

Ambient Occlusion Volumes "AOV"

Morgan McGuire NVIDIA Research & Williams College

Artistic Motivation



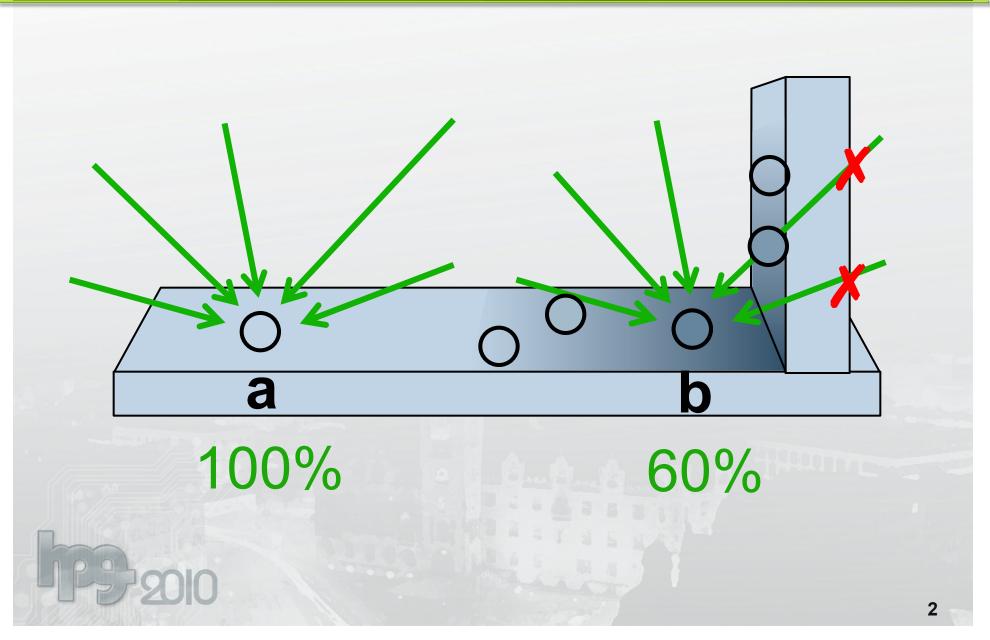
- Perceived depth
- Proximity

- Lighting contrast
- Curvature and creases



Intuition





Selected Previous Work



- Analytic
 - Sphere proxies [BUNNELL 05, HOBEROCK AND JIA 07, SHOPF ET AL. 09]
 - Offline [BAUM ET AL. 89, ZHUKOV ET AL. 98, HOBEROCK AND JIA 07, SHOPF ET AL. 09]
- Sampled
 - Ray tracing [e.g., DUTRE ET AL. 04]
 - Signed distance field [Evans '06]
 - Precomputed [Kontkanen and Laine 05, Malmer
 - Voxel ray trace [REINBOTHE ET AL. 09]
 - Light probe [SLOAN ET AL. 07]
 - Raster bit mask [Laine and Karras '10]
- Phenomenological
 - Tree-specific [HEGEMAN
 - Unsharp masking [LUF, LINE, 00]
 - Screen space [MITTRING '07, SHANMUGAM AND ARIKAN '07, BAVOIL AND SAINZ '09, KAJALIN '09]

Sparse sampling

Analytic on bounding box

Precomputed volume of AO effect

Tighter bounding volume and LOD

3

AOV Features

- Real-time
- Dynamic polygon soup
- Physically based
- Noise-free

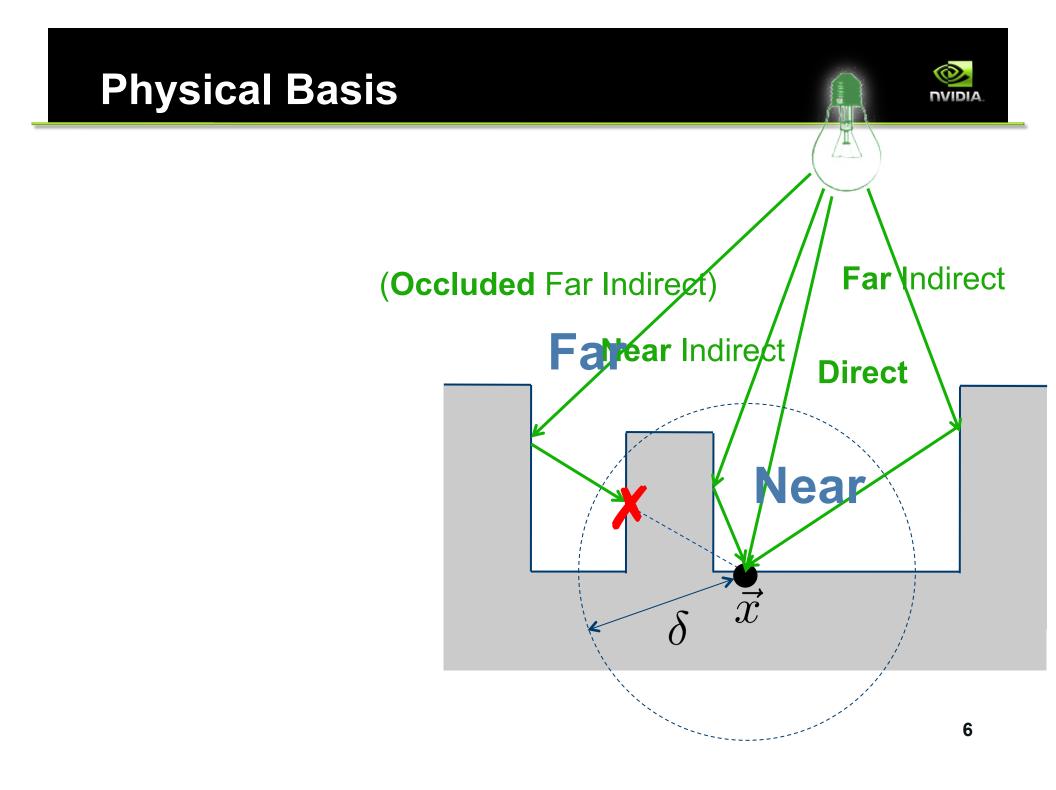
Unlike phenomenological screen-space methods:

- Viewer independent
- Viewport independent
- Designed for integration with real GI
- Approaches the quality of offline ray traced occlusion

- Requirements:
 - Geometry shader for preferred implementation
 - Normal and depth ("Geometry") buffers
 - High fill rate GPU
 - Minimum thickness to objects; overdarkening when this is violated

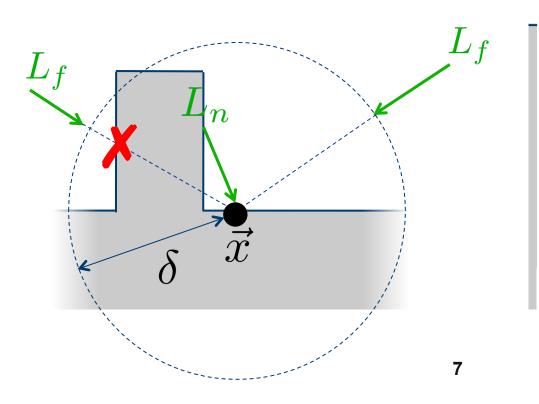






Physical Basis





Physical Basis



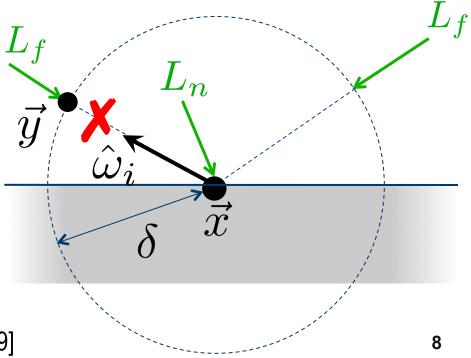
Let
$$\vec{y} = \vec{x} + \delta \hat{\omega}_i$$

