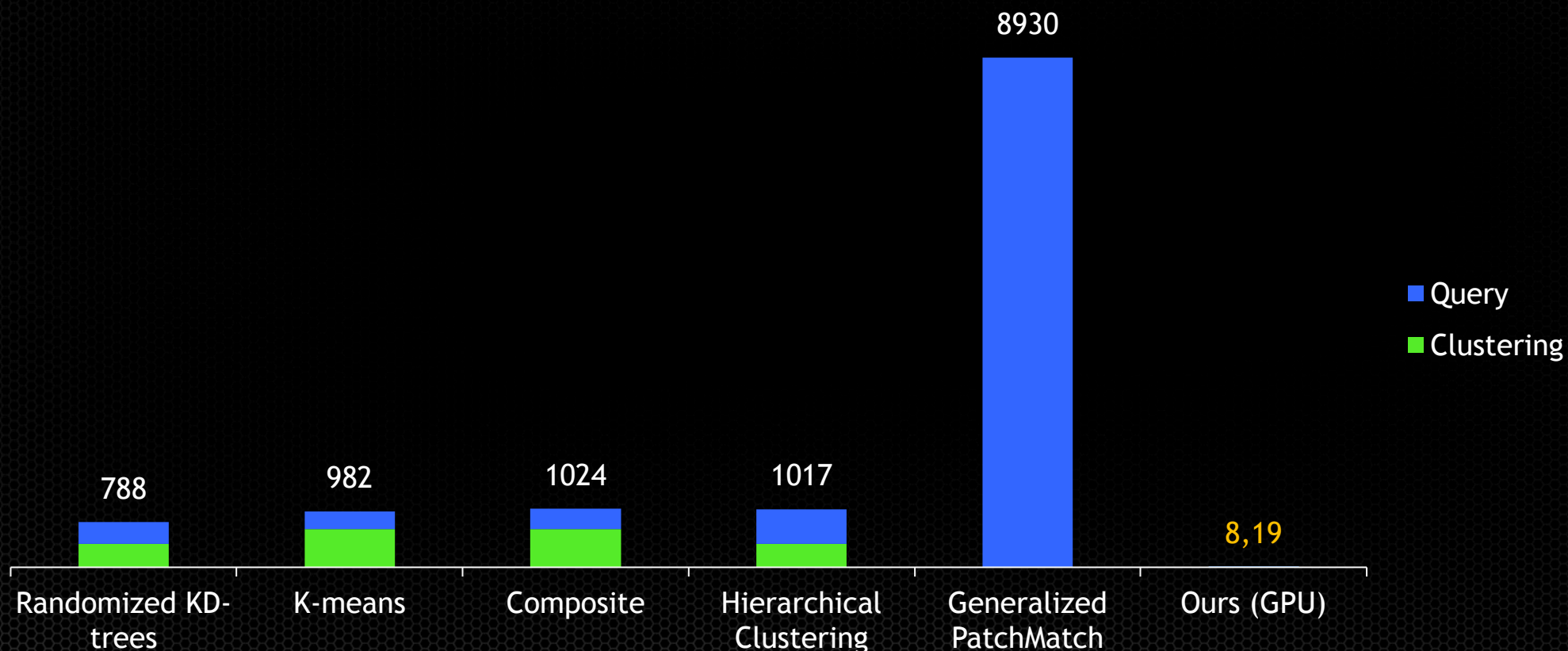
Single Frame Noise Reduction

BM3D - PSNR [dB], k=16
(the higher the better)



