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Motivation

Why build yet another RTGI method?
 – Significant number of existing techniques
 – RSM, CLPV, VBGI etc

Motivation

- Why build yet another RTGI method?
 Significant number of existing techniques
 RSM, CLPV, VBGI etc
- Wanted a diffuse GI method that:
 - Is stable enough (no view dependence, no flickering etc)
 - Can capture multiple light bounce effects
 - Is fast enough to be of practical use
 - Has limited requirements → easy to integrate to rendering engines

Main Idea

- Why not combine the benefits of existing methods?
- RT Radiance Caching
 - Fast to sample
 - Stable
- But use Reflective Shadow Maps to populate RC

 Cheap creation (additional data in SM MRTs)
 Camera view independent
 Good scaling (e.g. importance sampling)
- Additional functionality for multiple bounces and occlusion

Method Outline



Gl rendering

Radiance field estimation

RH Configuration



Real-Time Diffuse Global Illumination Using Radiance Hints

RSM Sampling



Sample from random points inside the cell

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HPG<u>2011</u>

RSM Sampling



Accepted samplesRejected samples

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Radiance Encoding



Real-Time Diffuse Global Illumination Using Radiance Hints

Radiance Encoding



RH radiance is encoded as spherical harmonics

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Radiance Encoding



With up to 8 MRTs:

4- and 9-coefficient spherical harmonics can encode RGB radiance field

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Comments: RH Sample Distribution

- Uniform distribution of sample points in RH cell
- Why?
 - There is nothing special about RH location!
 - It should be representative of entire cell volume

Min and Max RSM Sample Distances

- For reasons that will become apparent next, also maintain and store for each RH:
 - Min distance to RSM sample
 - Max distance to RSM sample



Comments: Multiple RSMs

- For multiple RSMs (multiple/omni-directional):
 - A fixed number of samples is distributed among RSMs
 - Ideal for importance sampling of light sources





Secondary Bounces



Geometry-less:

Randomly sample the radiance field!

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Secondary Bounces



Interpolate SH from nearest RHs (volume texture tri-linear interpolation)

Integrate incident radiance on the hemisphere aligned with d:

→ "reflected" radiance on an imaginary surface aligned with d

Secondary Bounces: RH Reliability

- Are all random RH samples equally reliable?
 - Certainly not !
 - RH near surfaces are more reliable → must be favored
 - But ... we know nothing about the geometry
- Solution:
 - For each RH, use the minimum distance r_{min} from RSM sample positions
 - Bias RH contribution using r_{min}

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Secondary Bounces: RH Reliability

Interpolated min distance at arbitrary location

Min distance to RSM samples

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Diffuse GI Reconstruction

- Directly sample the RH volume textures at 4 locations in a rotating kernel above the surface
- Perform integration in SH domain over the surfacealigned hemisphere

Voxel diagonal

Half voxel diagonal

A Simple Example



Direct illumination



2nd bounce (total 11.6ms)



1st bounce



Path tracing

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Occlusion

- What about visibility tests?
 RSMs alone are not very helpful
- Store "blocking" information? Trying to avoid:
 - View-dependent geometry injection
 - Volume-based occlusion. Can be slow to generate and requires multiple texture reads per sample
- Can I use existing data?
 - -Yes, but only in secondary bounces
 - Special treatment for first bounce

Secondary Bounce Occlusion

• We can use a probabilistic (heuristic) attenuation metric using the stored min/max distances



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Secondary Bounce Occlusion Example

 The secondary bounce attenuation is not as important as the first bounce one but is almost for free.



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What About First-Bounce Occlusion?

- Most important occlusion stage
- Large RSM scene coverage "masks" occlusion (but results are still far from ground truth)
- Small RSM scene coverage leads to erroneous cases:



Wall not present in RSM

Depth-based Occlusion (Extension)

- Use camera depth map to intercept RSM samples
- Uses a voting system to attenuate RSM samples:
- Test a few points on the RH-RSM line of sight against the depth map



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Depth-based Occlusion (Extension)

- View-dependent, but:
- Not a binary visibility test ! → Time-coherent



10X4X10 Radiance Hints, single bounce, total GI time: 2.28ms

Depth occlusion enabled, 5.00ms

No occlusion

Depth-based attenuation

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Performance



Cumulative GI stage timings (3nd order SH)

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Examples – No 1st Bounce Occlusion



Real-Time Diffuse Global Illumination Using Radiance Hints

Examples - No 1st Bounce Occlusion



Real-Time Diffuse Global Illumination Using Radiance Hints

Examples - With 1st Bounce Occlusion



no first-bounce occlusion



depth-based RSM attenuation



Real-Time Diffuse Global Illumination Using Radiance Hints

Input and Requirements

- Just the light source RSMs (modern rendering engines require them for other tasks anyway)
- No geometry is rendered during GI calculations
- No geometry shaders are needed
- No pre-processing of any kind
- No post-processing
- Can be used in direct and deferred renderers

Other Extensions

- Small RH volumes can be placed in disjoint locations
 - More effective coverage of important areas
 - Nested RH volumes (for more detail)
- Due to their linear form (SHs, distances), RHs can be automatically mip-mapped and hierarchically sampled

Pros and Cons

- The good news are:
 - Yes, it is versatile and easy to configure
 - Has minimal requirements
 - Handles multiple bounces
 - The (core) method is view-independent
- But:
 - Is an approximate approach
 - Heuristically handles occlusion

Thank You

- Please visit the AUEB Graphics Group web site (<u>http://graphics.cs.aueb.gr</u>) for:
 - Shader source code
 - Additional demo images and videos
- A complete mathematical analysis can be found in the paper.

Pitfalls

 Same problems as any other RSM-based method:
 No sufficient coverage of geometry by RSMs → Not enough reliable samples



Path tracing

VBGI

RH + occlusion LPV / RH

Real-Time Diffuse Global Illumination Using Radiance Hints