 $\mathcal{V}(\vec{x}, \vec{y}) = 1$ iff \vec{y} is visible to $\vec{x}, 0$ otherwise
 $L_i(\vec{x}, \hat{\omega}_i) = L_n(\vec{x}, \hat{\omega}_i) \cdot (1 - \mathcal{V}(\vec{x}, \vec{y})) + L_f(\vec{y}, \hat{\omega}_i) \cdot \mathcal{V}(\vec{x}, \vec{y})$

Set δ to your global illumination algorithm's sampling resolution (or choose artistically)

 $\delta = \infty$ is undesirable: makes everything 100% occluded for indoor scenes [ShanmuGam and Arikan 07]

[ARIKAN ET AL. 05; SZIRMAY-KALOS ET AL. 09]



Incident Light

[KAJIYA 86]

$$L_o = L_e + \int L_i \cdot f \cdot (\hat{\omega}_i \cdot \hat{n}) \, d\hat{\omega}_i$$

[MCGUIRE 09, 10]

$$\begin{split} L_o &= L_e + & \text{``emitted"} (e.g., emissive map) \\ &\sum_{\hat{\omega}_i} L_s \cdot \mathcal{V} \cdot f \cdot (\hat{\omega}_i \cdot \hat{n}) + & \text{``direct"} (BRDF + shadow map) \\ &\int L_n \cdot (1 - \mathcal{V}) \cdot f \cdot (\hat{\omega}_i \cdot \hat{n}) \ d\hat{\omega}_i + & \text{``local indirect"} (often ignored) \\ &\int L_f \cdot \mathcal{V} \cdot f \cdot (\hat{\omega}_i \cdot \hat{n}) \ d\hat{\omega}_i & \text{``ambient"} (e.g., S.H. evt. light) \end{split}$$

Ambient term:

"ambient light" (e.g., precompute, VPL, or ISPM) "**accessibility**" (via AO estimation)

$$\int L_f \cdot \mathcal{V} \cdot f \cdot (\hat{\omega}_i \cdot \hat{n}) d\hat{\omega}_i \approx \left[\int L_f \cdot f \cdot (\hat{\omega}_i \cdot \vec{n}) d\hat{\omega}_i \right] \cdot \left[\frac{1}{\pi} \int \mathcal{V} \cdot \max(\hat{\omega}_i \cdot \vec{n}, 0) d\hat{\omega}_i \right]$$

best when L_f and f are smooth (ideally, constant) medium frequency



Ambient Occlusion



"accessibility"

"ambient occlusion"

$$\left[\frac{1}{\pi} \int \mathcal{V} \cdot \max(\hat{\omega}_i \cdot \vec{n}, 0) d\hat{\omega}_i\right] = 1 - \left(\operatorname{AO}(\vec{x})\right)$$

obscurance Ambient occlusion of \vec{x} by one polygon, P:

$$AO_{P}(\vec{x}) = 1 - \frac{\alpha_{P}}{\pi} \int_{P} \mathcal{V}(\vec{x}, \vec{z}) \cdot \max\left(\frac{\vec{z} - \vec{x}}{|\vec{z} - \vec{x}|} \cdot \hat{n}, 0\right) \cdot g(|\vec{z} - \vec{x}|) d\vec{z}$$