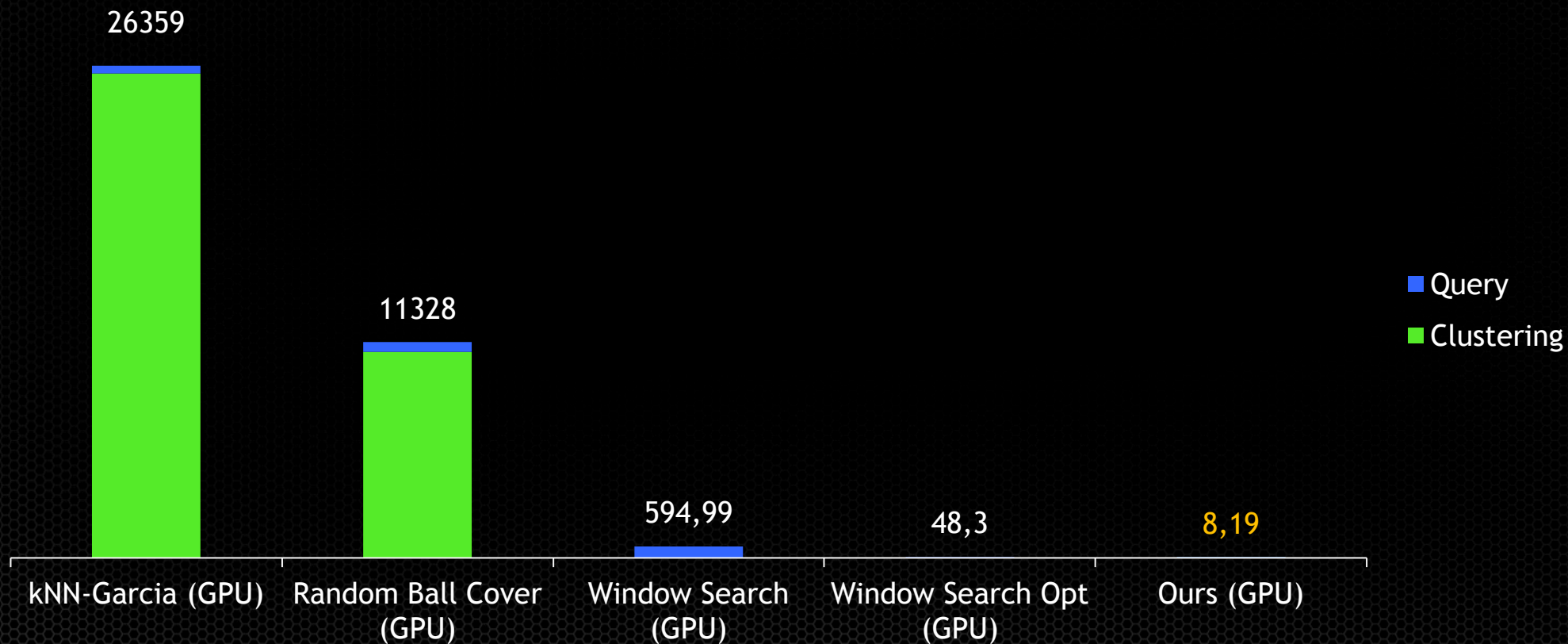
Single Frame Noise Reduction

Run-time [ms], k=16, 0.25MPix
(the lower the better)



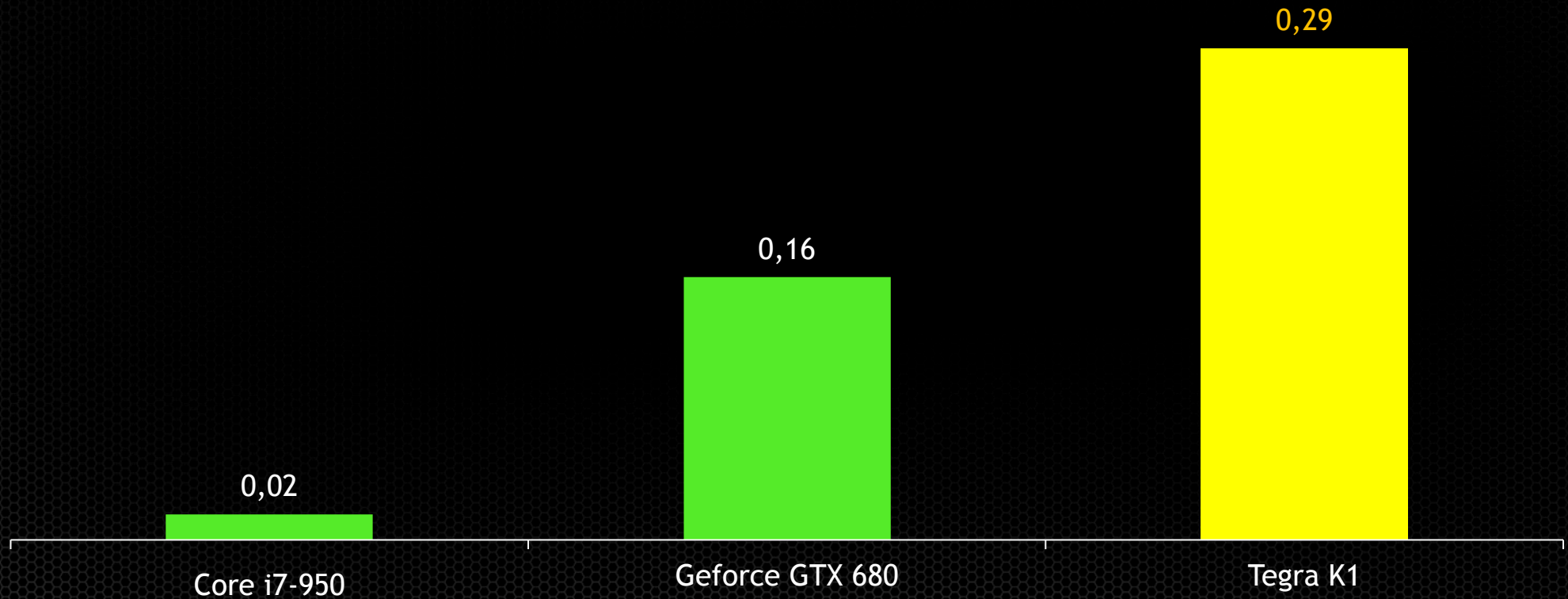
Single Frame Noise Reduction

Run-time [ms], k=16, 0.25MPix
(the lower the better)