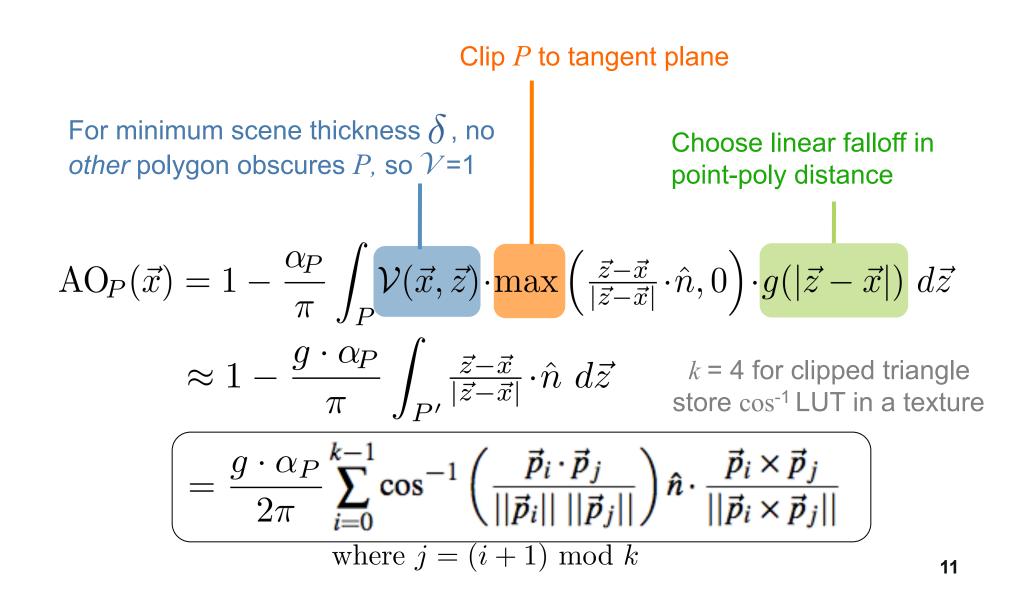
$$[ZHUKOV ET AL. 98]$$

$$\delta \quad |\vec{z} - \vec{x}|$$

$$IO$$

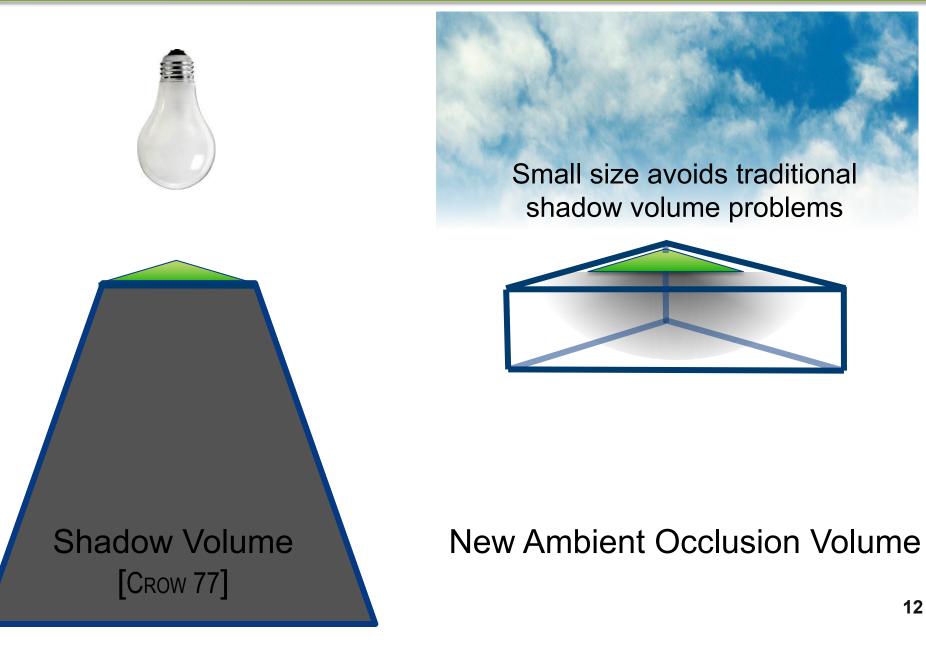
AOV Fundamental Operation





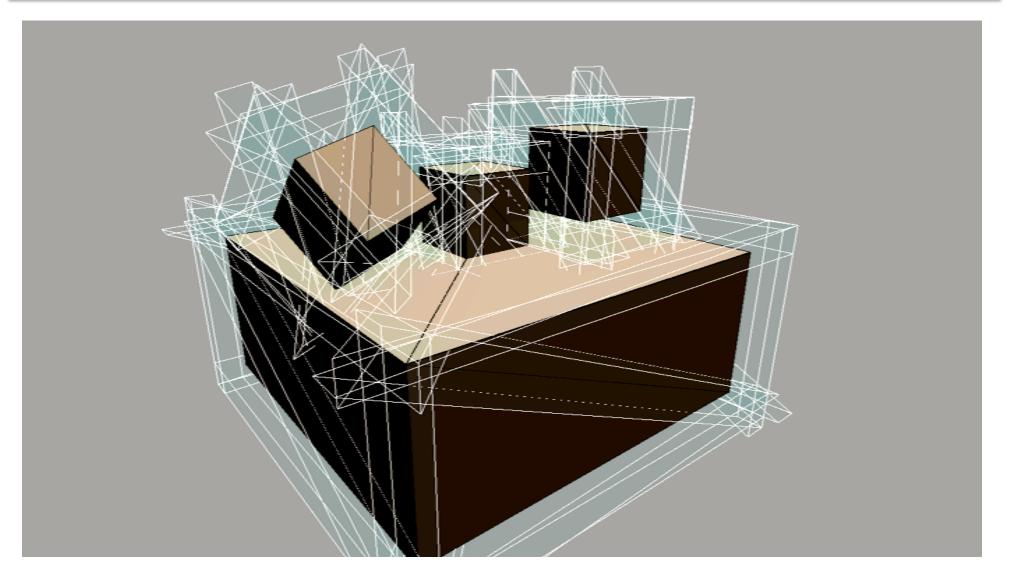
Iterating over Polygons Near a Point





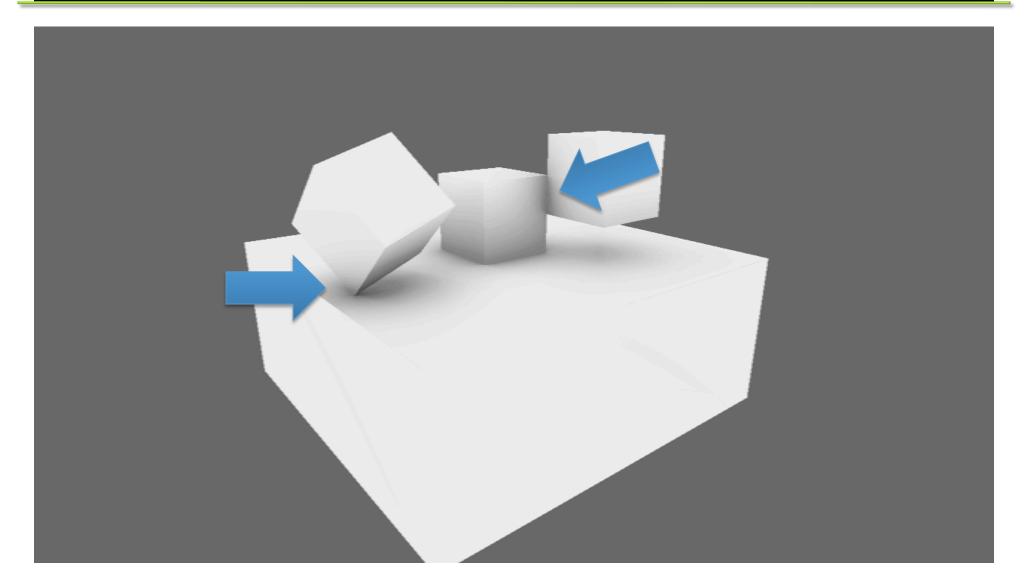
Geometry + AOVs





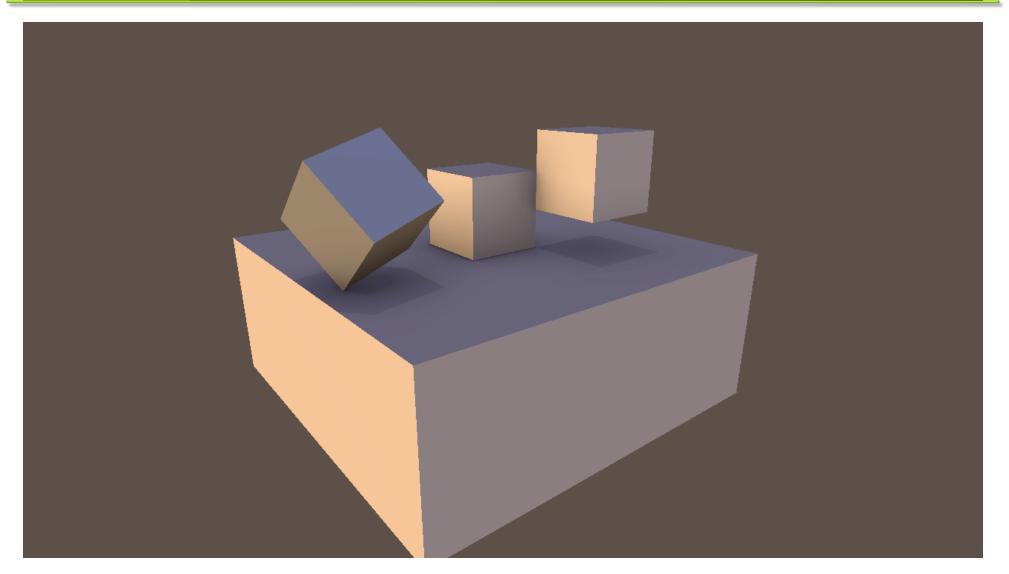
Accessibility Factor





Final Shading Result





Details

Quality

- Partial coverage
- Disable near plane clipping

Use "z-fail" depth test or full-screen quad if camera position is inside AOV

Compensation map

Performance

- Precompute volumes for static geometry
- Sparse sampling









Ray traced AO

- "Ground truth" baseline
- 8-cores, BVH

Crytek SSAO [MITTRING '07, KAJALIN '09]

- Popular industry technique
- Artistically driven

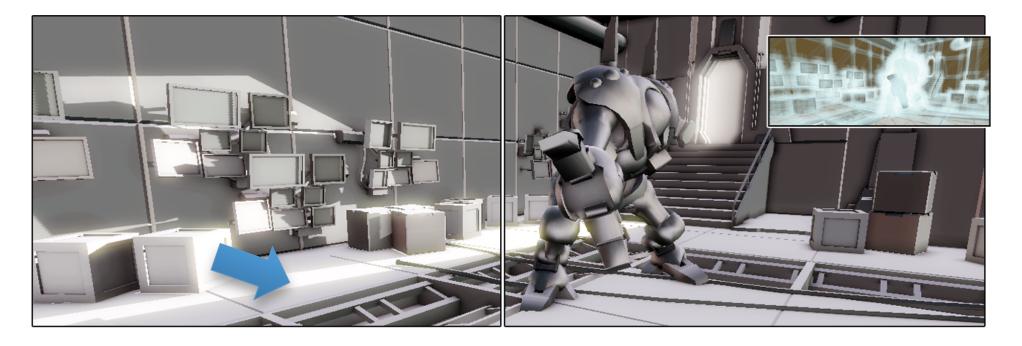
Volumetric AO [SZIRMAY-KALOS ET AL. '09]

- Fastest screen space method
- Physical based

AOV (This paper)

Qualitative





Ray traced AO

124309 ms = 2 minutes

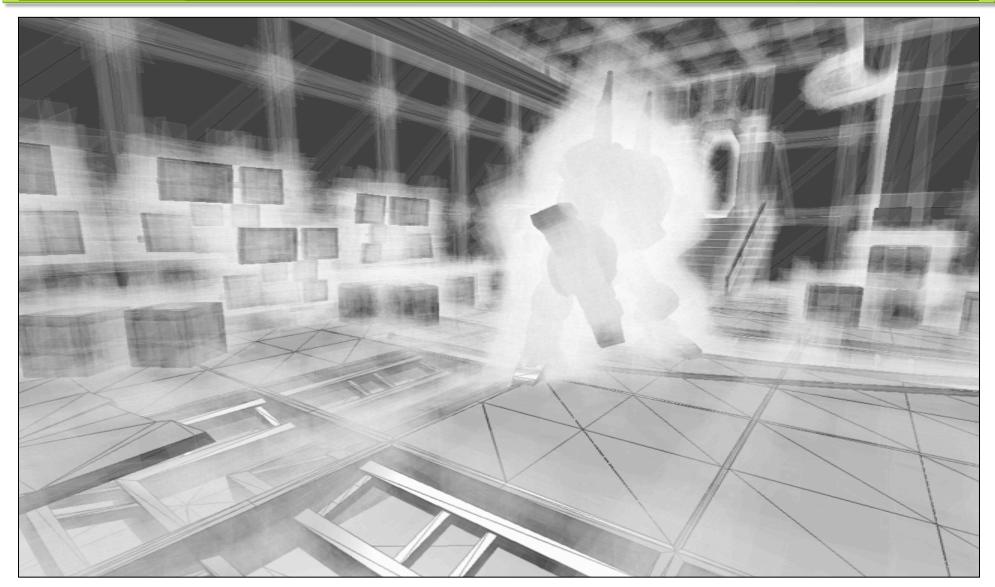
Real time AOV

23 ms (or 6 ms with 3x3 subsample)

1.4 million triangles, 1280x720 pixels, δ = 0.42m "Secret War" scene from *Marvel Ultimate Alliance 2* courtesy Vicarious Visions