Architectures

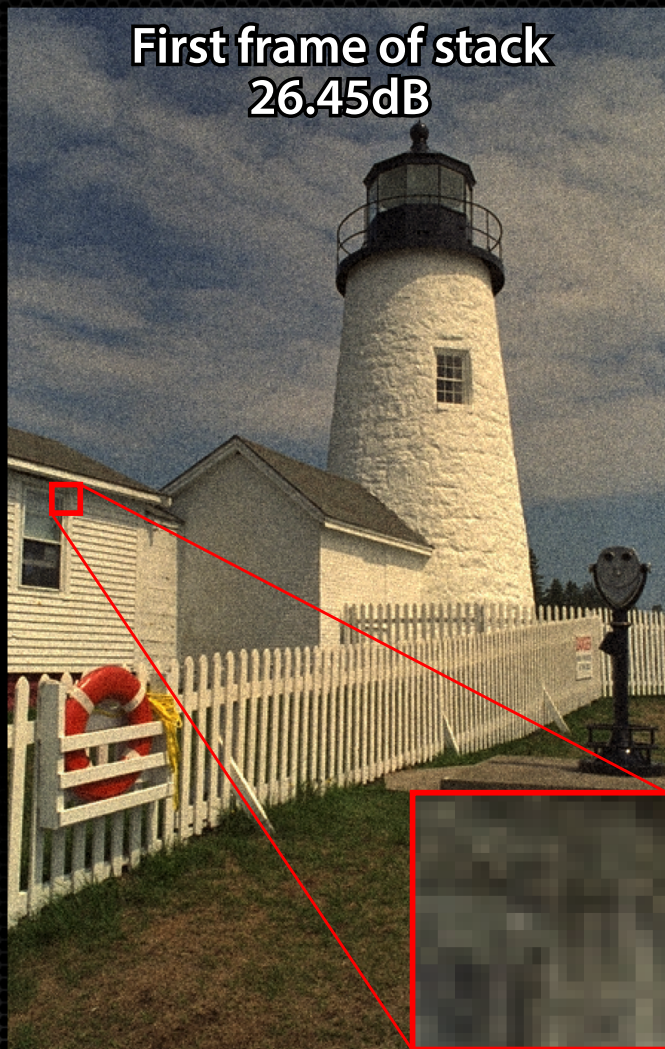
MPix/s/Watt, k=16, 0.25MPix
(the higher the better)



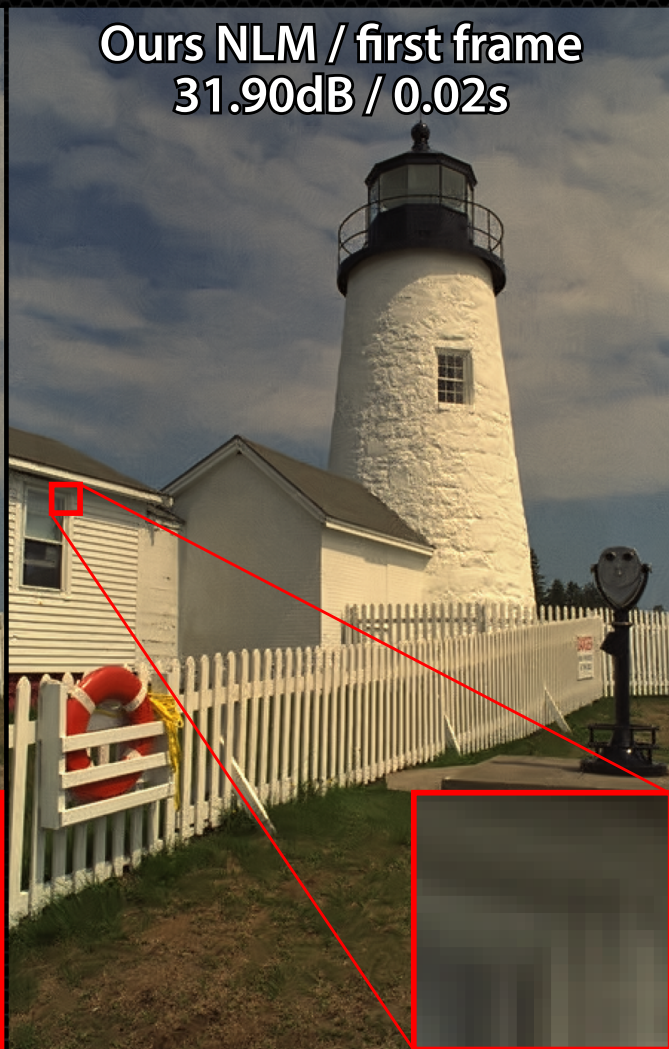
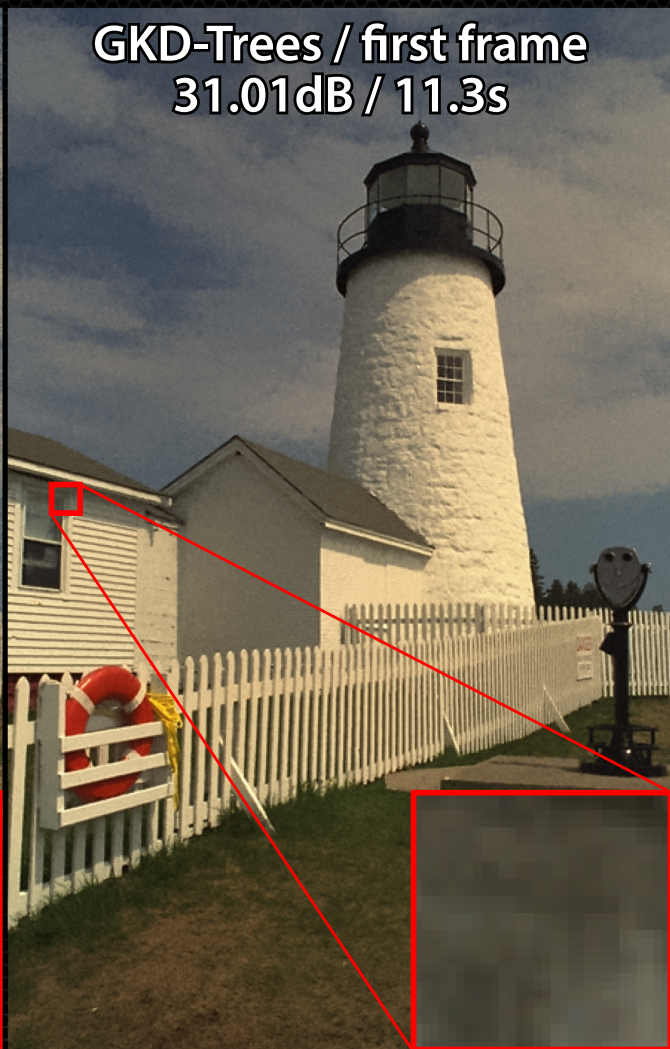
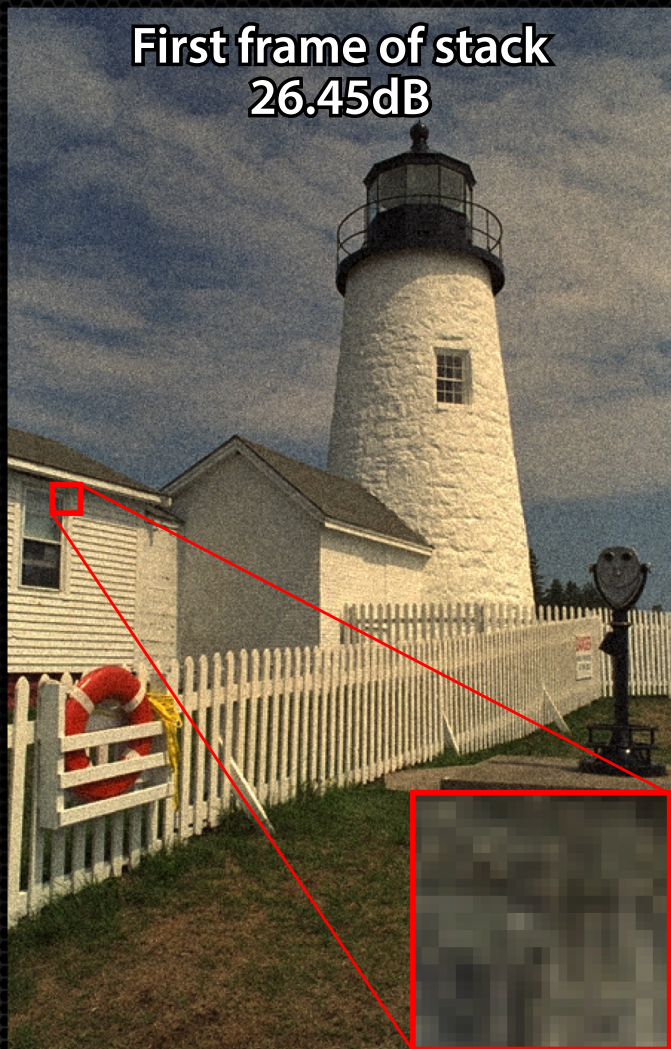
Burst Denoising - Single Frame