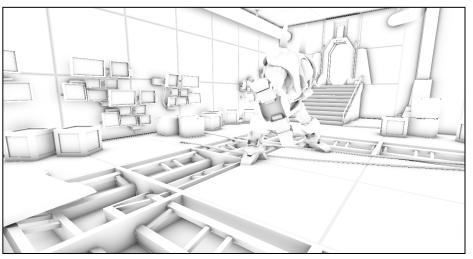
Bounding Volume Wireframe

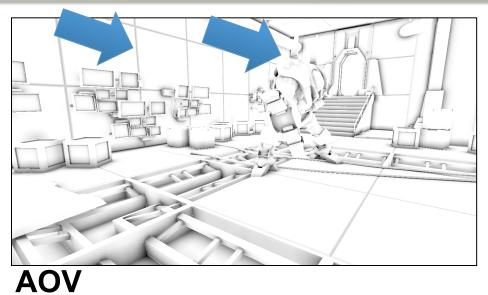




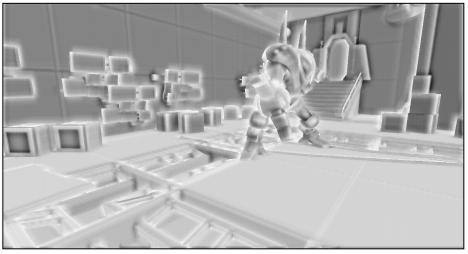
Quality Comparison



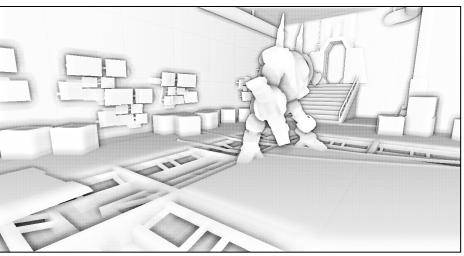




Ray trace



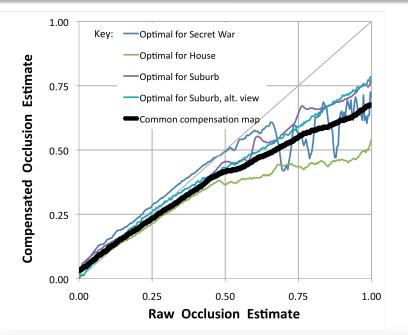
Crytek SSAO

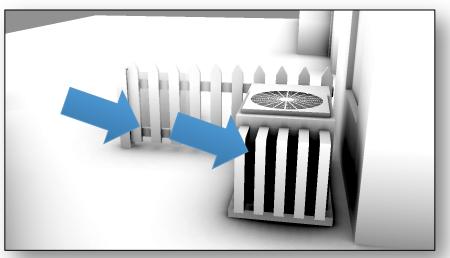


Volumetric

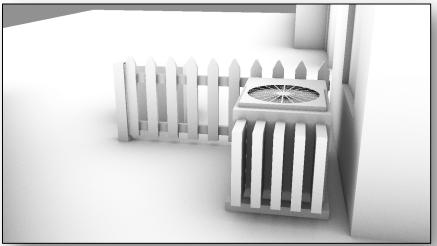
Compensation Map



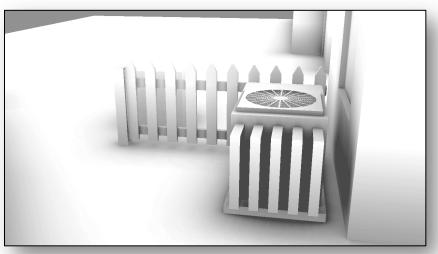




Raw AOV Result



Ray trace

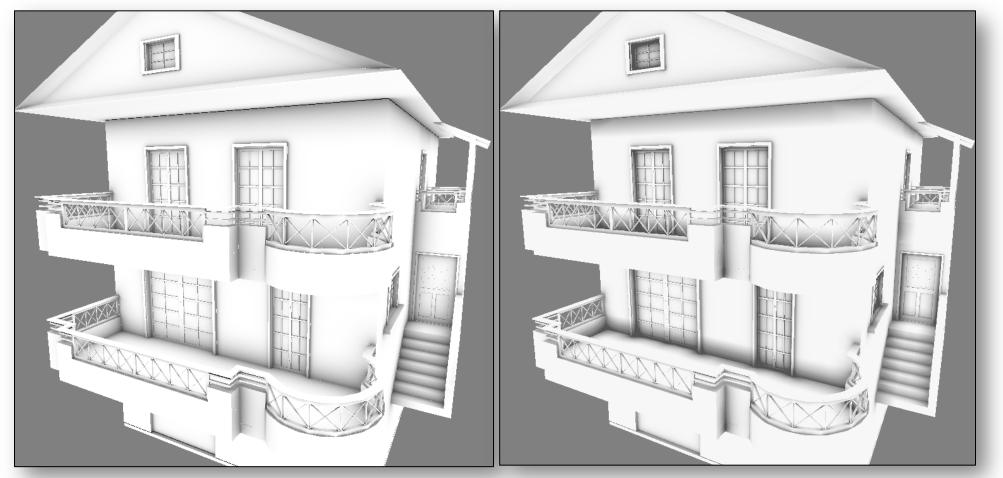


AOV + Compensation 2

22

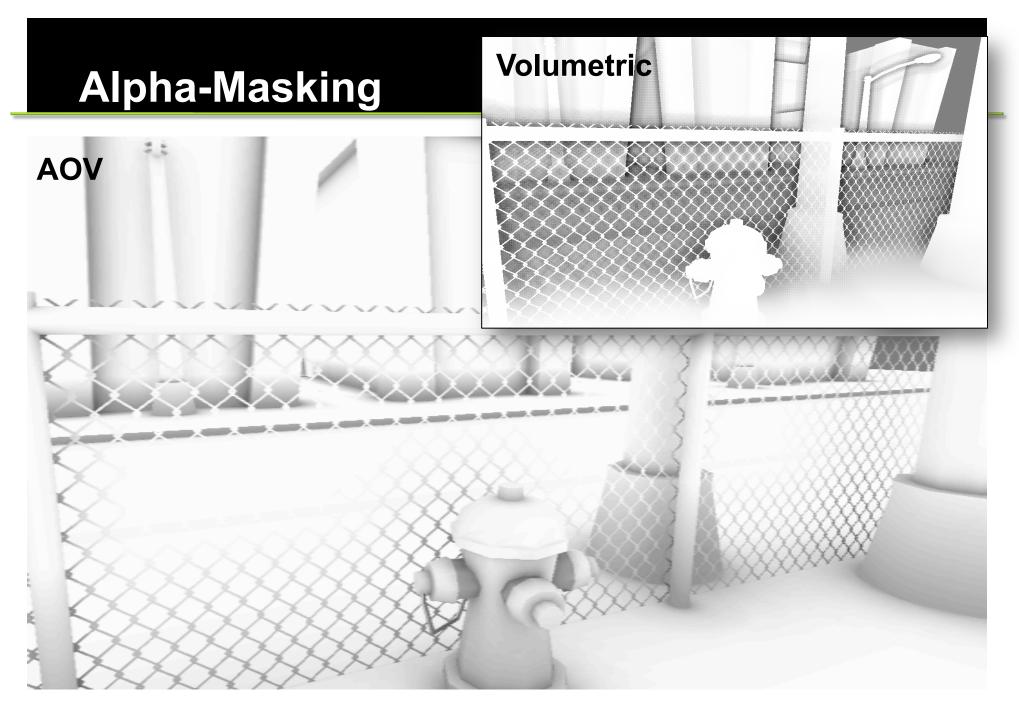
Overdarkening Artifact





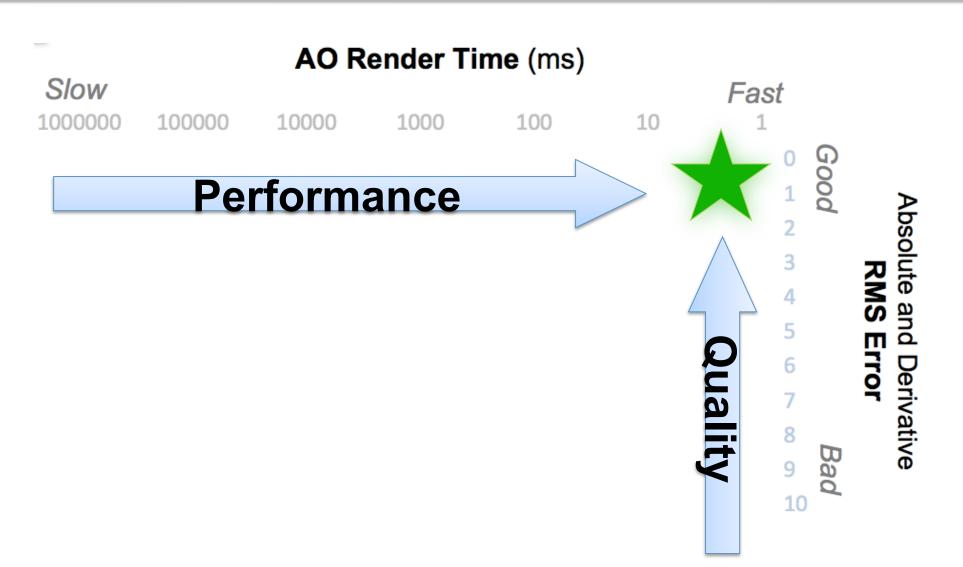
Ray trace

AOV



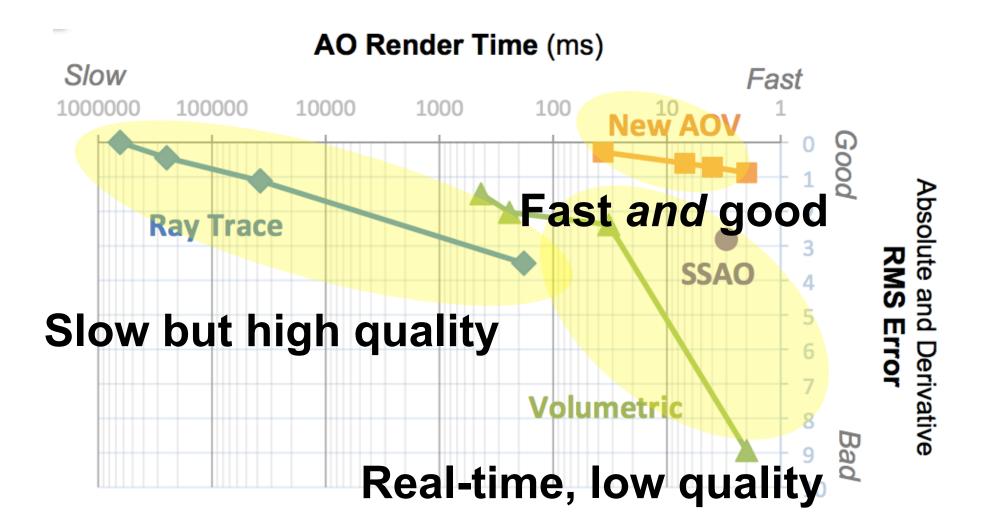
Quality vs. Performance (varying sample rate)





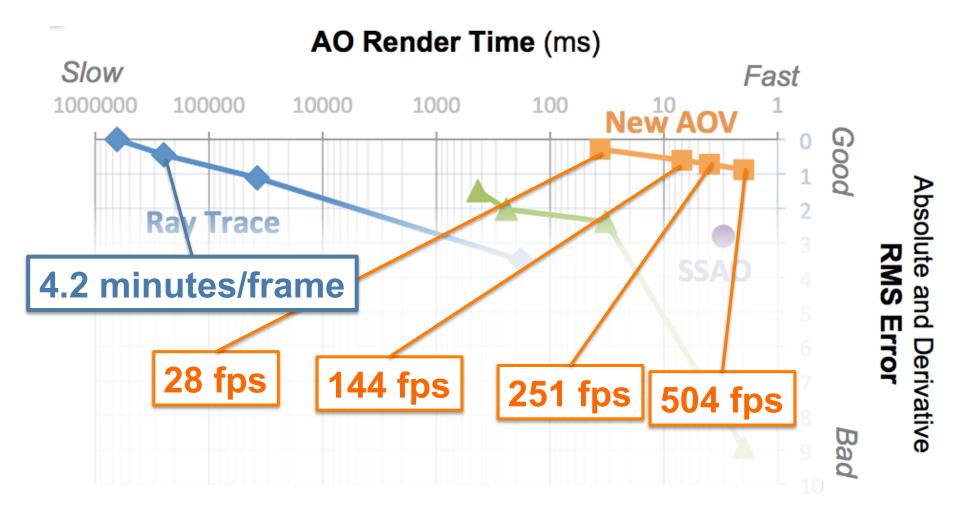
Quality vs. Performance (varying sample rate)





Quality vs. Performance (varying sample rate)

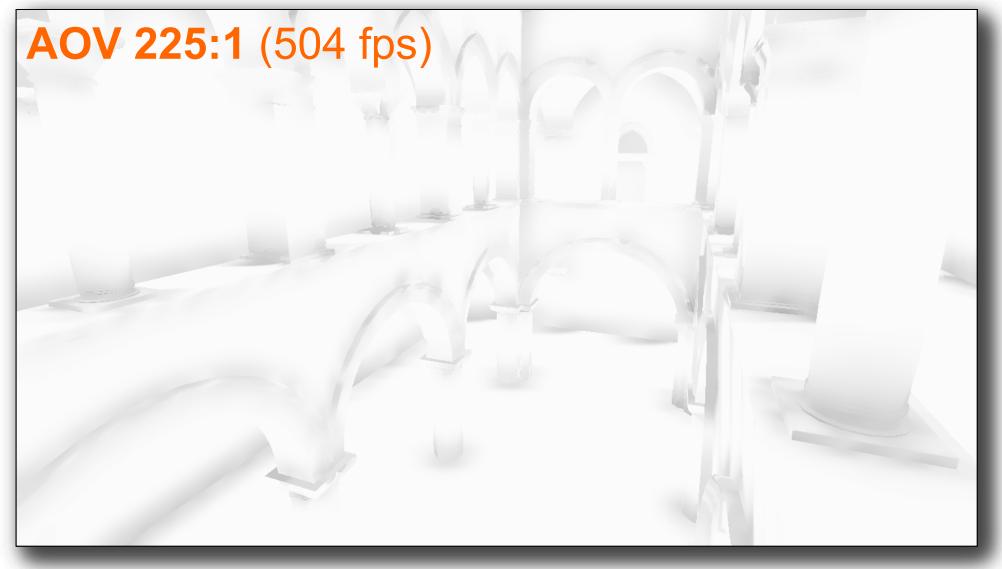


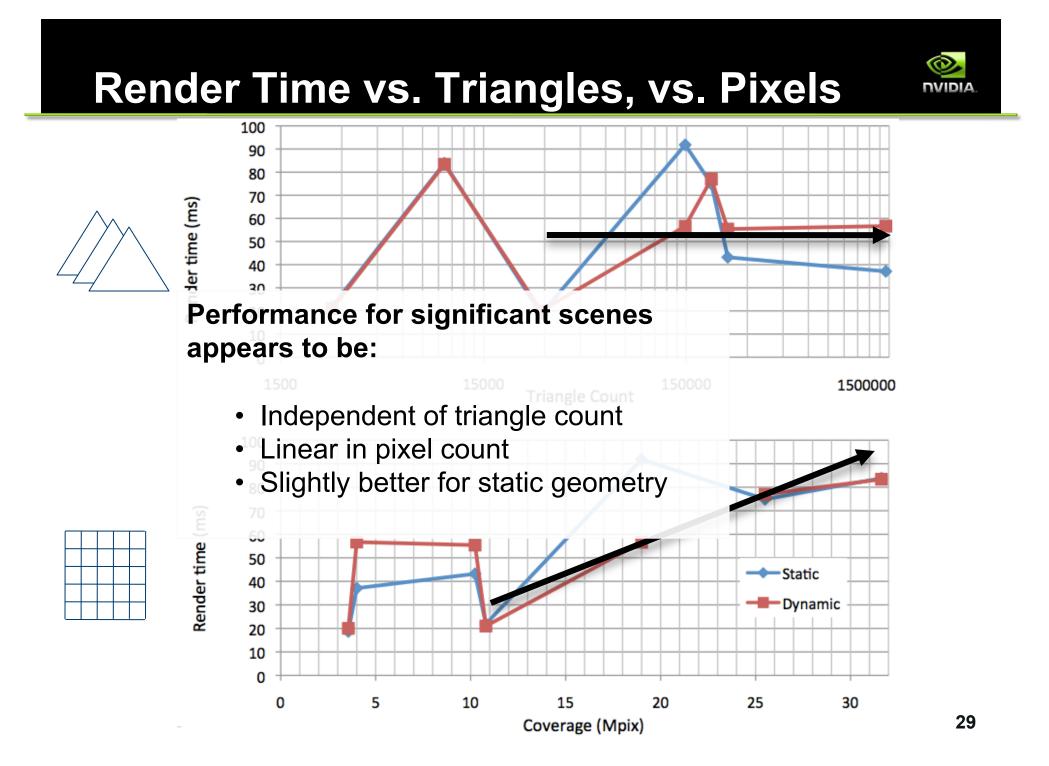


AOV Performance at Ray Trace Quality Level

Quality vs. Performance













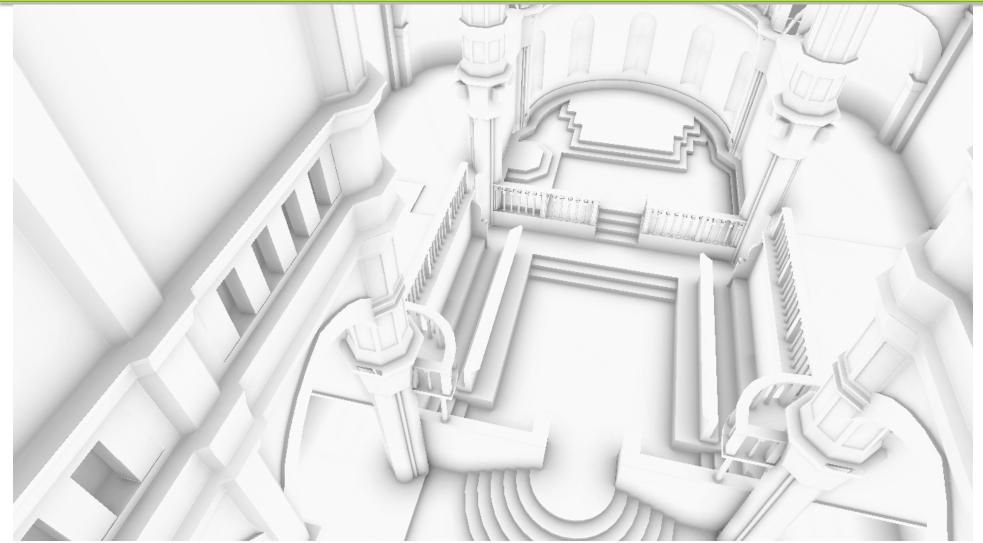






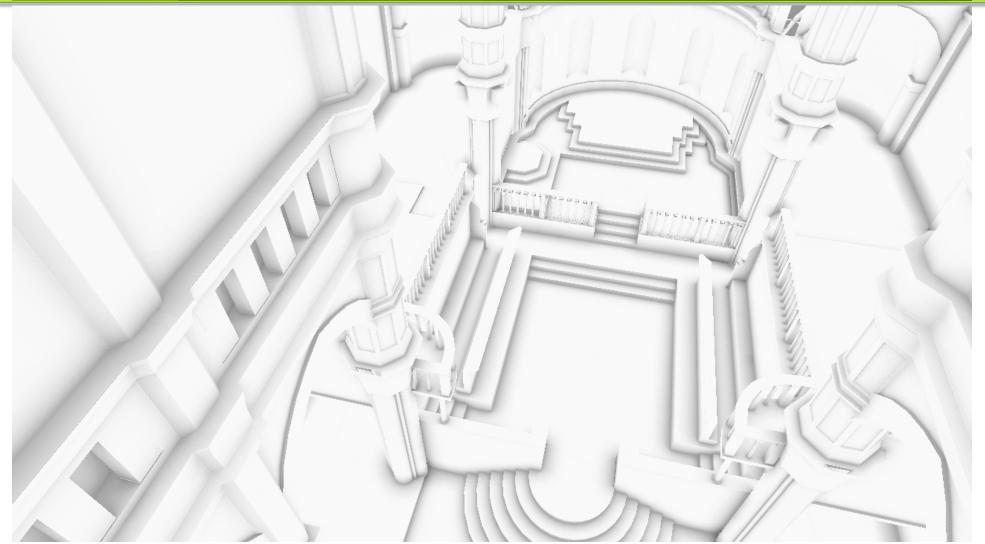






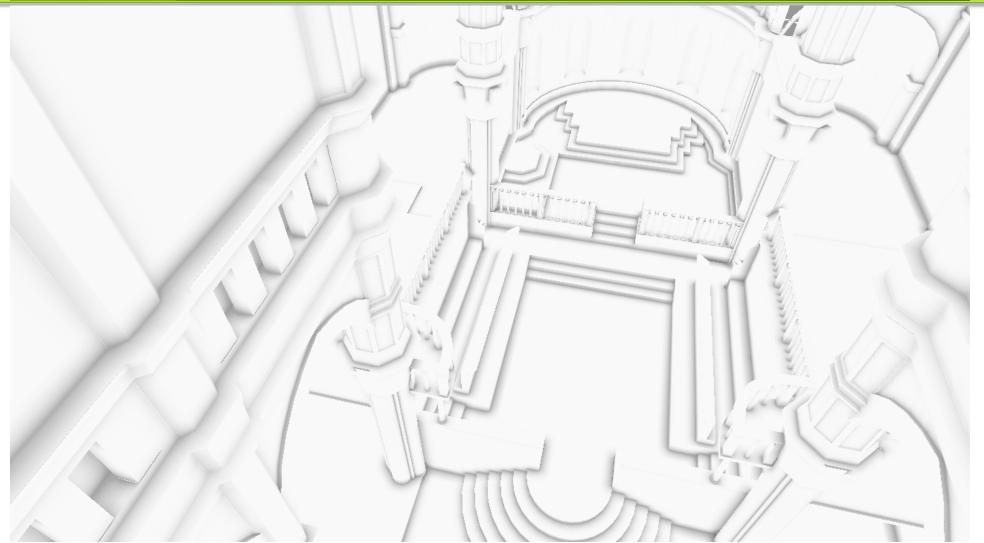


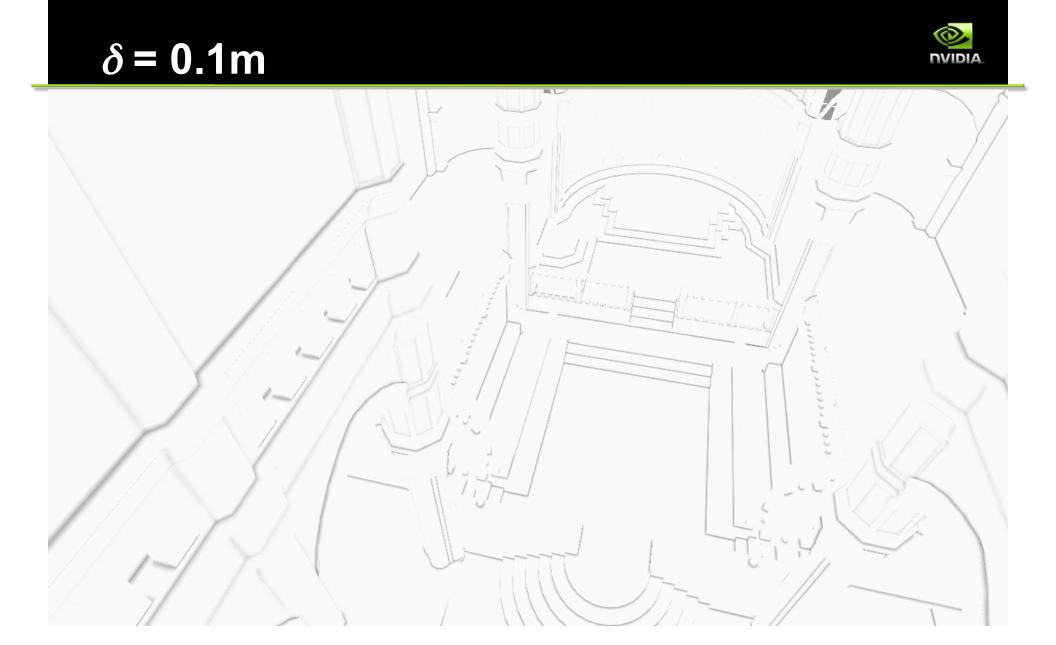


















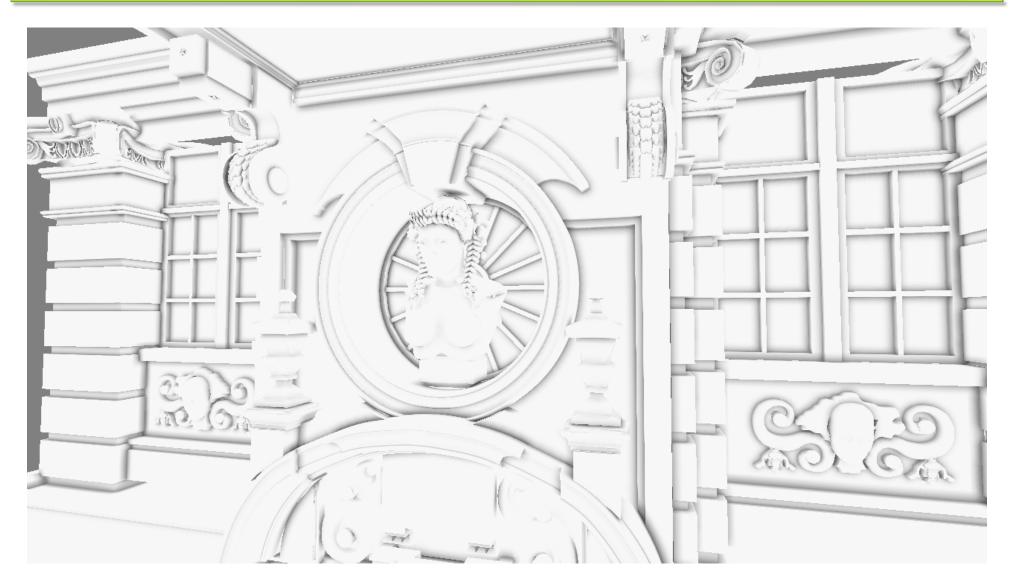
Foliage (150k triangles, with \alpha)







Architectural Detail (690k sliver triangles)



Summary



Presented physical basis for AO and other real-time terms

- Made clear previously implicit approximations and assumptions
- How to combine with real-time GI methods without overlap

Two tricks (AO

- Compute tig
- Compensati
- Includes α f
- Upsampling

High-quality AO

- Analytic: vie
- Comparable



Comparable to ray traced AO quality

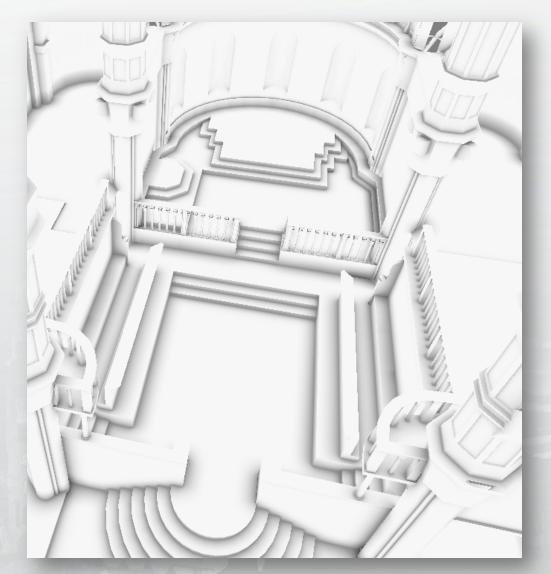
Acknowledgements



Peter Shirley, NVIDIA David Luebke, NVIDIA Tom Garrity, Williams College Corey Taylor, Electronic Arts Joakim Carlsson, Chalmers Patrik Sjölin, Chalmers

Louis Bavoil, NVIDIA

Chris Wassum, Vicarious Visions Max McGuire, Unknown Worlds Marko Dabrovic





ADDITIONAL MATERIAL