Burst Denoising - Single Frame



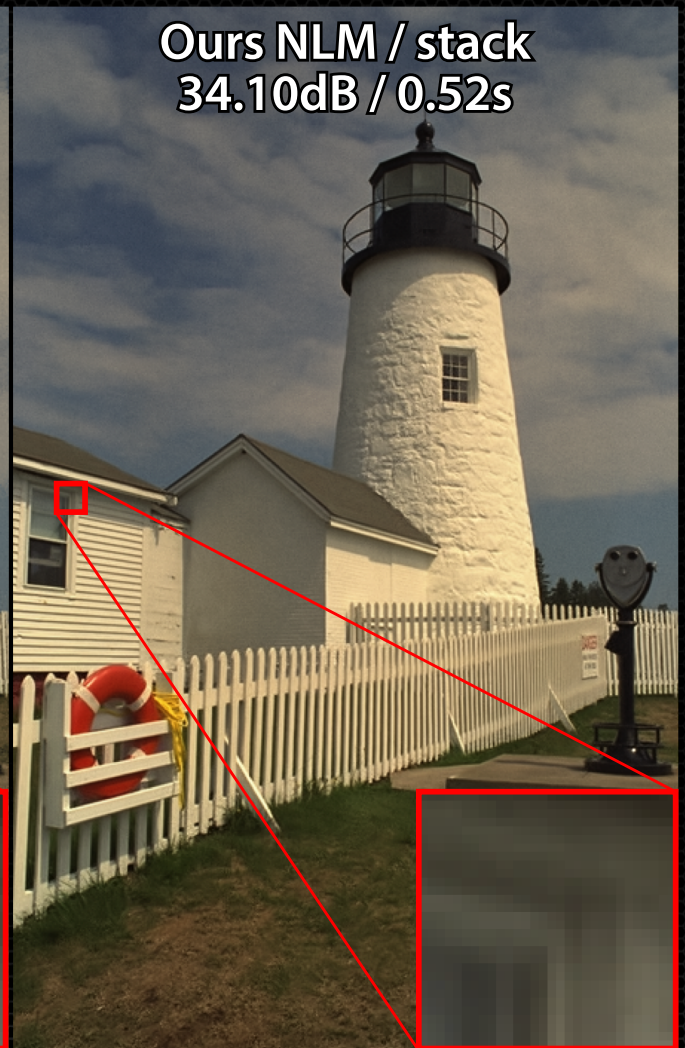
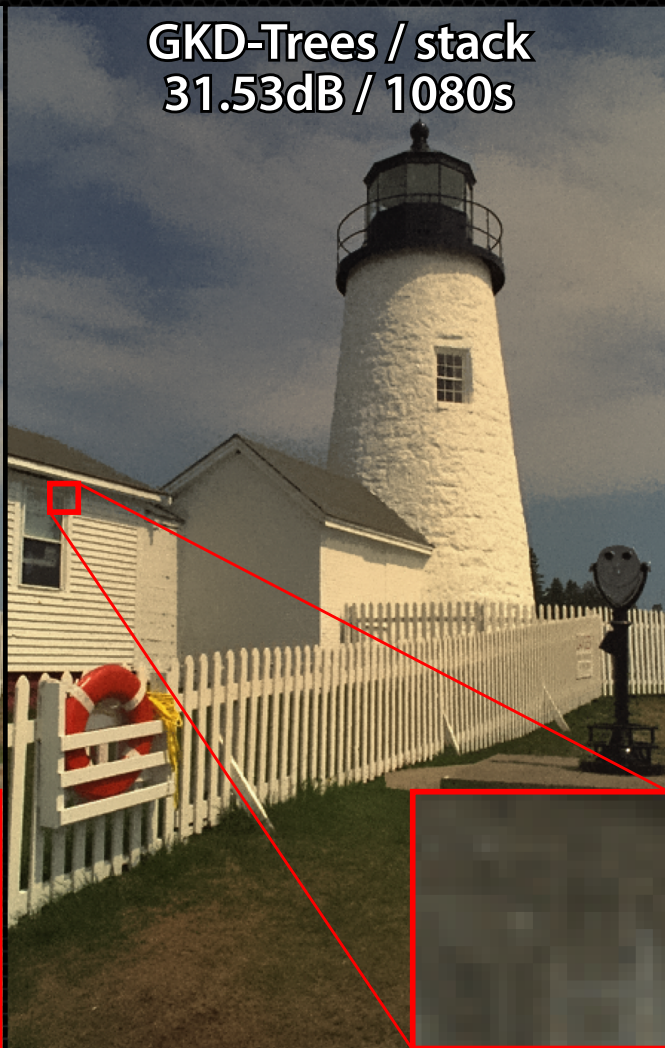
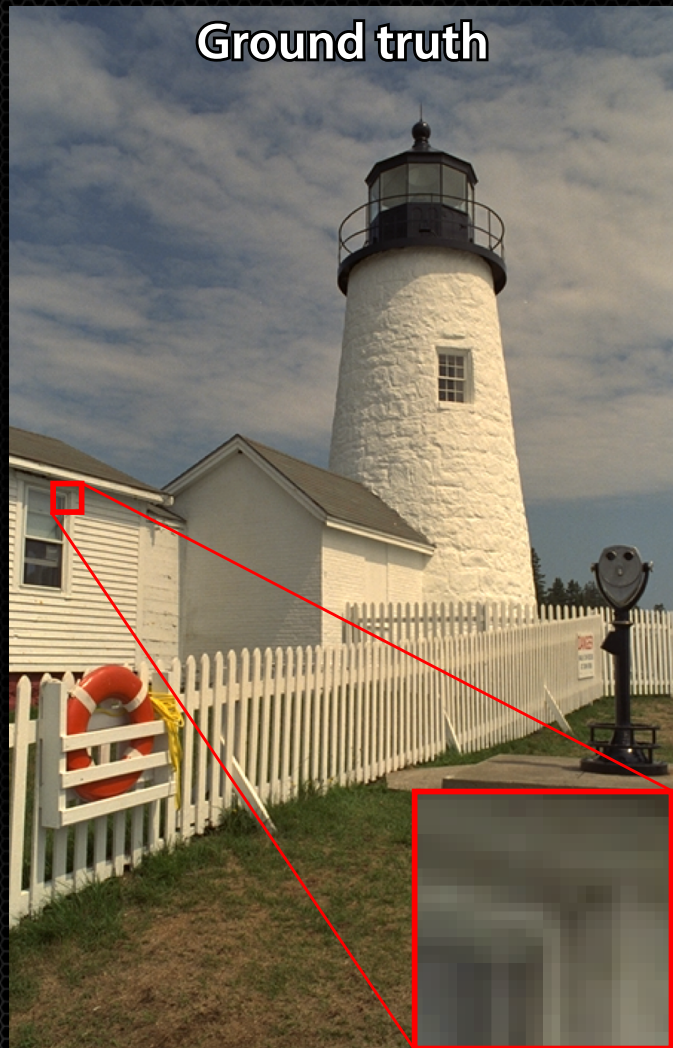
Burst Denoising - Single Frame