Future Directions



Integrate with real-time global illumination

- Corrects missing high frequencies in ISPM and VPL approaches
- Natural extension to *near-field* indirect illumination: accumulate both light and occlusion

Performance improvements

- Ongoing work with Louis Bavoil at NVIDIA
- LOD and hexaprism from Laine and Karras EGSR '10

Real-world artist controls

- AO caster/receiver flags
- Per-surface falloff function
- Delta as a function of distance from camera

Algorithm



- 1. Render x, n geometry buffers [Saito and Takahashi 91]
- 2. Bind **Accessibility** buffer, clear to 1
- 3. Set subtractive blending mode
- 4. Draw Call + Vertex Shader: as if making a regular pass
- 5. Geometry Shader:

For each polygon P with vertices $\{p_0, ..., p_{k-1}\}$:

- 1. Compute prism *B* bounding $g_P(x) > 0$
- 2. If camera is inside B, then emit full screen quad, else emit B

6. Pixel Shader:

- 1. Read position *x* and normal *n*
- 2. Compute $g = g_P(x)$; discard if $g \le 0$
- 3. Clip *P* to the local tangent plane, generating quad $P' = \{p_0', ..., p_3'\}$
- 4. Output to $AO_{P'}(x)$ to blender



Quality vs. Performance (varying sample rate)