Burst Denoising - All Frames



Burst Denoising - All Frames



Global Illumination



Global Illumination

4spp



Ours



Global Illumination

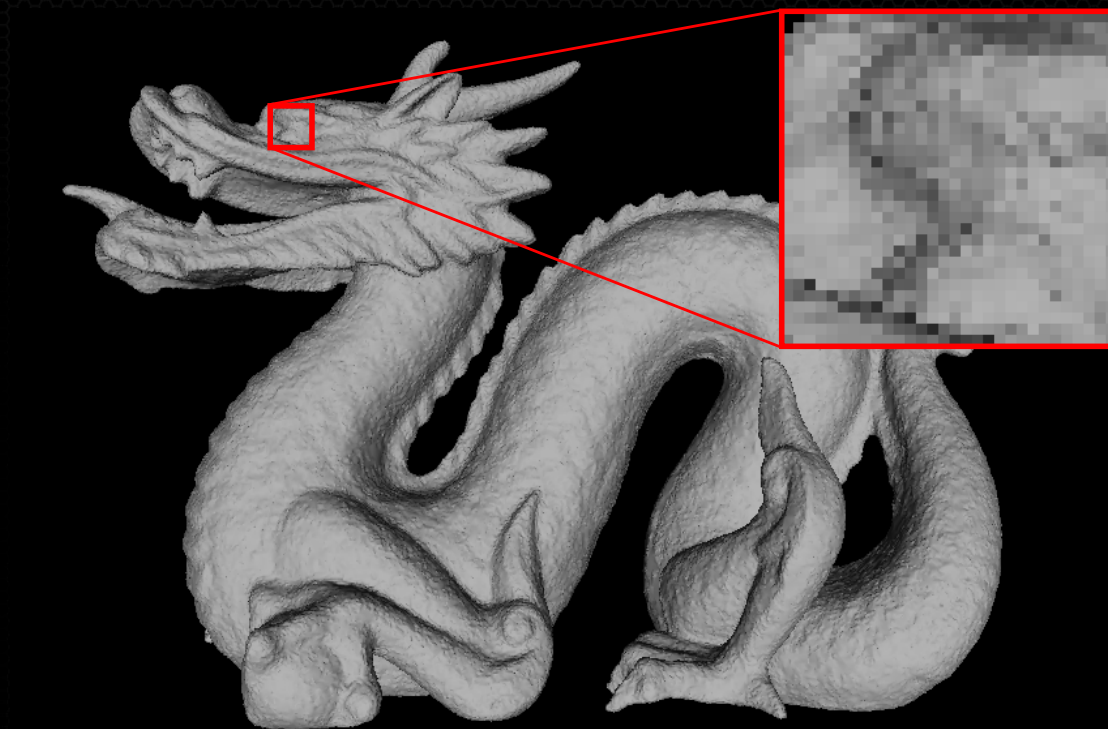
Ours

35.11dB / 2.20s

512spp

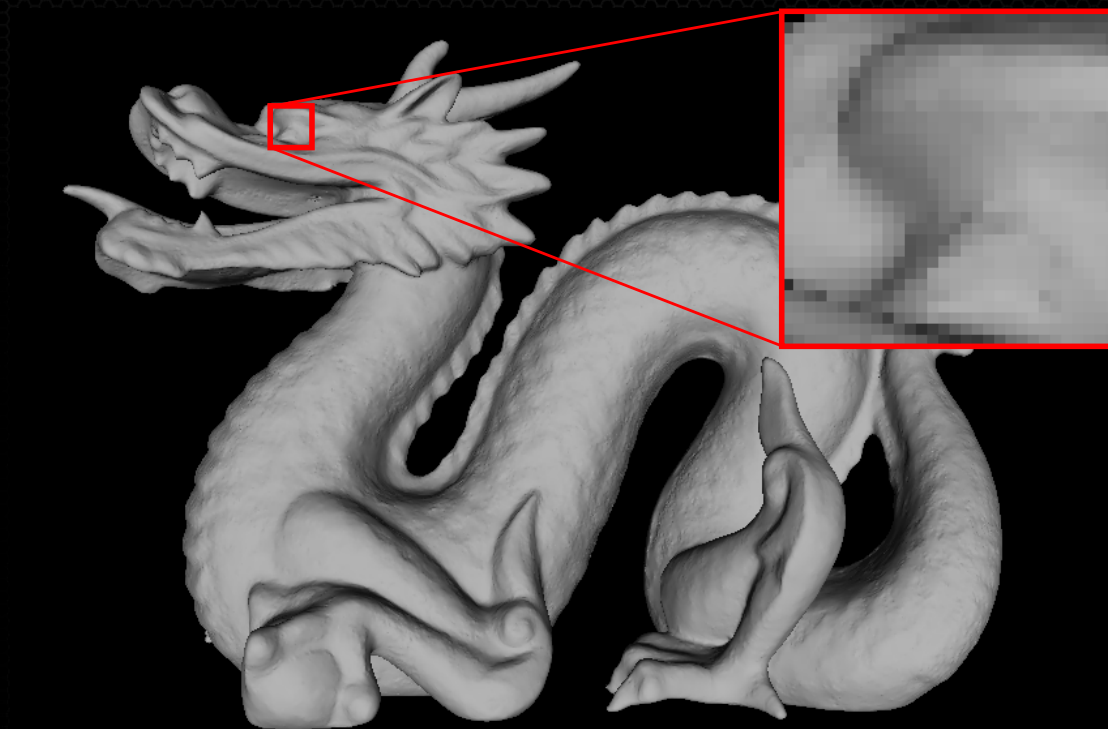