Scene		Belgium		Boxes Correctness		City			House			Trees			Secret War Video Game			Sibenik Architecture			Sponza			Suburb Worst Case		
	Architecture 687,054 tris			144 t		Alpha 9,624 1		tris	Architecture 28,866		tris	Foliage 148,101 tris			1,445,620 tris				40,090 tris	0,090 tris		Architecture 199,362 tris		2,688		tris
1ethod, samples	GF 280 (ms)	GF 480 (ms)	Error (d²)			GF 280 (ms)	GF 480 (ms)	Error (σ ²)	GF 280 (ms)	GF 480 (ms)	Error (σ²)	GF 280 (ms)	GF 480 (ms)	Error (σ²)	GF 280 (ms)	GF 480 (ms)	Error (σ^2)	GF 280 (ms)	GF 480 (ms)	Error (σ²)	GF 280 (ms)	GF 480 (ms)	Error (σ²)	GF 280 (ms)	GF 480 (ms)	Error (a
ay Trace 5000	490803.0	490803.0	0.00	76103.3	0.00	603202.0	603202.0	0.00	283226.0	283226.0	0.00	691334.0	691334.0	0.00	556228.0	556228.0	0.00	514959.4	514959.4	0.00	642571.0	642571.0	0.00	401222.0	401222.0	0.0
1941	190687.0	190687.0	0.35	29712.1	0.12	234515.0	234515.0	0.65	109923.0	109923.0	0.23	270322.0	270322.0	0.28	216142.0	216142.0	0.89	200163.7	200163.7	0.57048	249890.0	249890.0	0.45	155504.0	155504.0	1.0
292	28779.9	28779.9	1.02	4528.6	0.27	35372.4	35372.4	1.47	16574.2	16574.2	0.60	40803.0	40803.0	0.80	32564.8	32564.8	2.07	30220.5	30220.5	1.49404	37627.1	37627.1	1.12	23439.2	23439.2	2.1
1	156.4	156.4	6.83	79.5	1.06	167.9	167.9	6.06	87.7	87.7	2.88	195.0	195.0	6.06	161.1	161.1	9.38	155.3	155.3	6.40968	180.9	180.9	3.50	130.7	130.7	8.9
OV (new) 1	77.7	16.95	0.59	1.9	0.06	137.3	46.343	0.46	25.9	9.530999	0.27	100.3	19.435	2.03	31.2	30.99	0.43	?	23.568	0.51684	110.1	36.337	0.28	31.7	22.178	0.6
$1/3^2 \cdot 5^2$	41.6	5.744	1.03	0.3	0.06	20.5	7.213	0.51	7.2	2.318	0.69	38.0	6.881	2.40	21.3	6.379	0.73	?	4.64	0.93845	32.2	6.96	0.61	5.2	4.72	0.6
$1/5^2 \cdot 5^2$	28.1	2.15	1.55	0.1	0.06	8.9	3.432	0.72	5.6	1.538	0.78	28.7	4.729	2.74	18.9	5.598	0.88	?	3.152	1.16105	21.8	3.977	0.72	2.8	2.781	0.7
1/15 ² · 5 ²	11.9	2.62	2.28	0.1	0.08	2.9	1.231	1.10	2.9	1.031	0.90	12.8	2.821	3.14	4.6	5.044	1.16	?	1.875	1.59577	10.2	1.988	0.88	1.4	1.465	0.8
olumetric 1024	895.4	347.277	2.19	371.0	0.20	1035.3	496.336	3.96	473.7	401.605	1.20	742.8	386.223	4.32	954.8	395.758	1.62	?	431.225	6.79809	967.9	431.225	1.49	1050.1	1049.041	1.3
256	224.3	223.38	2.50	93.6	0.36	259.3	258.587	4.75	119.0	118.88	1.47	186.8	186.032	4.98	252.1	238.379	2.55	?	242.471	2.37686	242.9	242.471	2.03	265.2	263.368	2.2
32	29.3	29.334	4.11	12.4	1.03	33.6	33.723	7.03	15.6	16.572	2.42	24.4	24.343	6.35	31.0	31.79	4.74	?	32.474	5.6291	238.6	32.474	2.39	34.4	34.58	4.2
1	3.1	1.966	6.65	1.4	2.26	3.2	2.009	12.89	1.7	1.955	4.58	2.4	1.908	12.26	3.1	1.932	9.94	?	1.99	10.1938	3.1	1.99	8.93	3.2	3.149	11.3
rytek 16 · 4 ²	15.6	?	4.34	11.8	0.52	15.6	?	3.82	12.8	?	1.68	14.3	?	2.98	15.6	?	2.85	?	?	2.91351	15.7	?	2.81	15.5	?	2.7

Images, 3D models, and data at http://graphics.cs.williams.edu

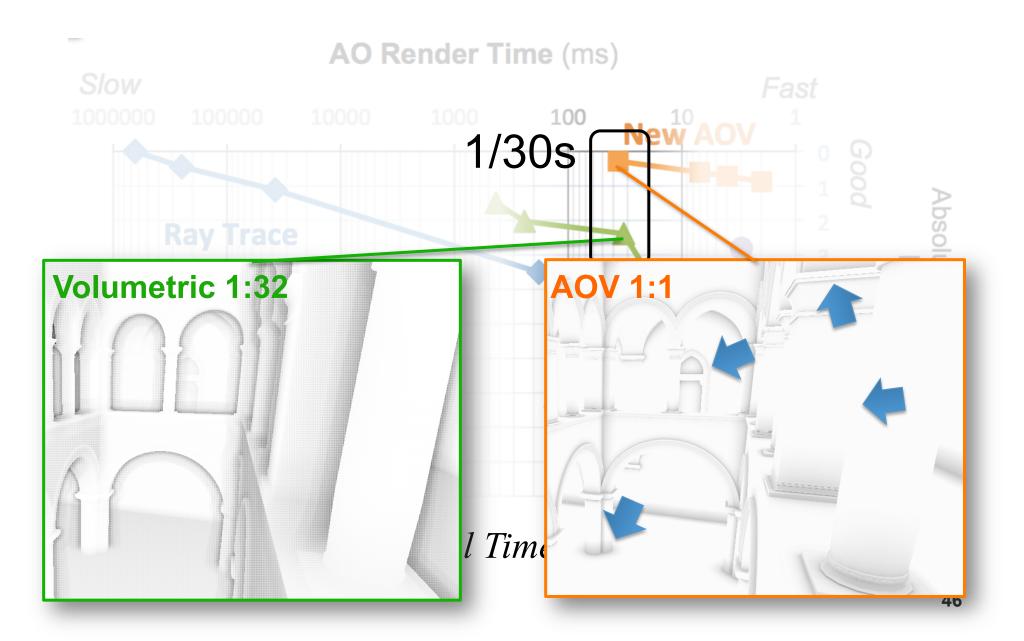






Quality vs. Performance (varying sample rate)





Geometry Shader



$$\vec{e}_{0 \leq i < k} = \begin{bmatrix} \hat{m}_{i} & \\ \hat{m}_{(i-1+k) \mod k} & \\ \hat{m}_{k} & \end{bmatrix}^{-1} \begin{bmatrix} -\delta \\ -\delta \\ 0 \end{bmatrix}$$
$$\vec{e}_{k \leq i < 2k} = \vec{e}_{i-k} - \delta \hat{m}_{k}$$

Operation Cost: Pixel Shader



Read x, n

2 fetch

Clip P Maximum: 3 dot, 4 if, 11 move, 2 divide, 2 vec3 lerp = 21 arith, 2 div, 4 if

Falloff function

3 vec3 sub, 4 dot, 1 clamp, 1 vec4 madd, 4 scalar mul = 29 arith, 1 clamp4

Form factor

Maximum 4 vertices * (1 cross, 5 dot, 2 rsqrt, 4 scalar mul, 1 fetch) 100 scalar arith, 8 rsqrt, 4 fetch

significant scalar ops: 150 arith, 2 divide, 6 fetch, 4 if