35.63dB / 243s

Geometry Noise Reduction



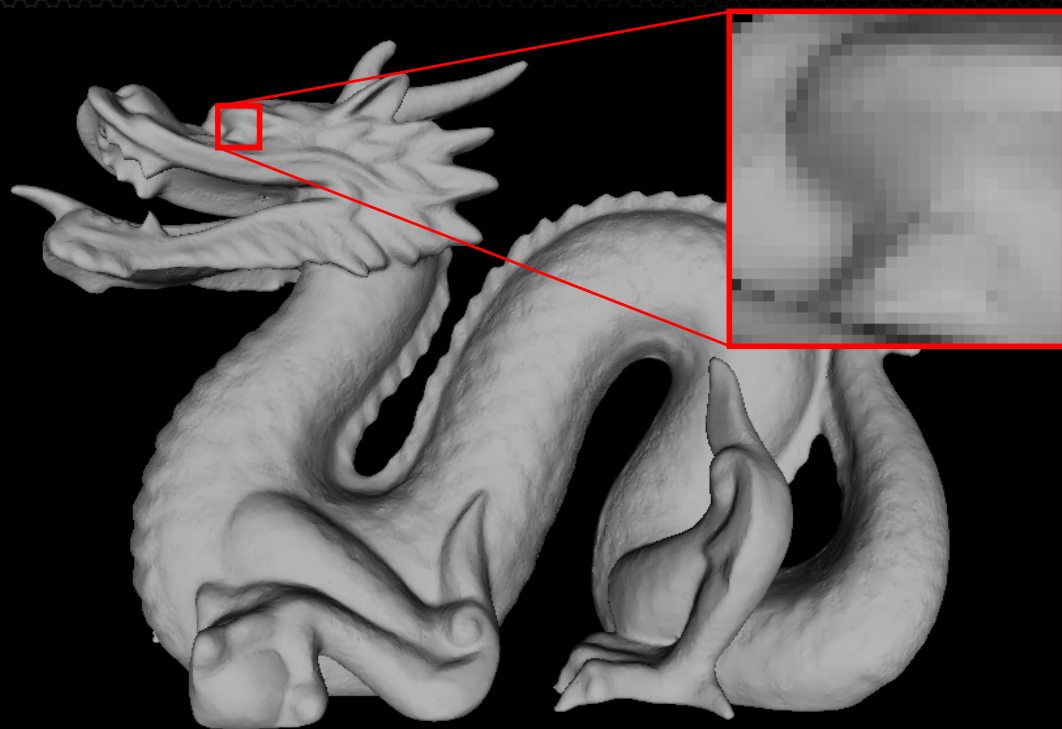
Noisy Input

Geometry Noise Reduction

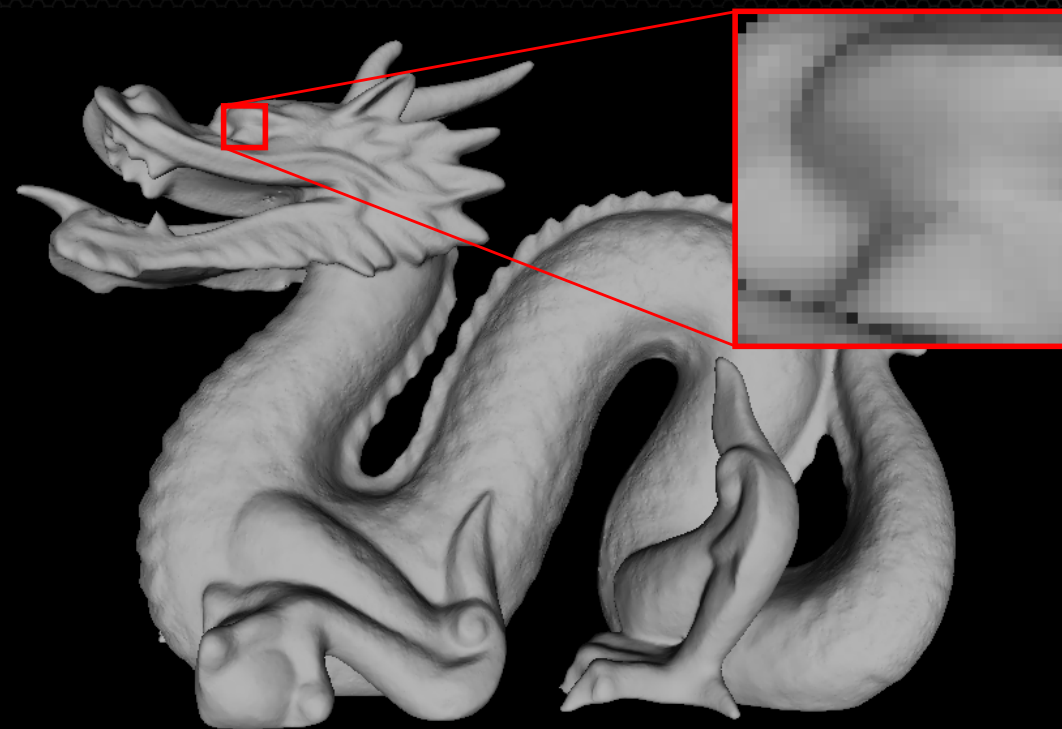


Ours

Geometry Noise Reduction



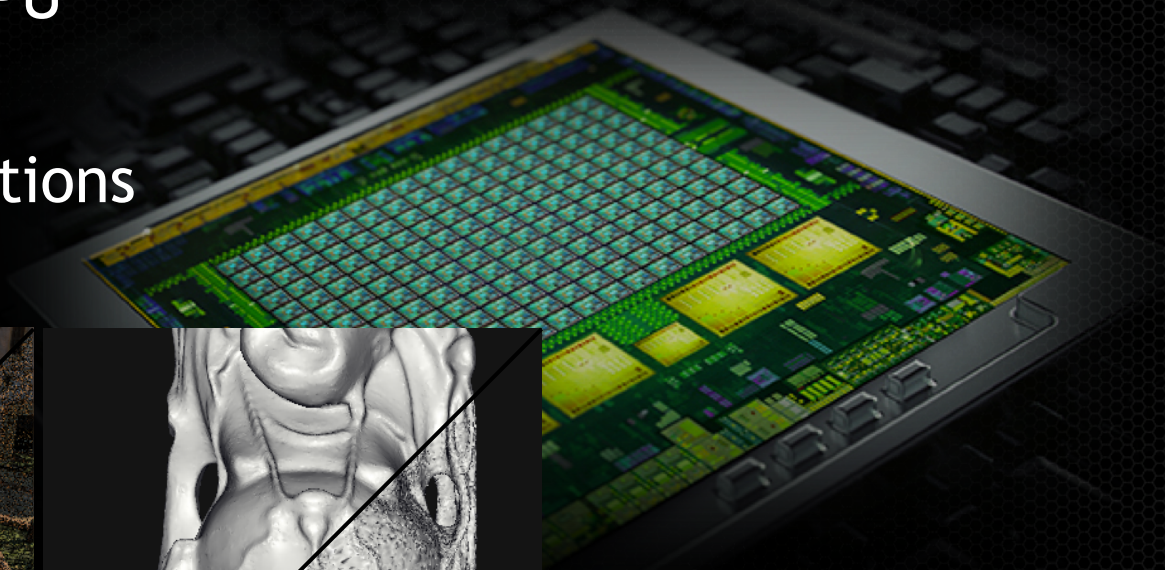
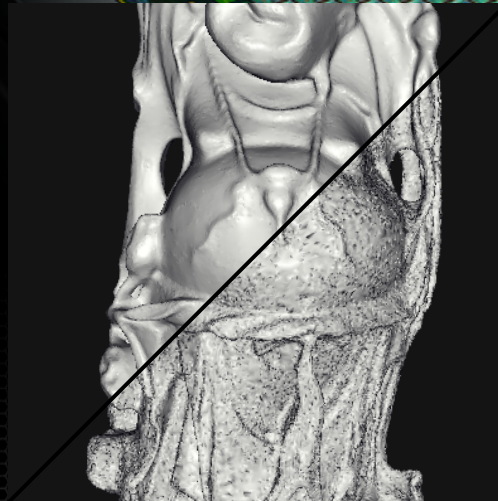
Ours



Exhaustive Search

Conclusions

- Efficient implementation on GPU
- High image quality
- Applicable to different applications



Thank you

- Paper and Binary:
 - <http://bit.ly/fast-ann>

